

# Introduction to Radio Interferometry: What you need to know to apply to ALMA



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# Resolution of Observations

**Angular resolution for most telescopes is  $\sim \lambda/D$**

D is the diameter of the telescope and  $\lambda$  is the wavelength of observation

**For the Hubble Space Telescope:**

$$\lambda \sim 1 \mu\text{m} / D \text{ of } 2.4\text{m} = \text{resolution} \sim 0.13''$$

**To reach that resolution at  $\lambda \sim 1\text{mm}$ , we would need a  
2 km-diameter dish!**

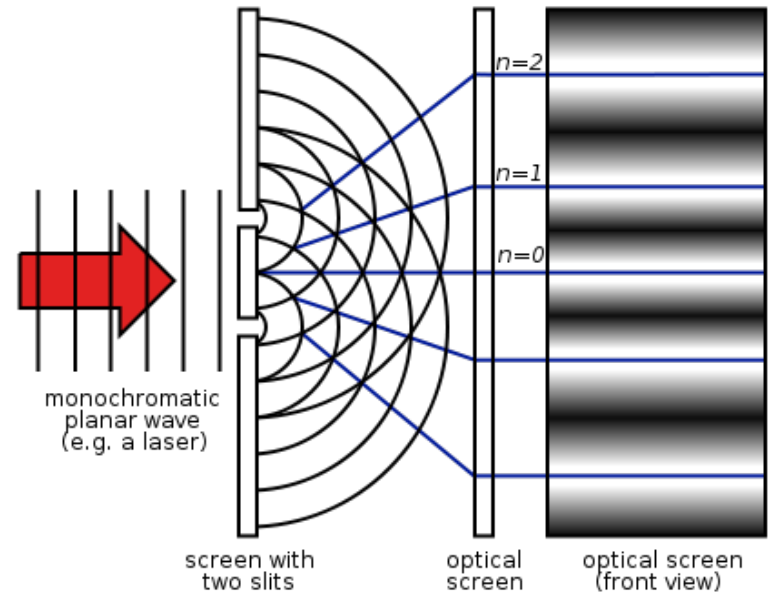
Instead, we use arrays of smaller dishes to achieve the same high angular resolution at radio frequencies

**This is interferometry!**



# What is an interferometer?

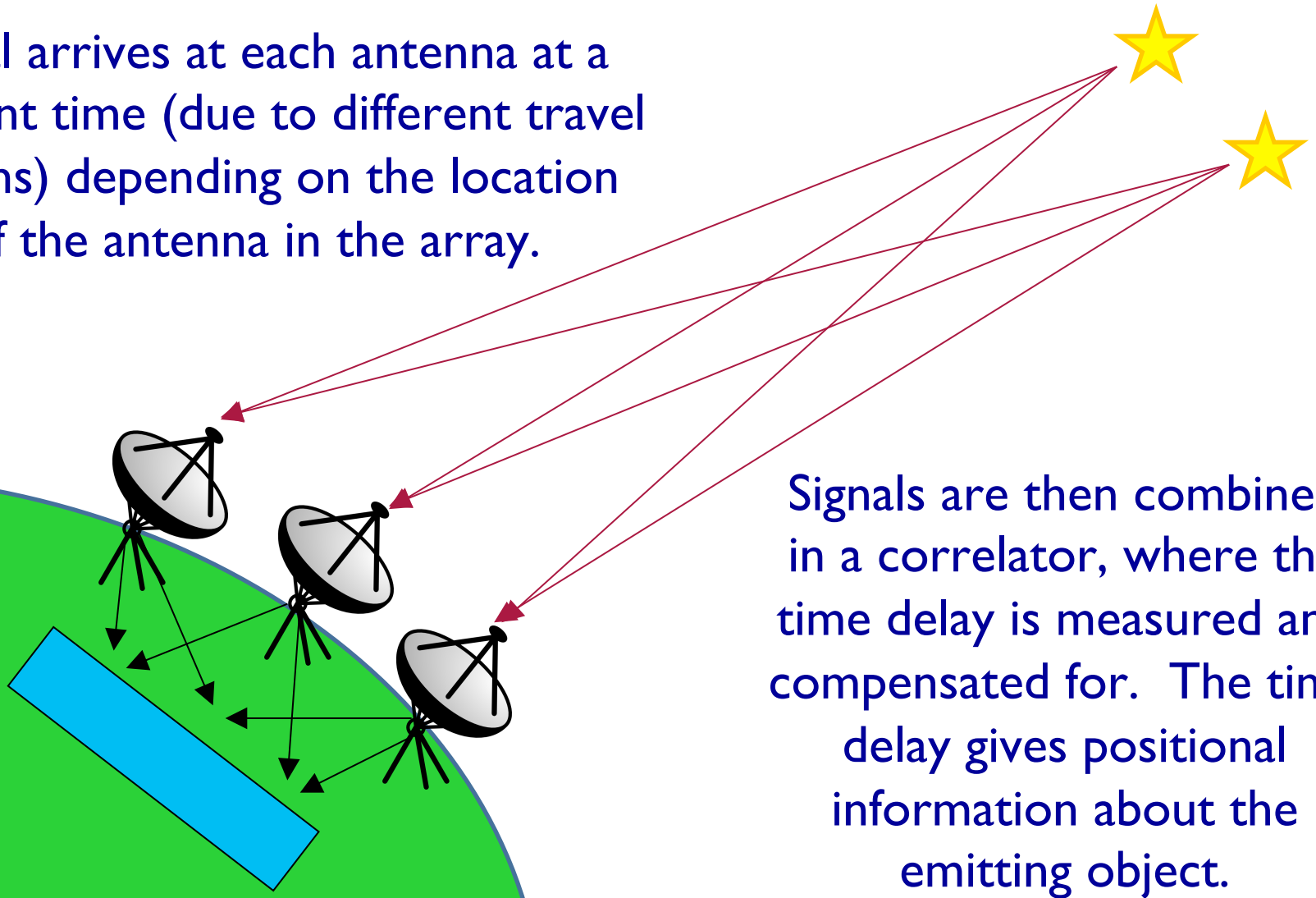
An *interferometer* measures the interference pattern produced by multiple apertures, much like a 2-slit experiment.



\*However, the interference patterns measured by radio telescopes are produced by **multiplying** - not adding - the wave signals measured at the different telescopes (i.e. apertures)

# How Do We Use Interferometry?

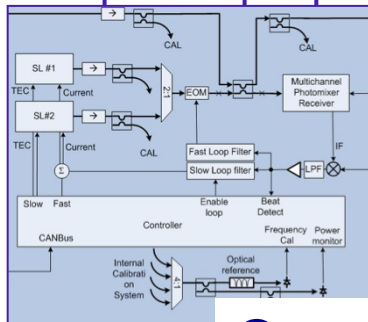
Signal arrives at each antenna at a different time (due to different travel lengths) depending on the location of the antenna in the array.



Signals are then combined in a correlator, where the time delay is measured and compensated for. The time delay gives positional information about the emitting object.



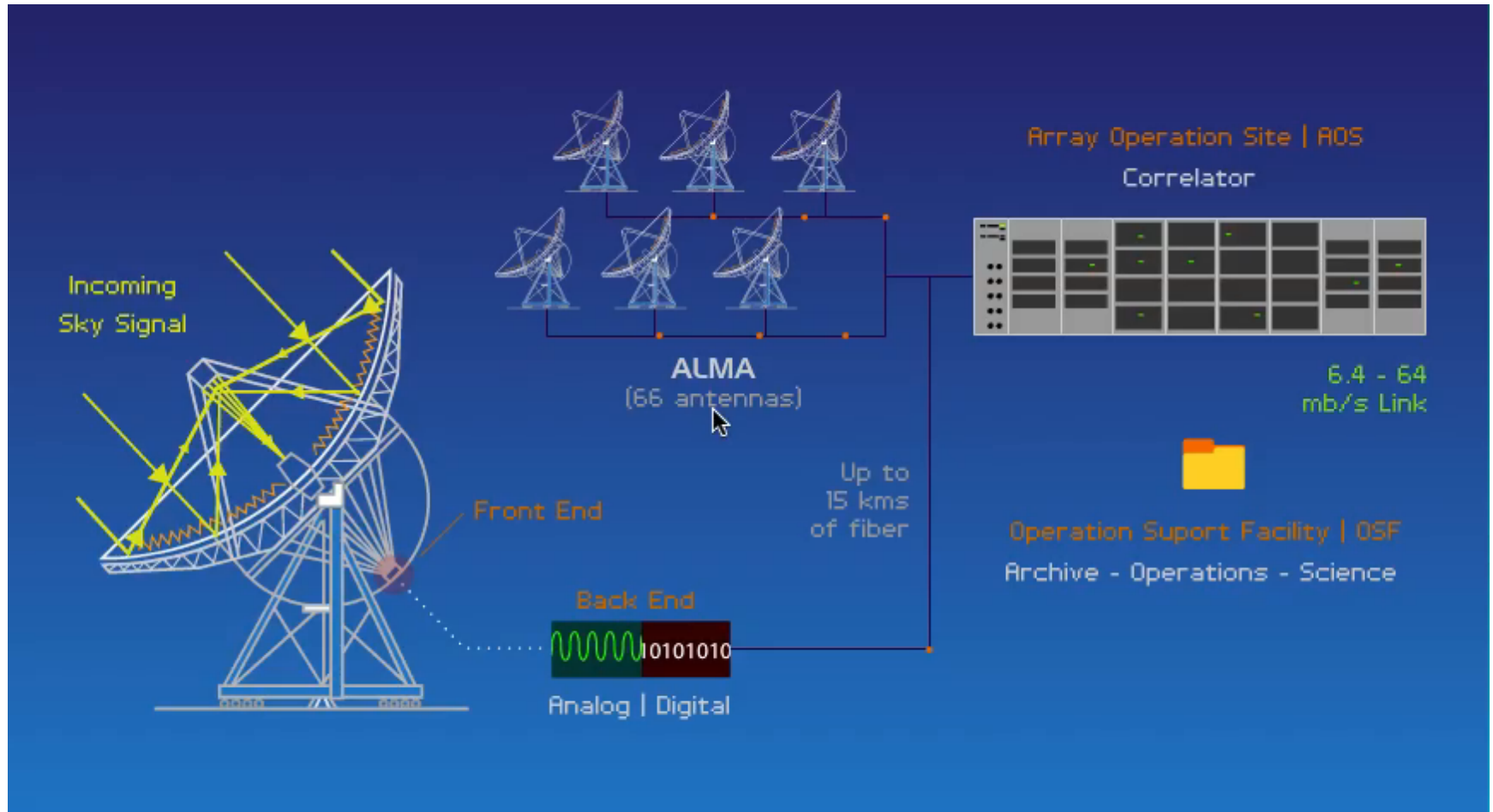
# Some Instrument Details



Outgoing signals: pointing and tracking, tuning receivers, timing reference

Incoming signals: device health, fiber length, astronomical signal (to the correlator for multiplication and averaging)

# An Interferometer In Action



# Interferometry and Fourier Transforms

- An interferometer measures the interference pattern produced by pairs of apertures.
- Interferometer data are termed “**visibilities**”
- The interference pattern is directly related to the source brightness:
  - For small fields-of-view: the complex **visibility**,  $V(u,v)$ , is the **2D Fourier transform** of the brightness on the sky,  $T(l,m)$

$$V(u, v) \xrightarrow{\text{FT}} T(l, m)$$

# What Are Visibilities?

Each  $V(u,v)$  contains information on  $T(l,m)$  everywhere

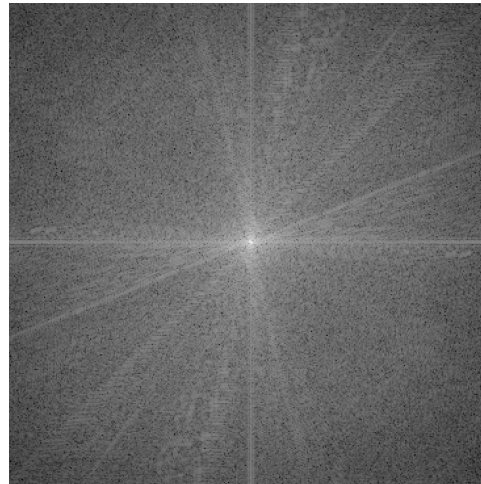
Each  $V(u,v)$  is a complex quantity

Expressed as (real, imaginary) or (amplitude, phase)

