

Introduction to Radio Interferometry



Cassie Reuter

**Authors: Alison Peck, Jim Braatz,
Ashley Bemis, Sabrina Stierwalt**

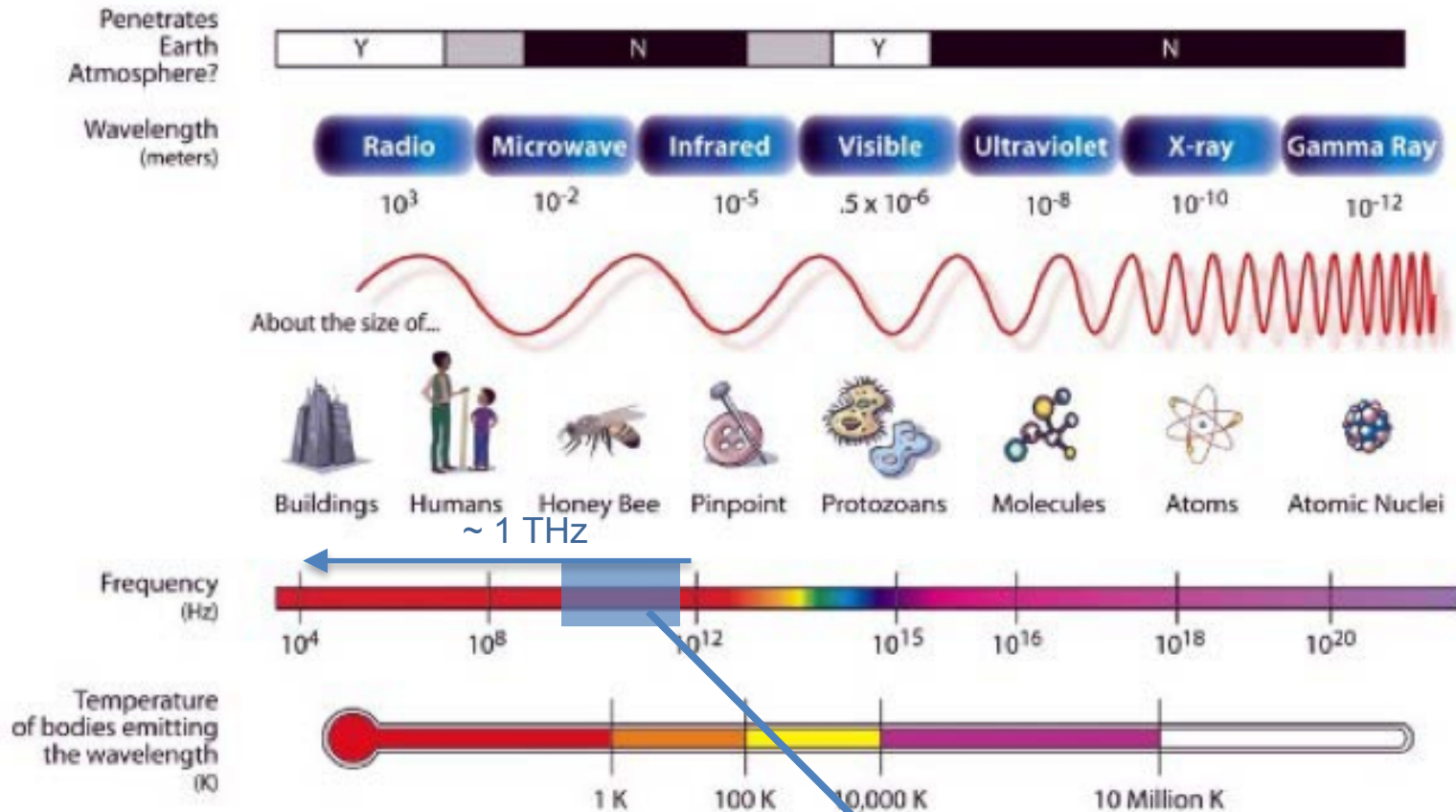
Atacama Large Millimeter/submillimeter Array
Karl G. Jansky Very Large Array
Very Long Baseline Array



Brief Outline

- Why Radio Astronomy
- What is interferometry?
- Fourier transforms
- UV plane sampling
- Calibration

What is radio astronomy?