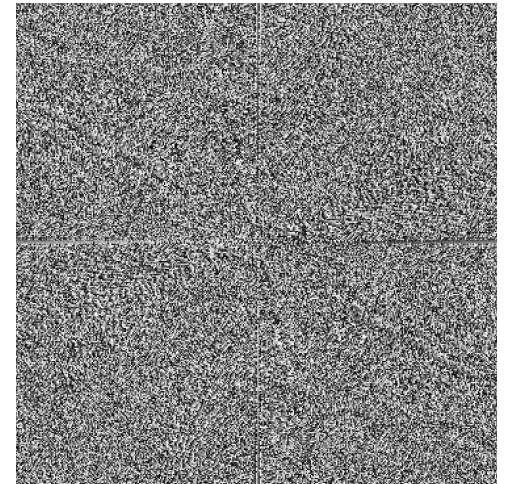


$T(l,m)$

FT  
→



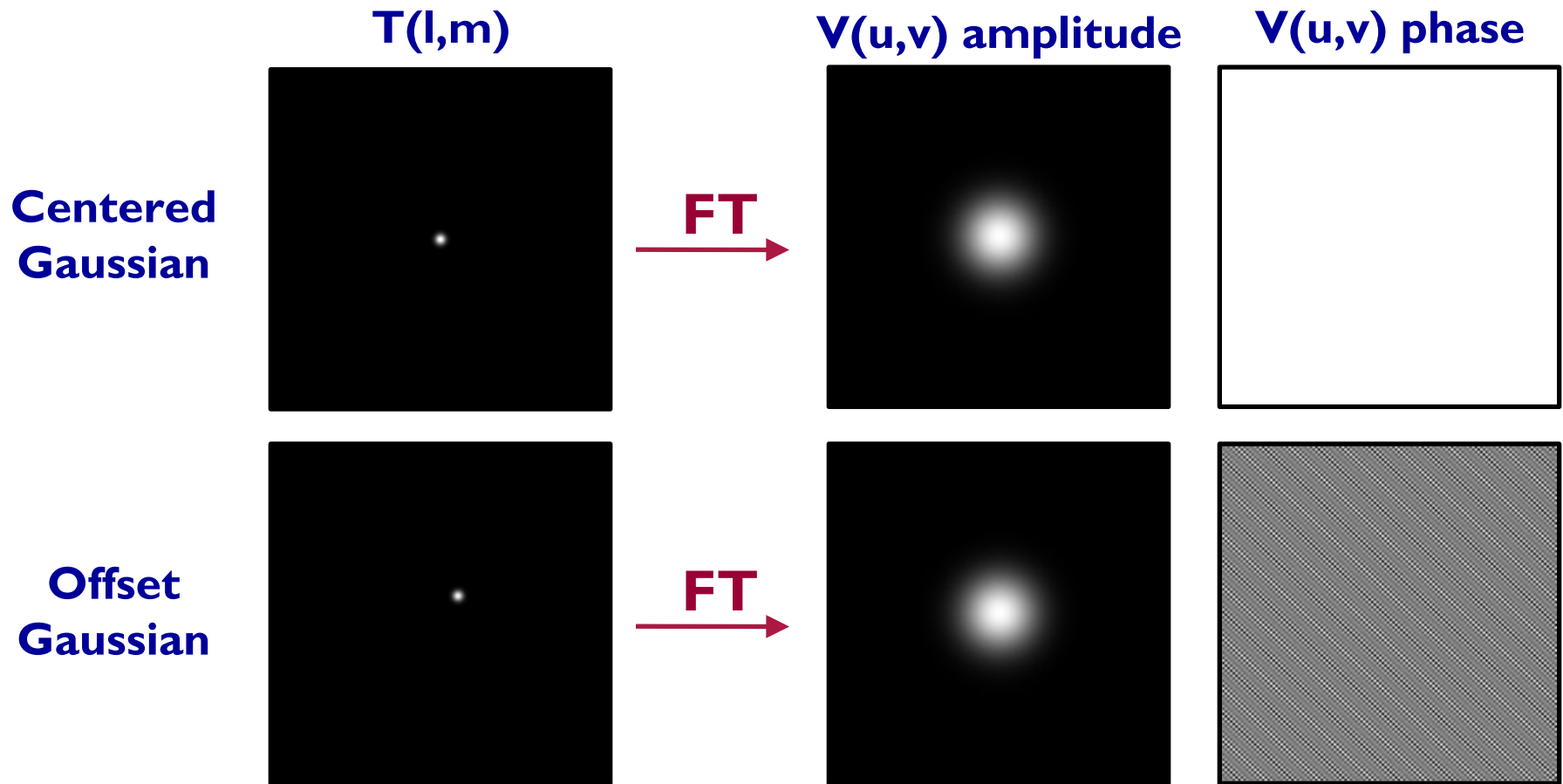
$V(u,v)$  amplitude



$V(u,v)$  phase



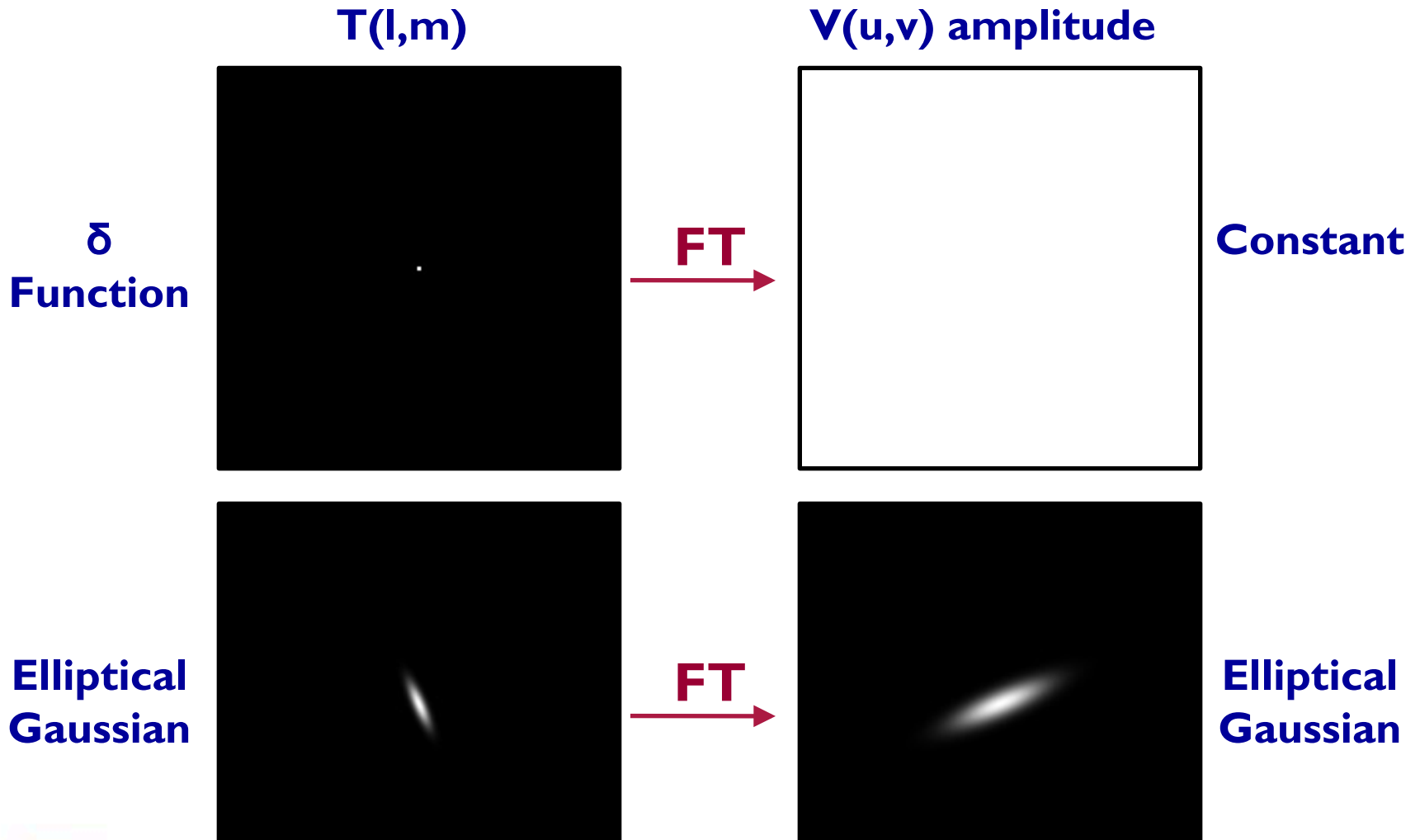
# Examples of 2D Fourier Transforms



## Rules of the Fourier Transform:

Amplitude tells you 'how much' of a spatial frequency  
Phase tells you 'where' the spatial frequency is

# Examples of 2D Fourier Transforms

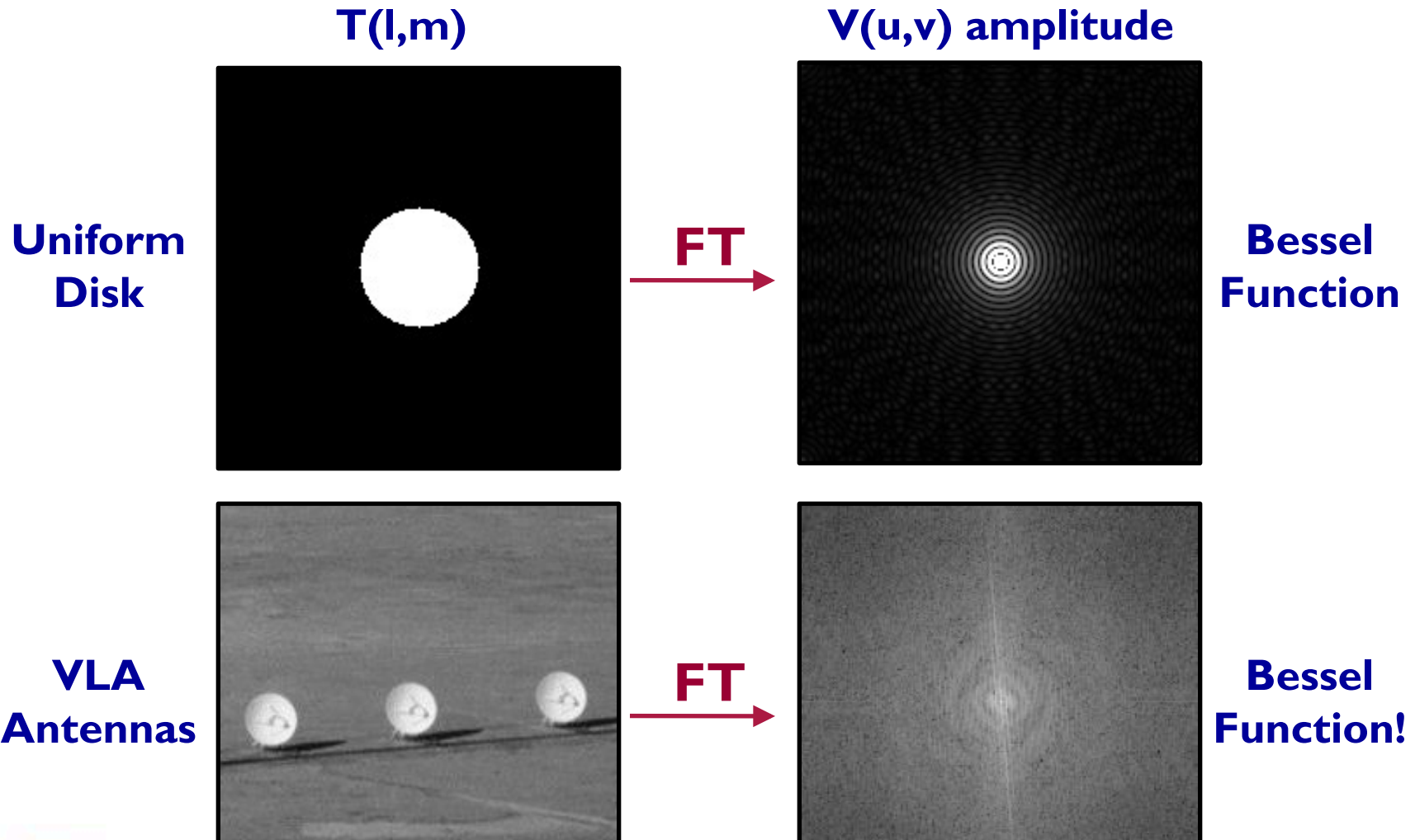


**Rules of the Fourier Transform:**

Narrow features transform to wide features (and vice versa)



# Examples of 2D Fourier Transforms



**Rules of the Fourier Transform:**  
Sharp features (edges) result in many high spatial features

# Basics of Aperture Synthesis

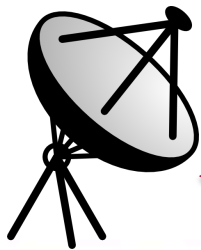
**Idea:** Sample  $V(u,v)$  at a enough  $(u,v)$  points using distributed small aperture antennas to synthesize a large aperture antenna of size  $(u_{\max}, v_{\max})$

One pair of antennas = one baseline

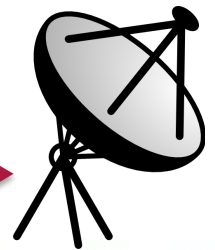
For **N** antennas, we get  **$N(N-1)$**  samples at a time

**How do we fill in the rest of the  $(u,v)$  plane?**

1. Earth's rotation
2. Reconfigure physical layout of N antennas



One baseline = 2  $(u,v)$  points

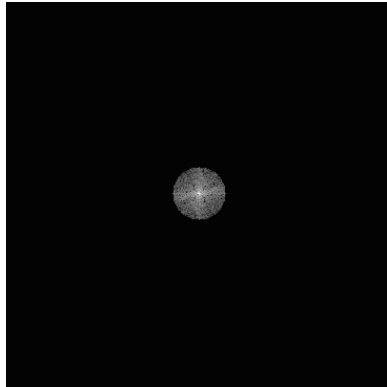


# Implications of (u,v) Coverage

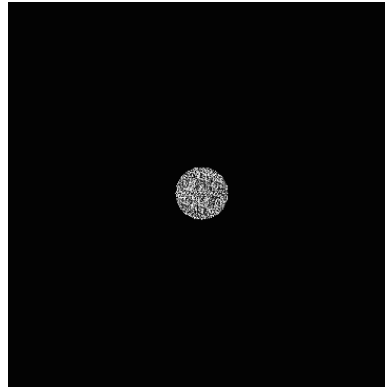
What does it mean if our (u,v) coverage is not complete?

Missing High  
Spatial  
Frequencies

$V(u,v)$  amplitude



$V(u,v)$  phase



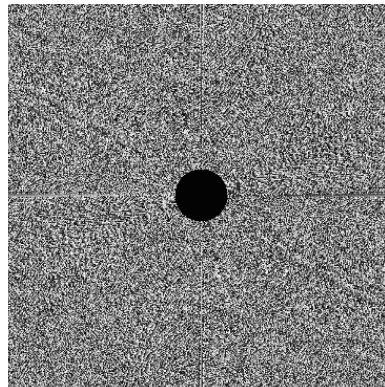
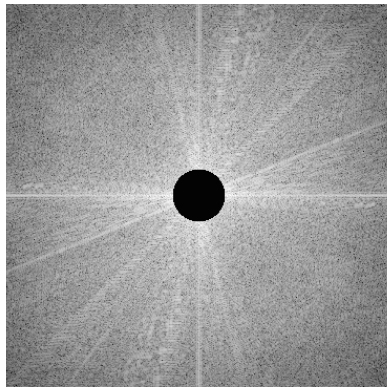
FT



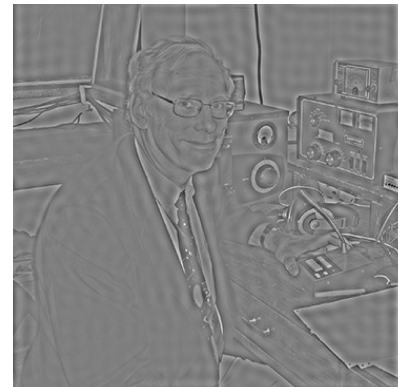
$T(l,m)$



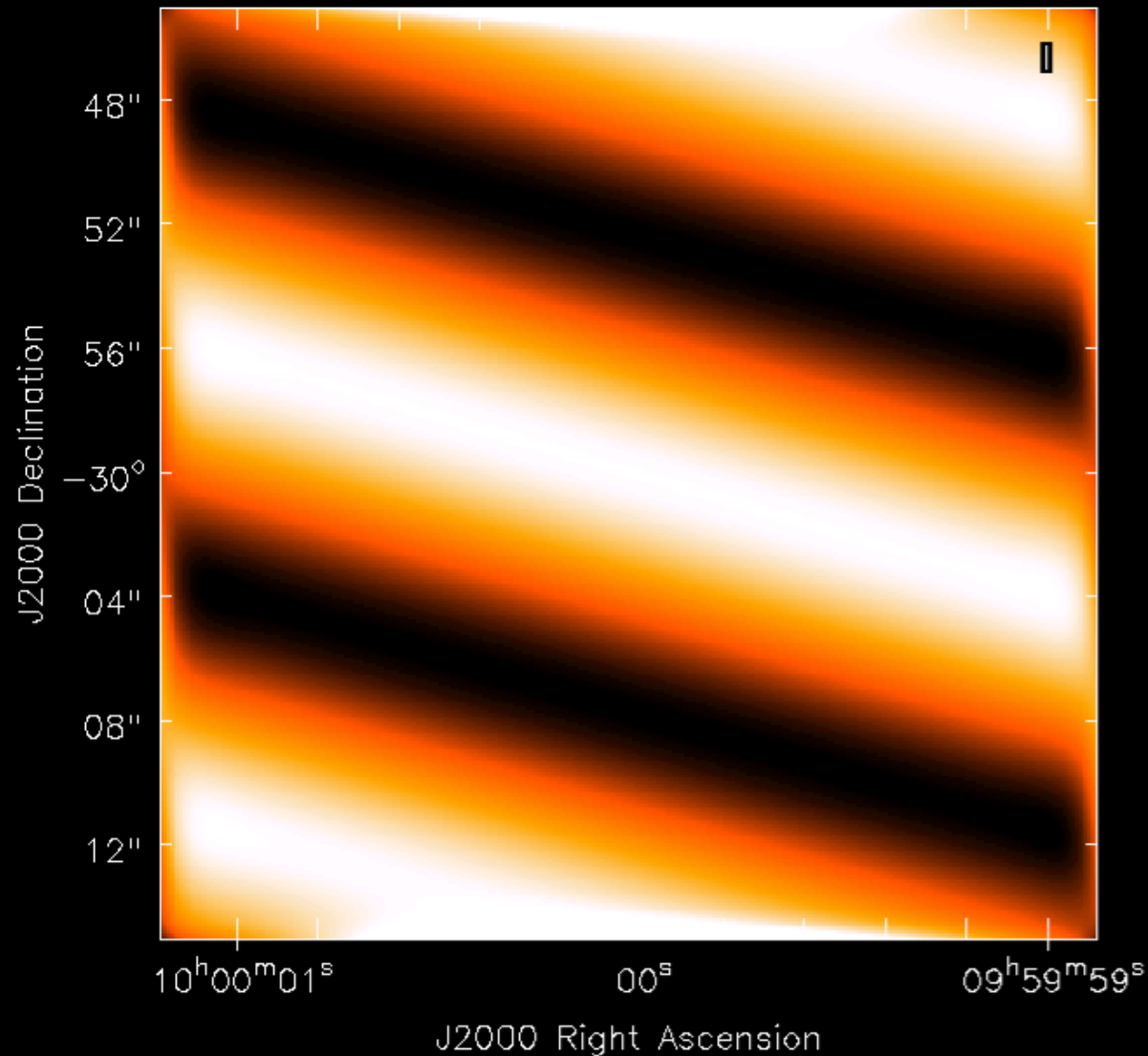
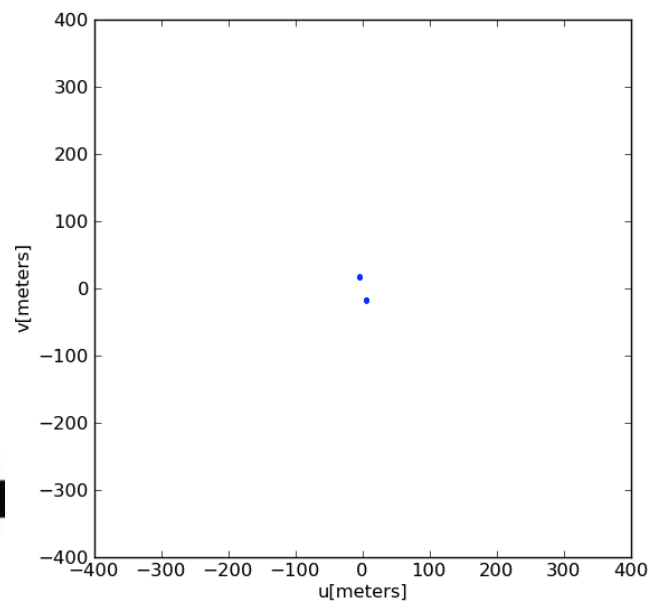
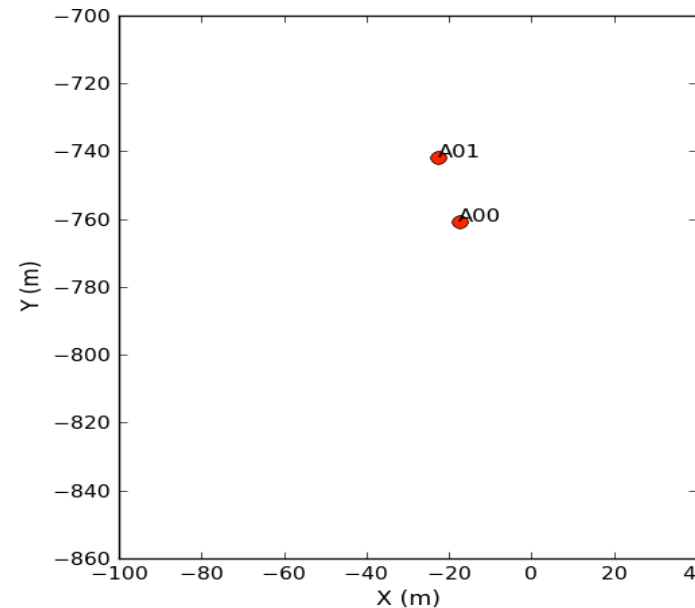
Missing Low  
Spatial  
Frequencies



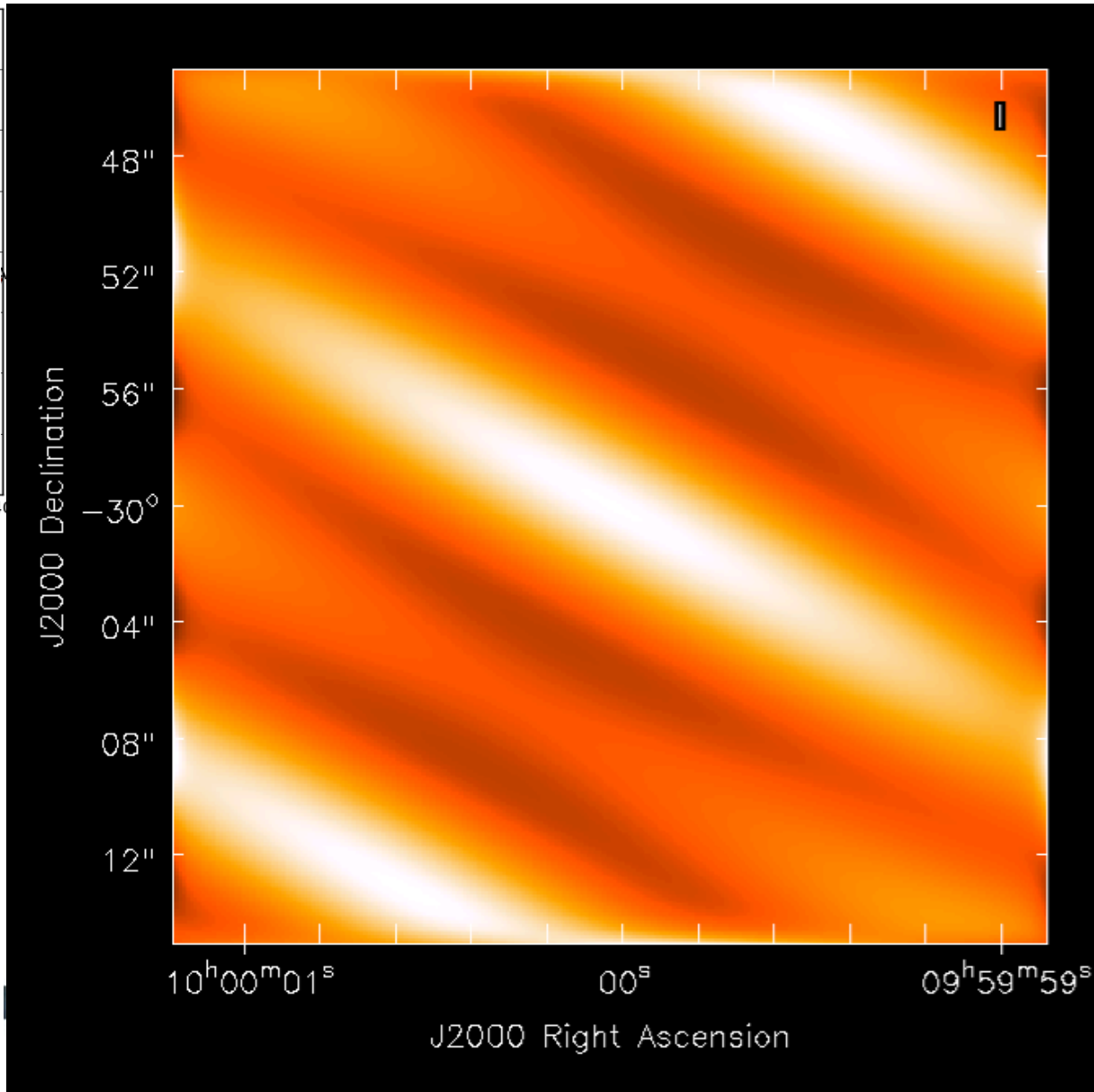
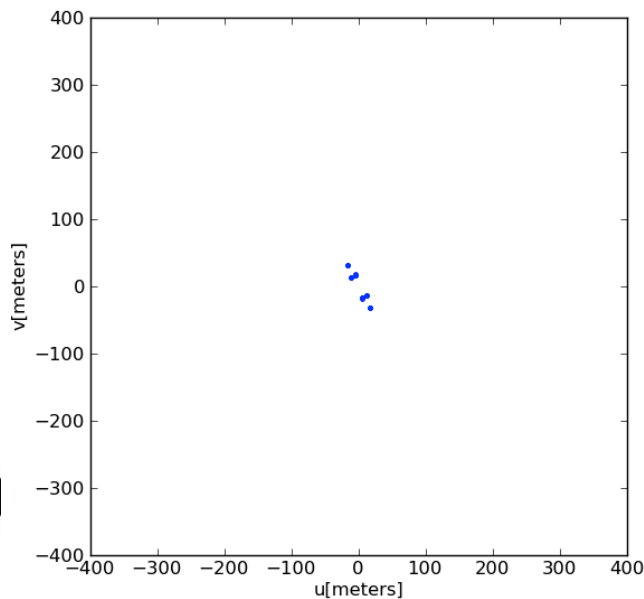
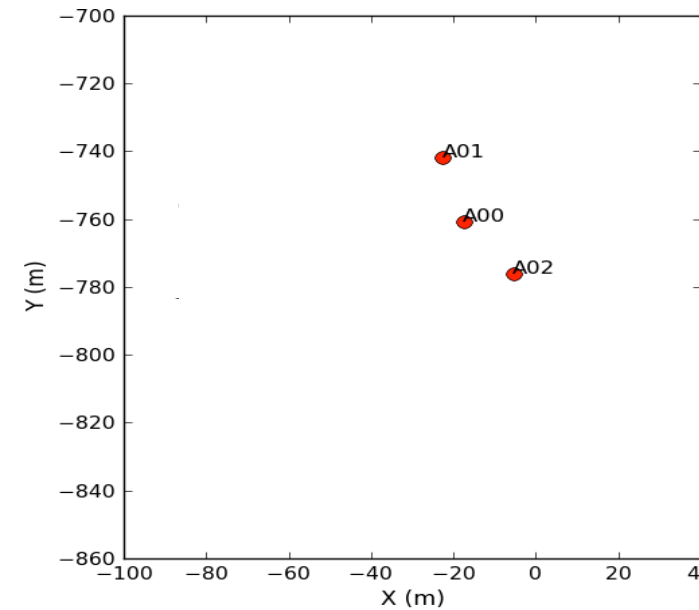
FT



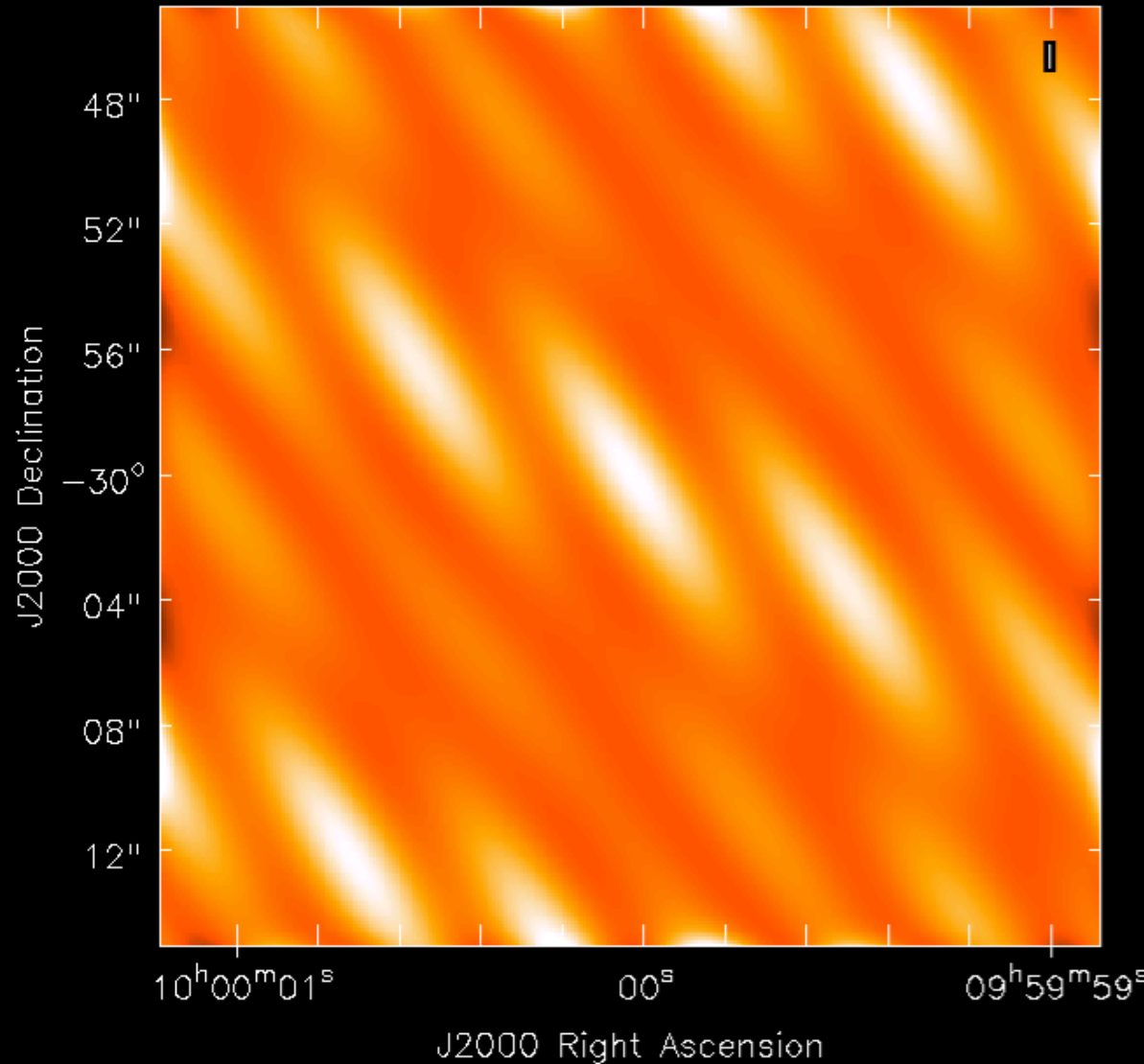
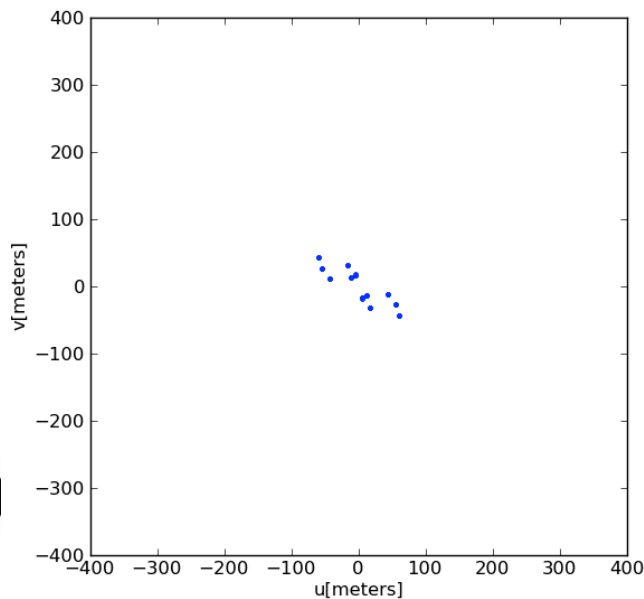
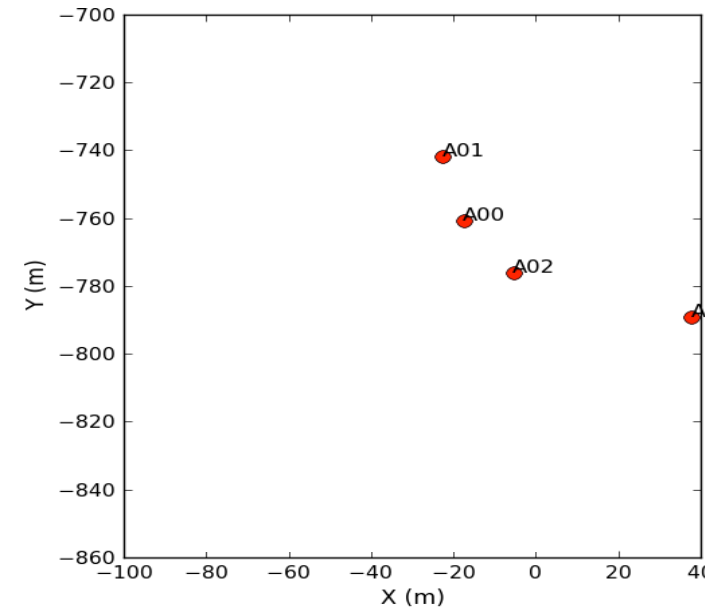
# Example: Fringe pattern with 2 Antennas



# Example: Fringe pattern with 3 Antennas

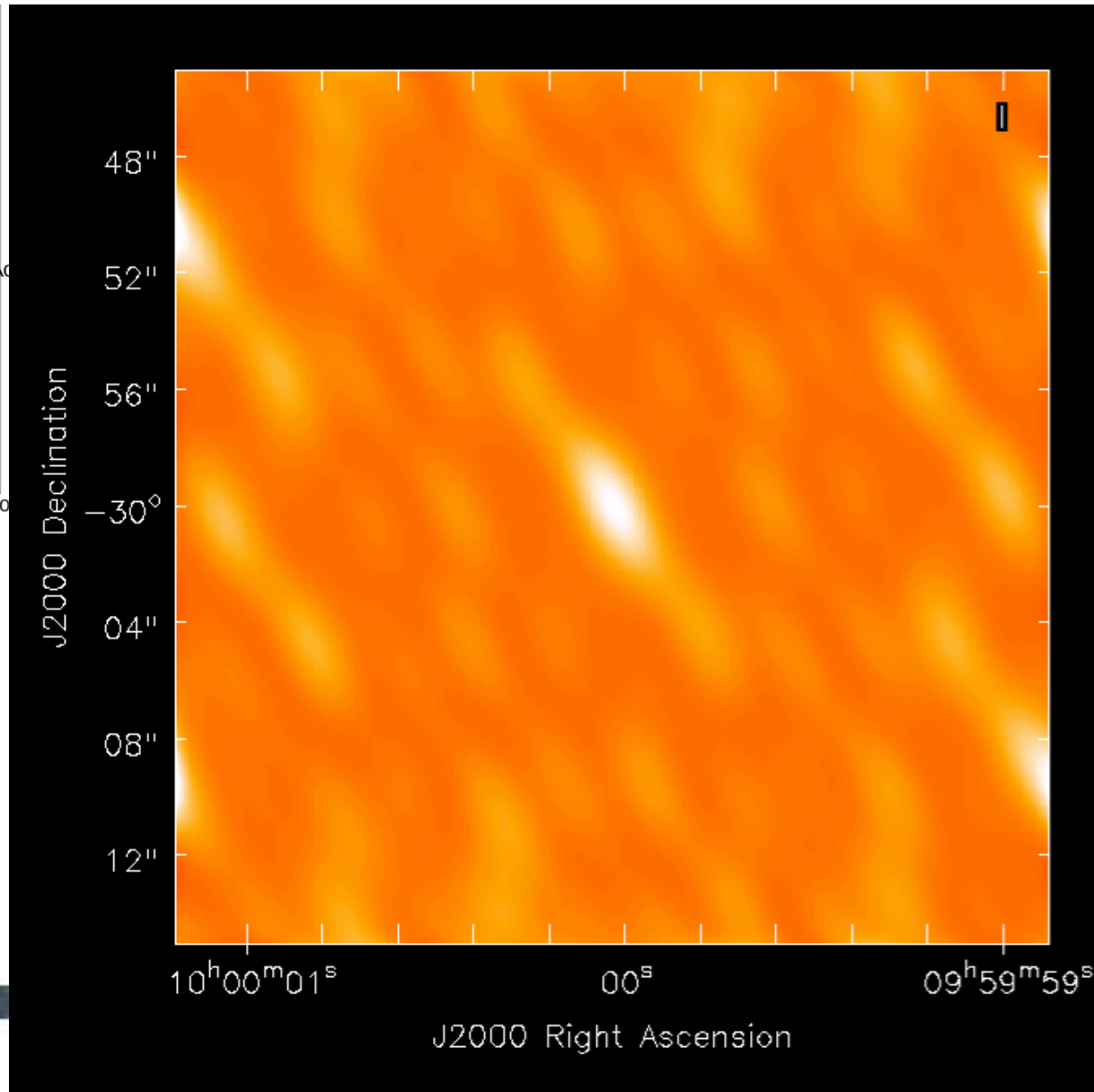
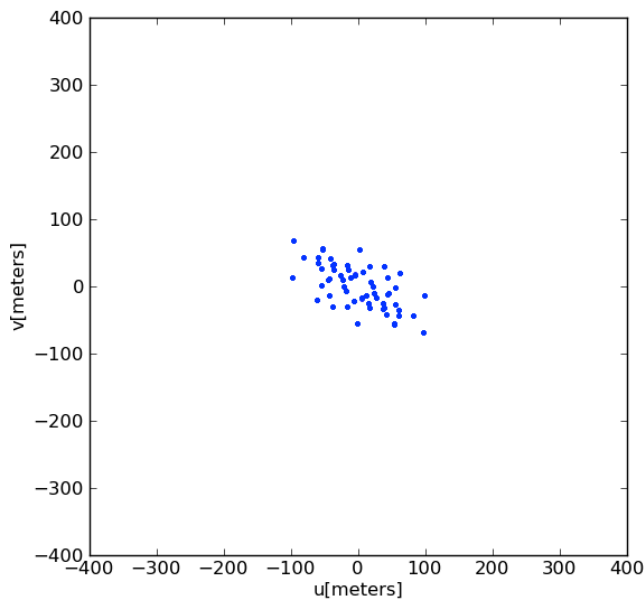
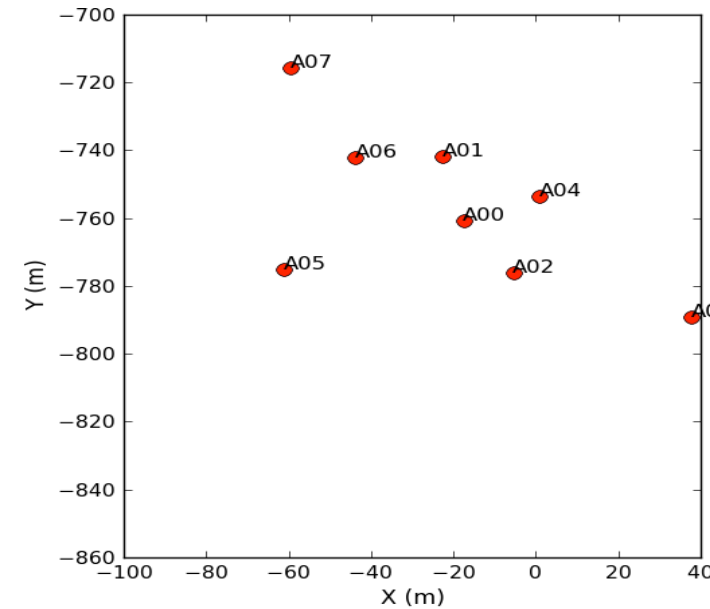


# Example: Fringe pattern with 4 Antennas

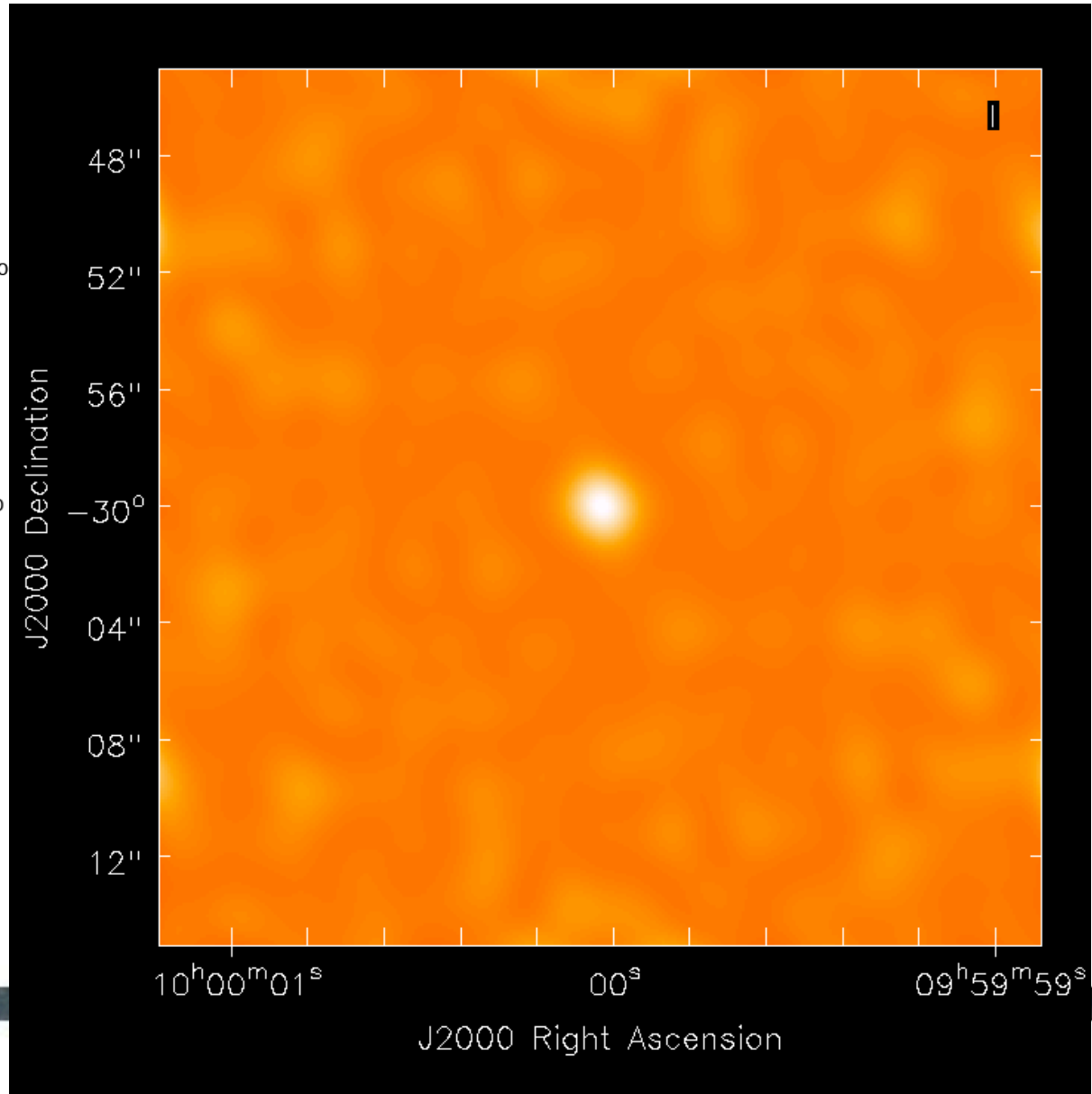
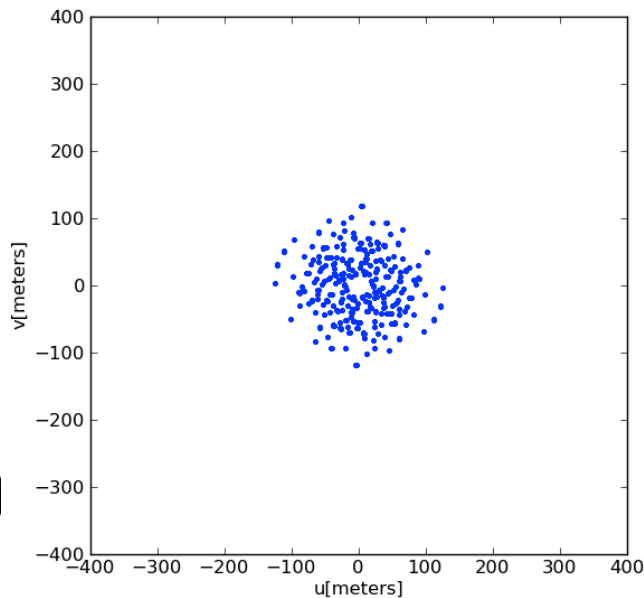
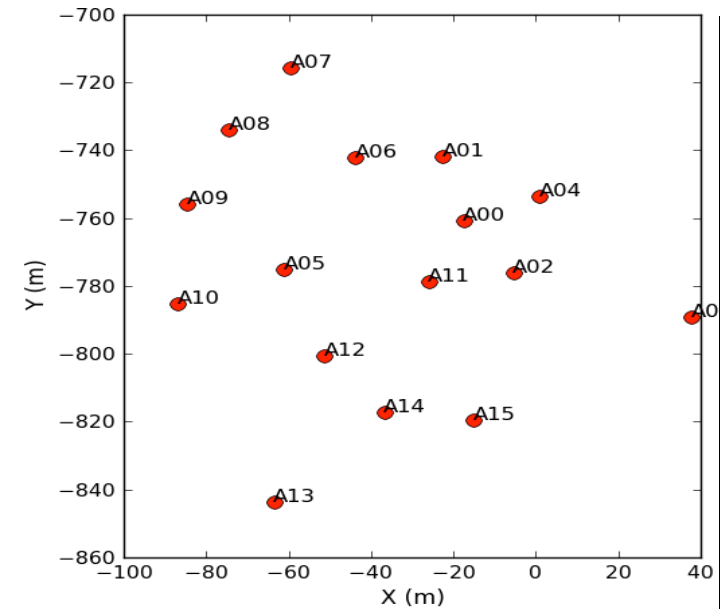




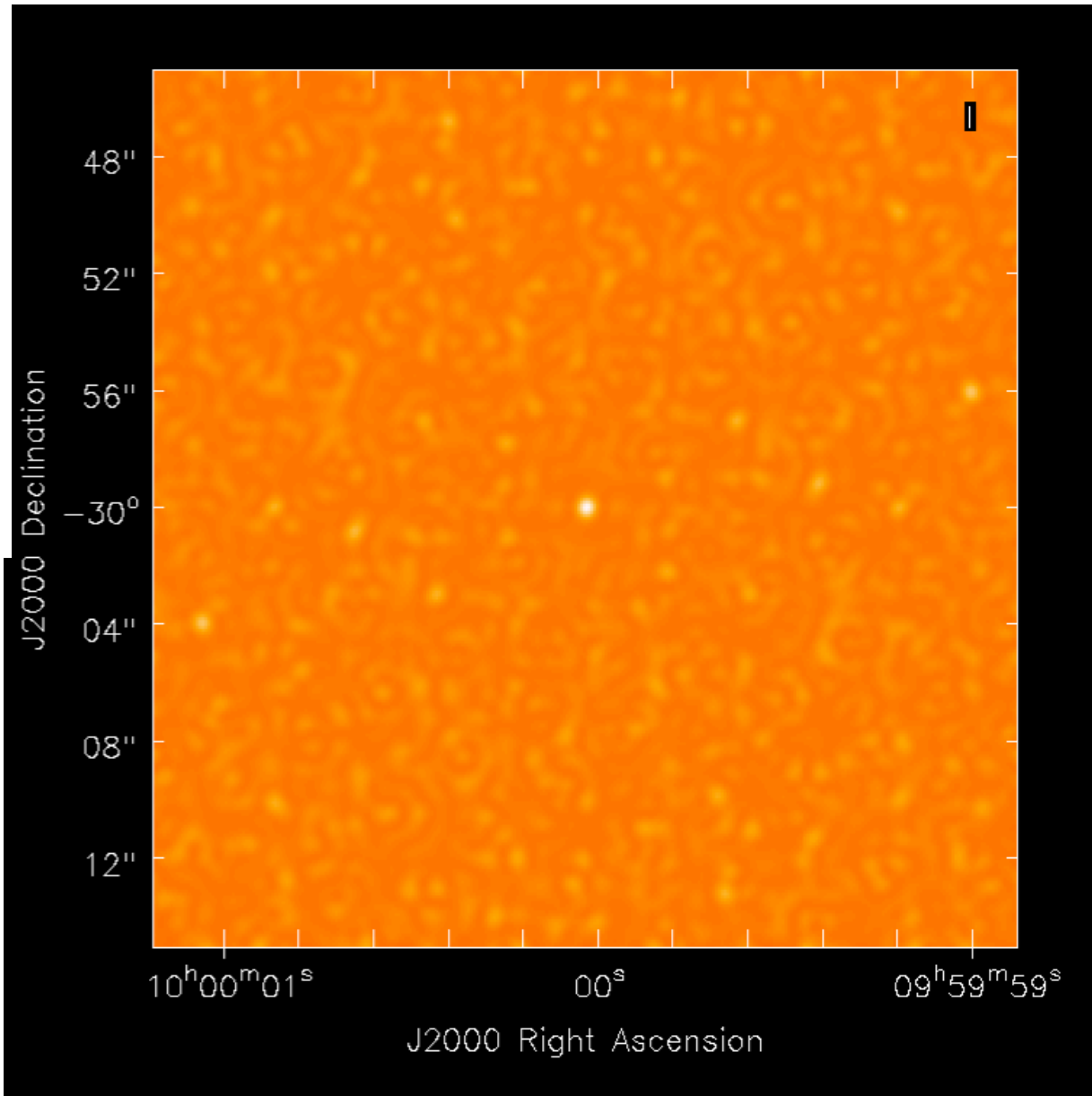
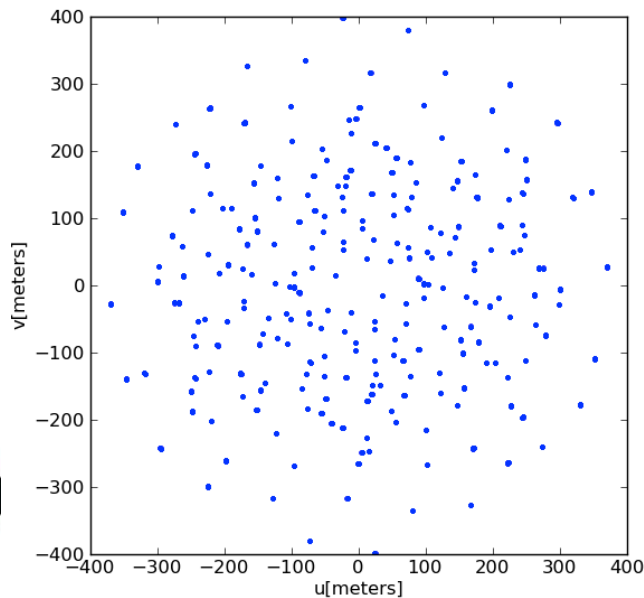
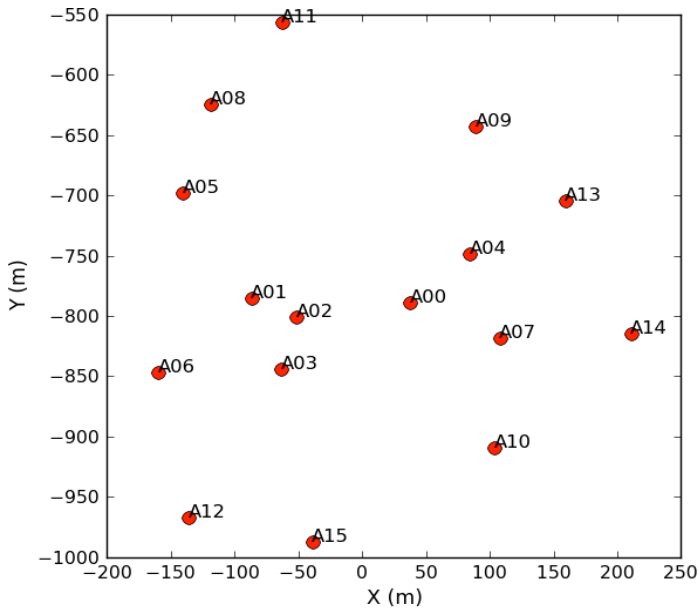
# Example: Fringe pattern with 8 Antennas



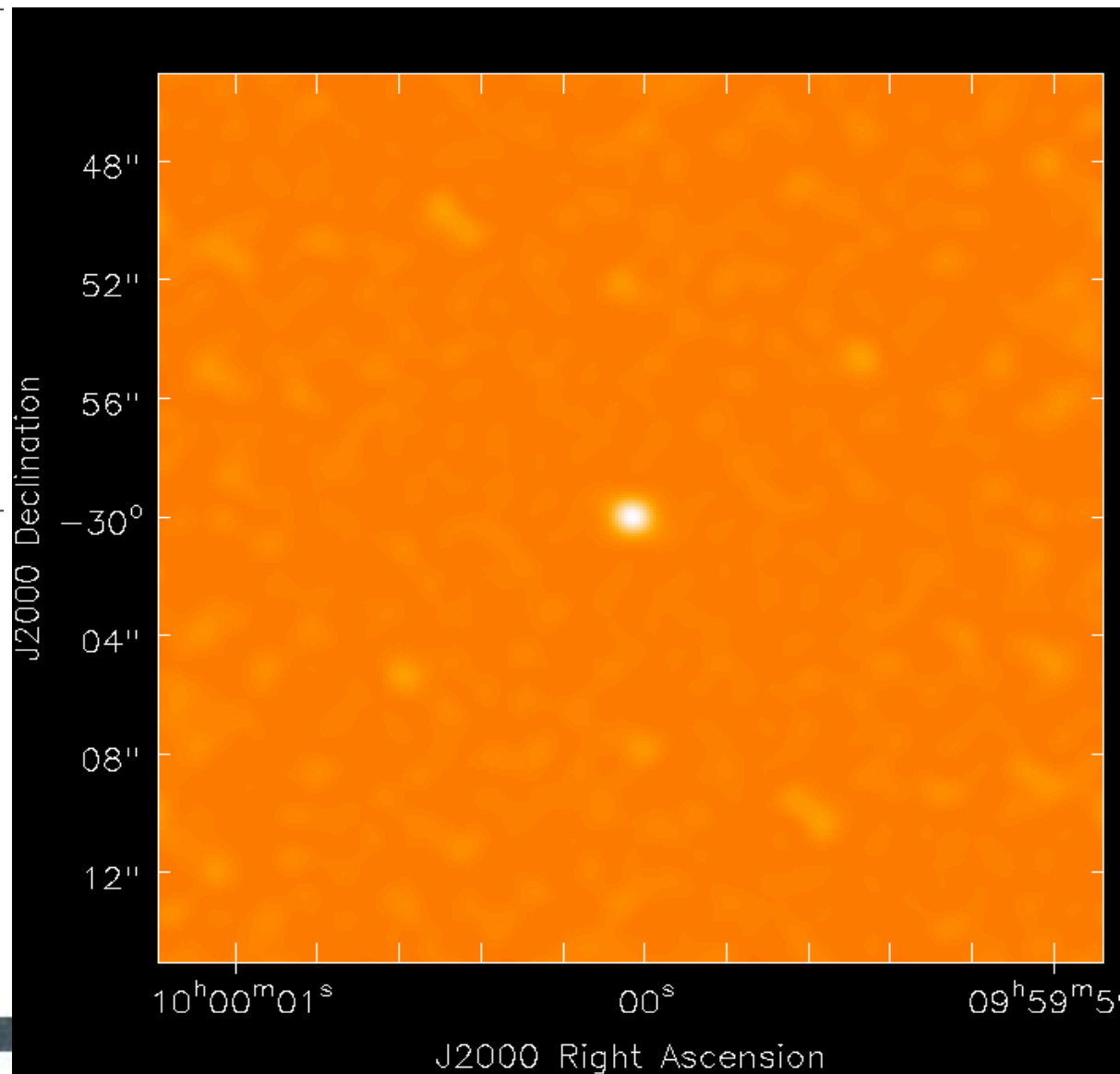
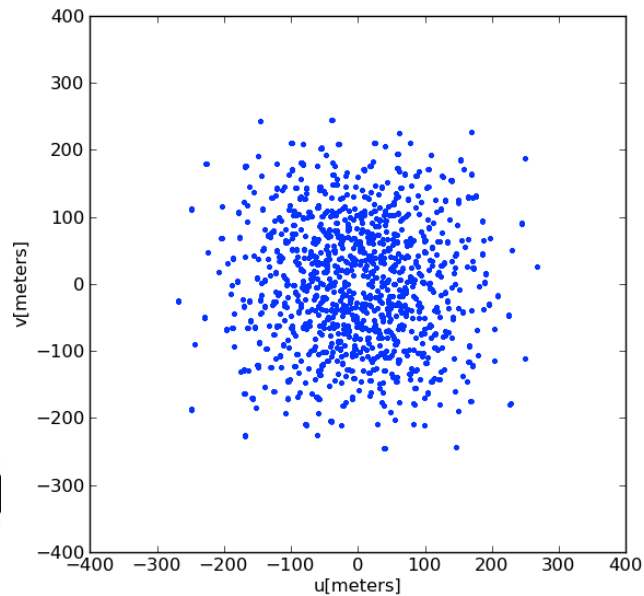
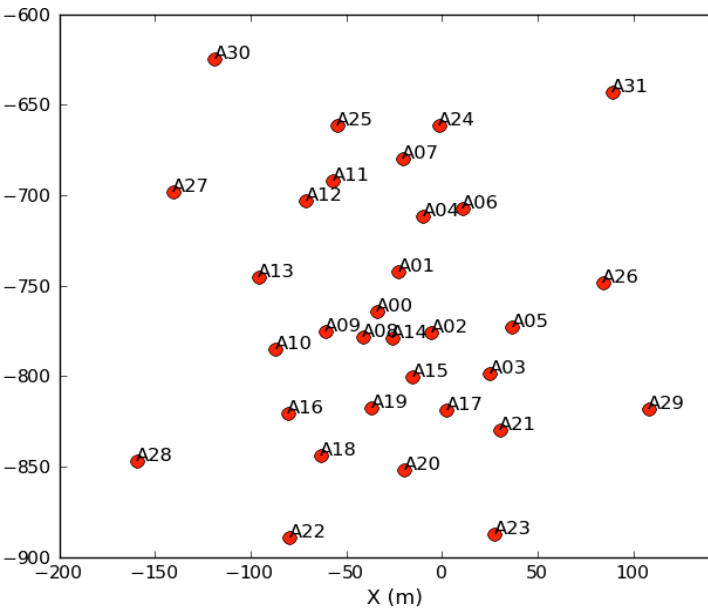
# 16 Antennas – Compact Configuration



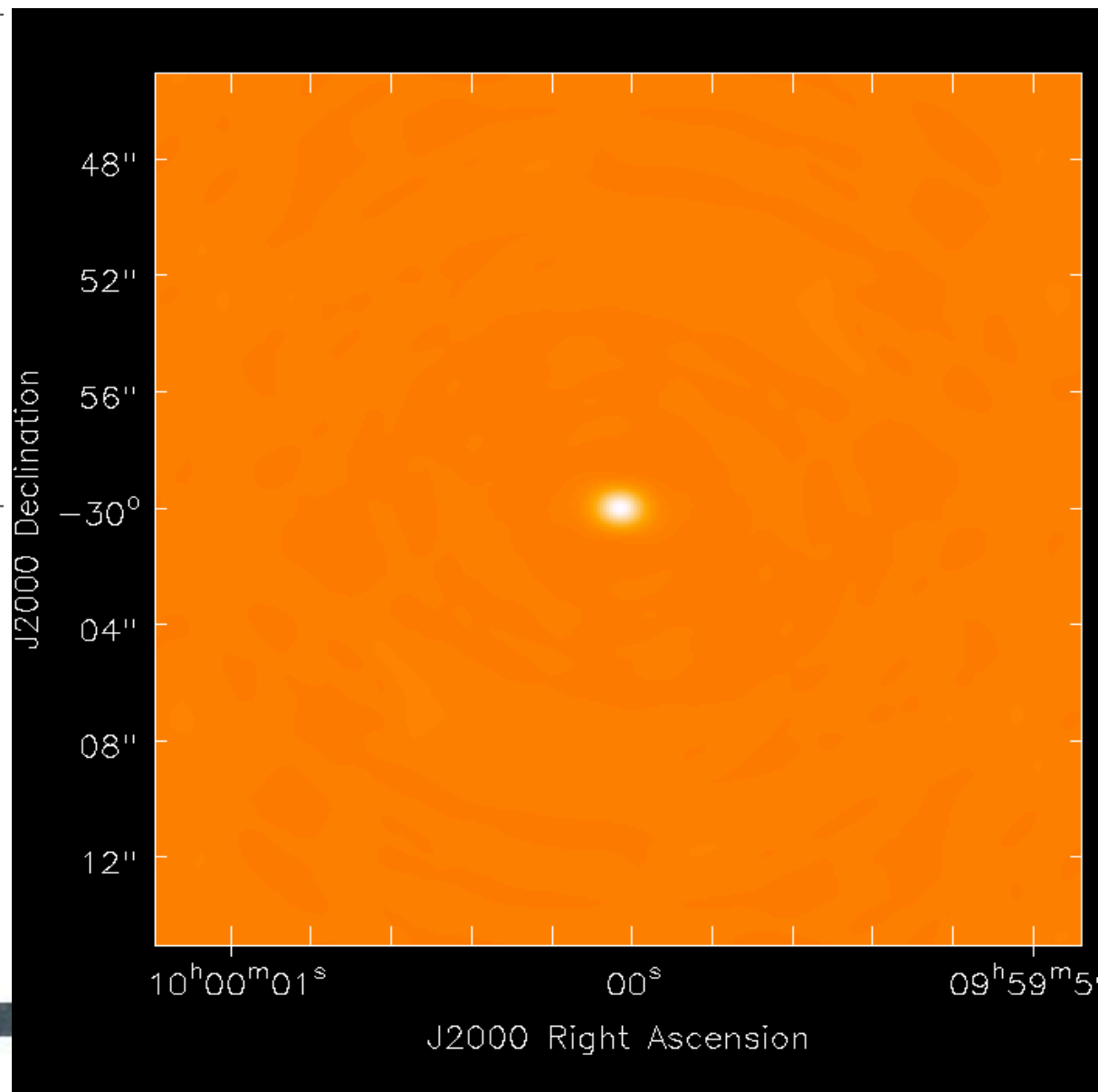
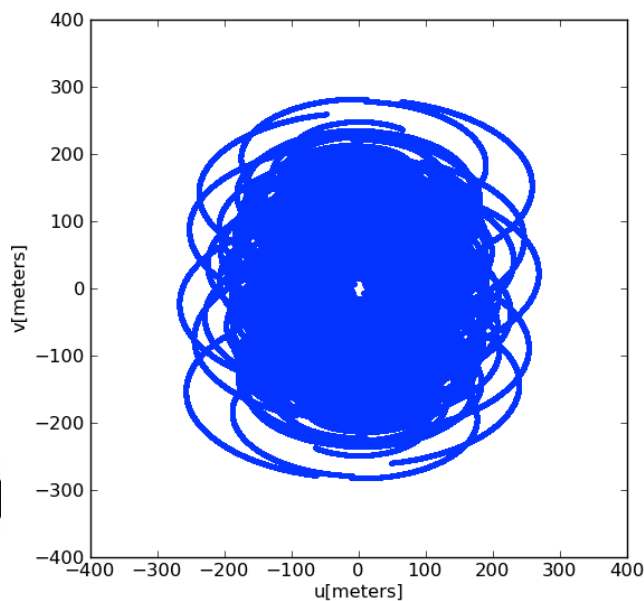
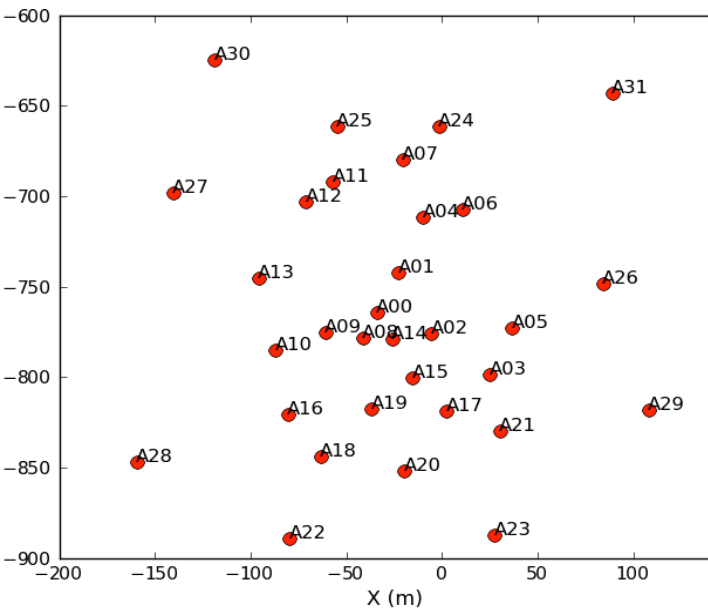
# 16 Antennas – Extended Configuration



# 32 Antennas – Instantaneous



# 32 Antennas – 8 hours



# Characteristic Angular Scales

**Angular resolution of telescope array:**

$$\sim \lambda/B_{\max} \text{ (} B_{\max} = \text{longest baseline)}$$

**Maximum angular scale:**

$$\sim \lambda/B_{\min} \text{ (} B_{\min} = \text{shortest distance between antennas)}$$

**Field of view (FOV):**

$$\sim \lambda/D \text{ (} D = \text{antenna diameter)}$$

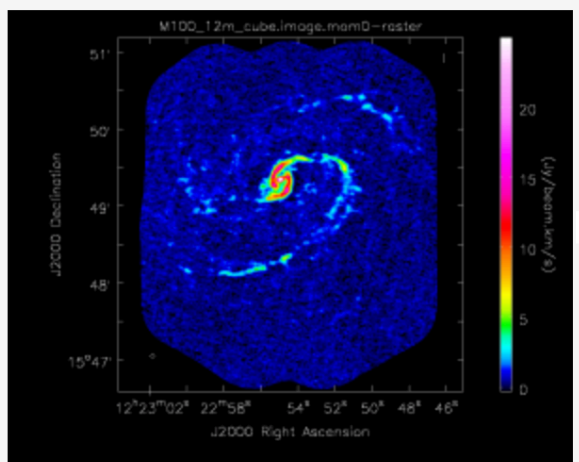
\*Sources more extended than the FOV can be observed using multiple pointing centers in a mosaic

**An interferometer is sensitive to a range of angular sizes:  $\lambda/B_{\max} < \theta < \lambda/B_{\min}$**

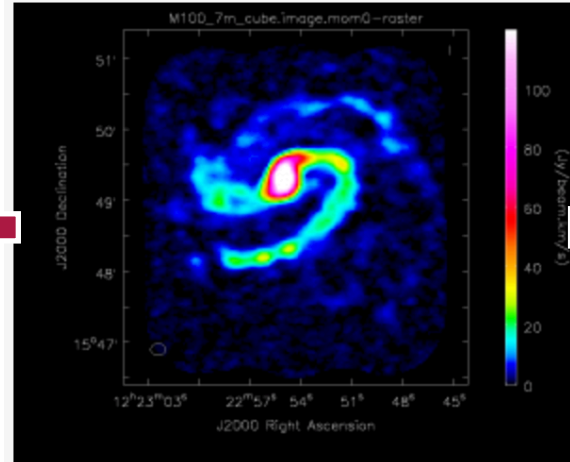


# Characteristic Angular Scales: M100

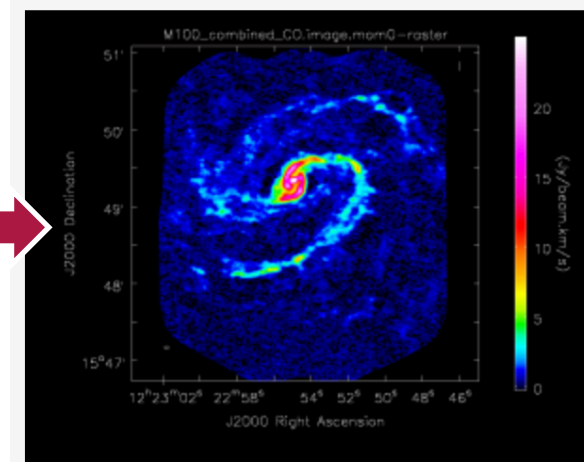
ALMA 12m



ACA 7m



Combined



ALMA 12m shows smaller spatial scales (denser, clumpier emission)  
ACA 7m data shows larger spatial scales (diffuse, extended emission)

**To get both — you need a combined image!**

# Angular Scales — A Proposal Tip!

Most Extended configuration	Allowed Compact configuration pairings	Extended 12-m Array Multiplier	Multiplier if compact 12-m Array needed	Multiplier if 7-m Array needed	Multiplier if TP Array needed and allowed
7-m Array	TP			1	1.7
C43-1	7-m Array & TP	1		7.0	11.9
C43-2	7-m Array & TP	1		4.7	8.0
C43-3	7-m Array & TP	1		2.4	4.1
C43-4	C43-1 & 7-m Array & TP	1	0.34	2.4	4.0
C43-5	C43-2 & 7-m Array & TP	1	0.26	1.2	2.1
C43-6	C43-3 & 7-m Array & TP	1	0.25	0.6	1.0
C43-7	C43-4	1	0.23		
C43-8	C43-5	1	0.22		
C43-9	C43-6	1	0.21		
C43-10	-	1			

From the ALMA Cycle 6 Proposal Guide

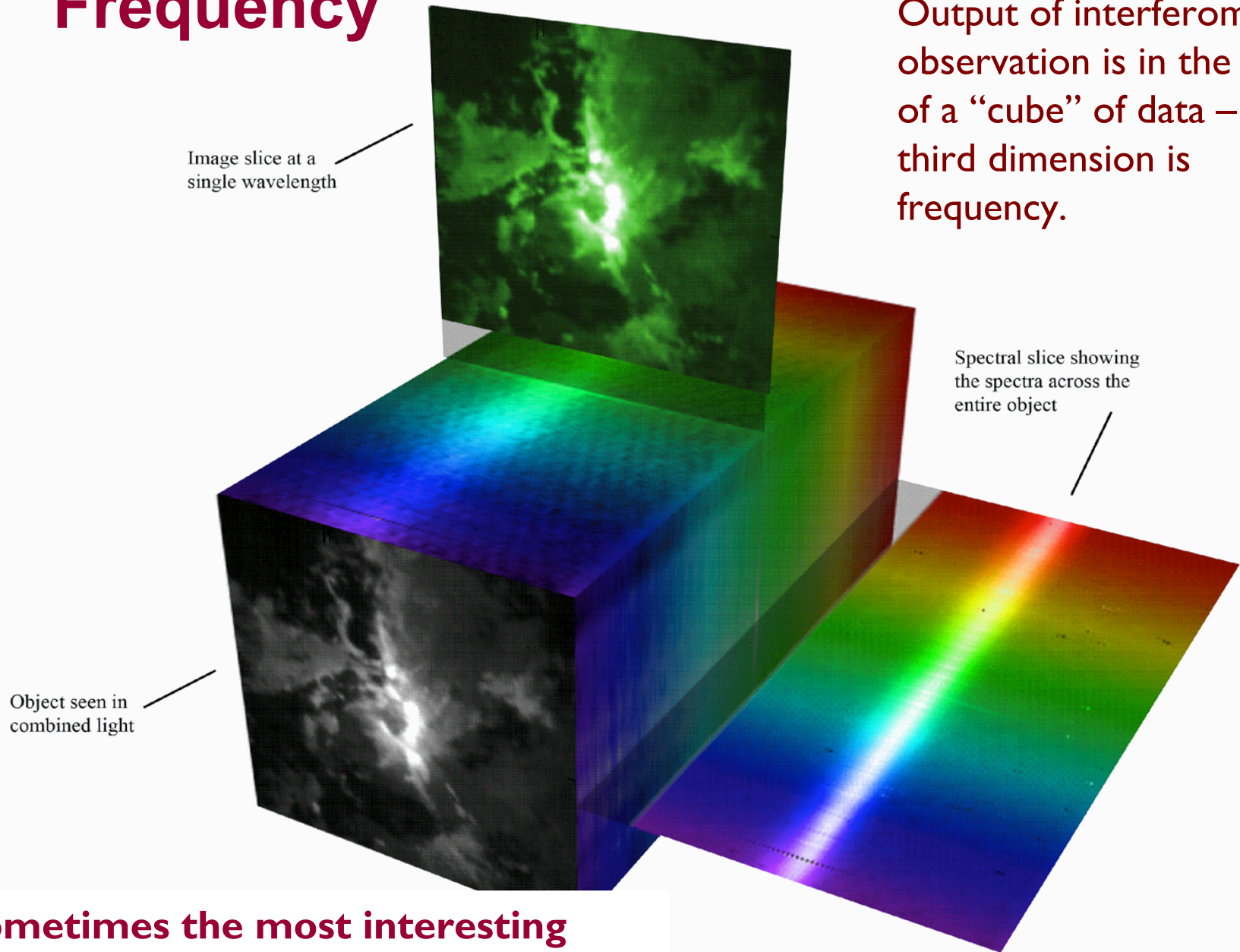


# Interferometry: Spatial Considerations (Summary)

- The **sensitivity** is given by the number of antennas times their area
- The **field of view** is given by the beam of a single antenna (corresponding to the resolution for a single dish telescope or the primary beam)
- The **resolution** is given by the largest distance between antennas (called the synthesized beam)
- The **largest angular scale** that can be imaged is given by the shortest distance between antennas

# Frequency

Output of interferometric observation is in the form of a “cube” of data – the third dimension is frequency.



**Sometimes the most interesting science lies in the third dimension!**

# Radio Astronomy uses *Heterodyne Technology*

Observed sky frequencies are converted to lower frequency signals (IF output) by mixing with a signal created by a Local Oscillator. The output can then be amplified and analyzed more easily while retaining the original phase and amplitude information.

**Synoptic diagram of heterodyne receivers  
(basic building blocks)**

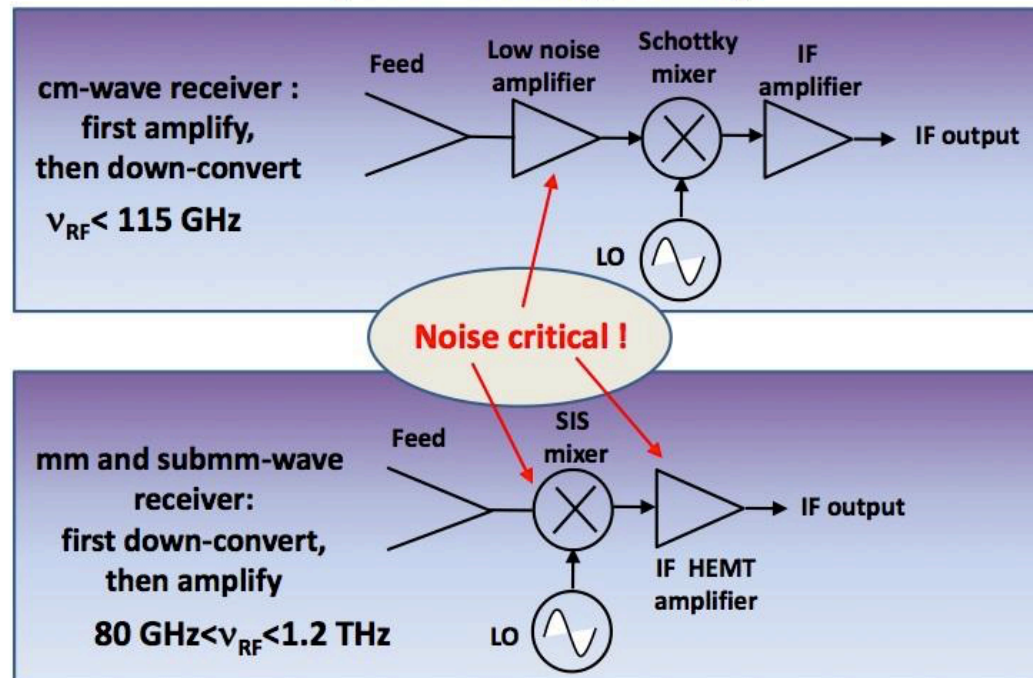
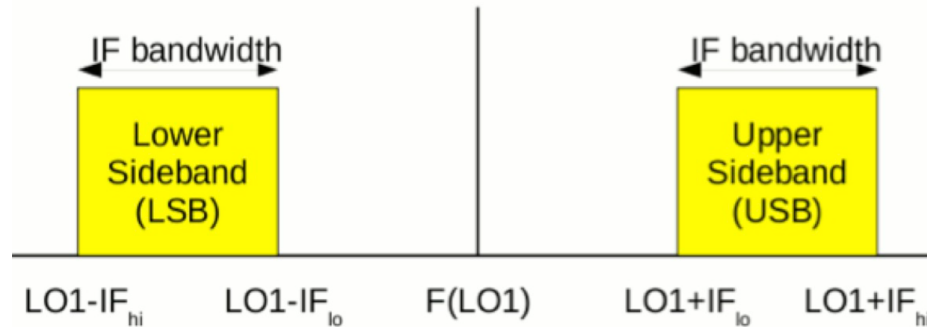


Image from  
Alessandro Navarrini  
(IRAM)



# ALMA's Correlator

ALMA's correlator can be configured in many ways, allowing for great flexibility in spectral resolution and coverage!

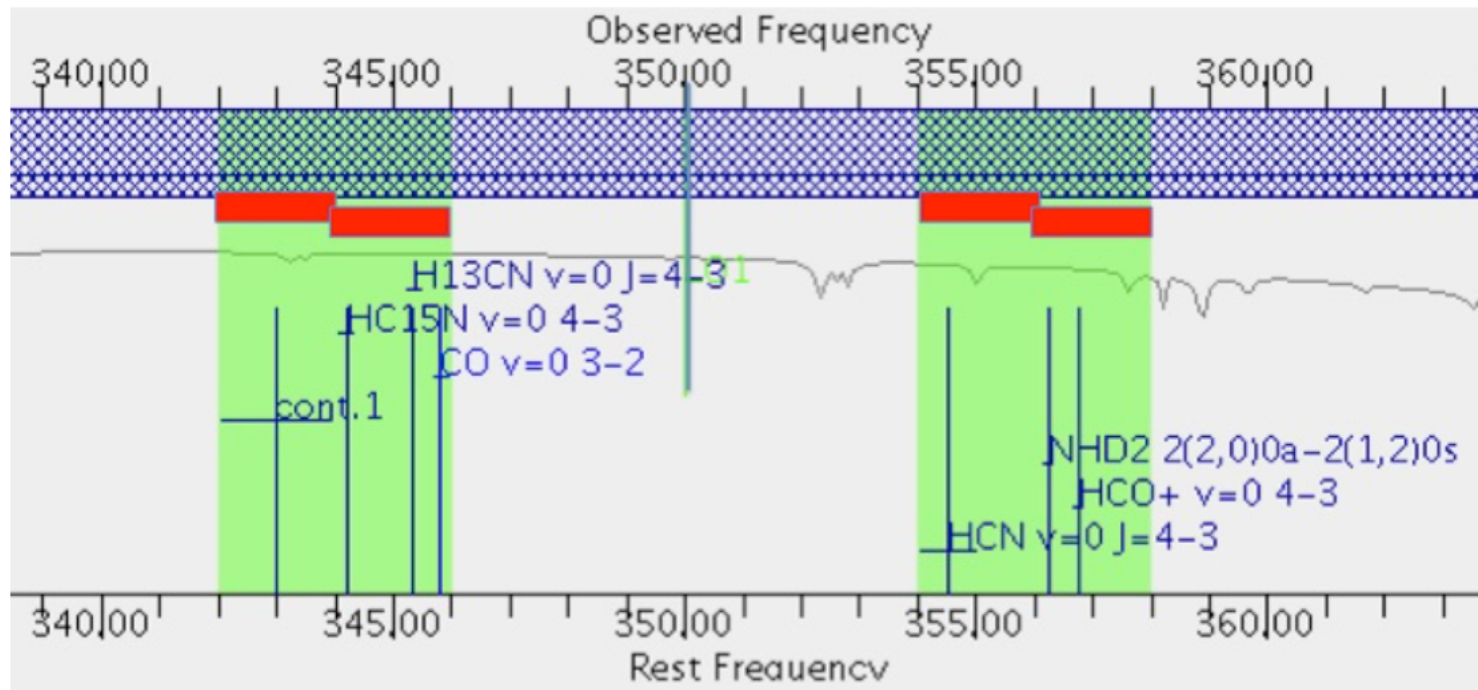


*\*Expanded in Band 6*

- Four 2 GHz-wide, tunable\* basebands in each polarization. Total bandwidth up to 7.5 GHz (x2 polarizations)
- IF range is 4-8 GHz\* in Bands 3-8 and 4-12 GHz in Bands 9&10
- Choose fine (down to 15 kHz) up to broad spectral resolution, split baseband into 2-4 spectral windows as needed



# ALMA's Correlator



## Example of a Frequency Setup

Green areas: IF ranges

Blue hashed: tuning range

Red bars: basebands

Curved line: atmospheric transmission

Horizontal lines: spectral windows

# Calibration

Calibration is the effort to measure and remove the time-dependent and frequency-dependent atmospheric and instrumental variations.

## Gain calibrator

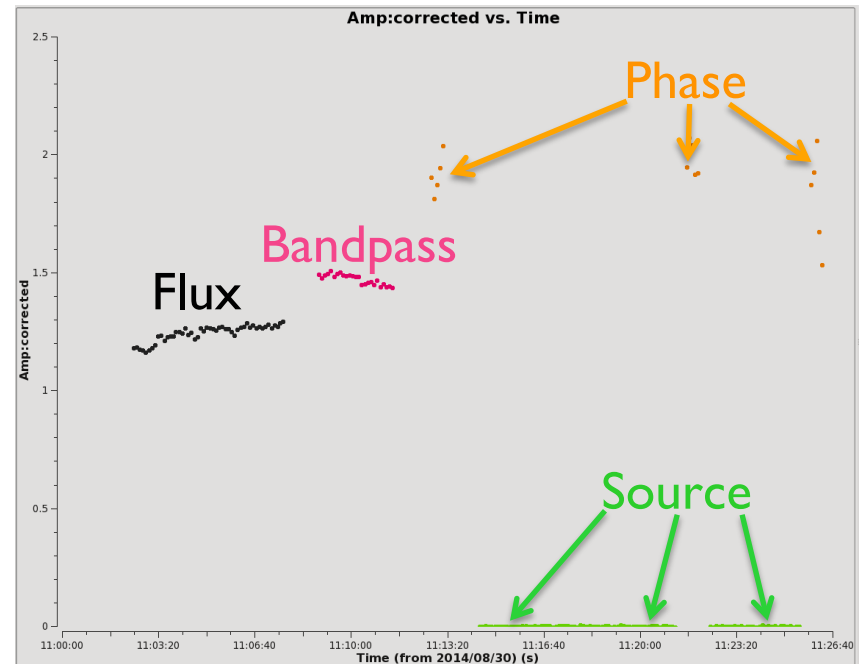
Bright quasar near science target  
Solves for atmospheric and instrumental variations with time

## Bandpass calibrator

Bright quasar  
Fixes instrumental effects and variations vs. frequency

## Absolute flux calibrator

Solar system object or quasar  
Used to scale relative amplitudes to absolute value



- ***In most cases, ALMA will handle calibration***
- ***Calibration results in overhead: sharing calibration is therefore good!***

# Key Takeaways/Considerations

- Interferometry samples the Fourier components of the sky brightness: visibilities
  - To make an image in the sky plane, we have to Fourier transform our sampled visibilities
  - $uv$  coverage will be incomplete (the more complete the better). With ALMA, high fidelity should be achieved in a short time, but simulations can test this
- Different baselines (array configurations!) sample different spatial scales
  - Angular resolution is given by  $\sim \lambda/B_{\max}$  → long baselines for high resolution
  - Maximum angular scale  $\sim \lambda/B_{\min}$  → resolve out large-scale structure
- If your mapping area exceeds  $1/3$  the primary beam: mosaic
- Spectral considerations: ALMA's correlator is highly flexible, but there are restrictions on what you can do!

# Good Future References

Thompson, A.R., Moran, J.M., Swensen, G.W. 2017 “Interferometry and Synthesis in Radio Astronomy”, 3rd edition (Springer)

<http://www.springer.com/us/book/9783319444291>

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Perley, R.A., Schwab, F.R., Bridle, A.H. eds. 1989 ASP Conf. Series 6 “Synthesis Imaging in Radio Astronomy” (San Francisco: ASP)

[www.aoc.nrao.edu/events/synthesis](http://www.aoc.nrao.edu/events/synthesis)

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IRAM Interferometry School proceedings

[www.iram.fr/IRAMFR/IS/IS2008/archive.html](http://www.iram.fr/IRAMFR/IS/IS2008/archive.html)

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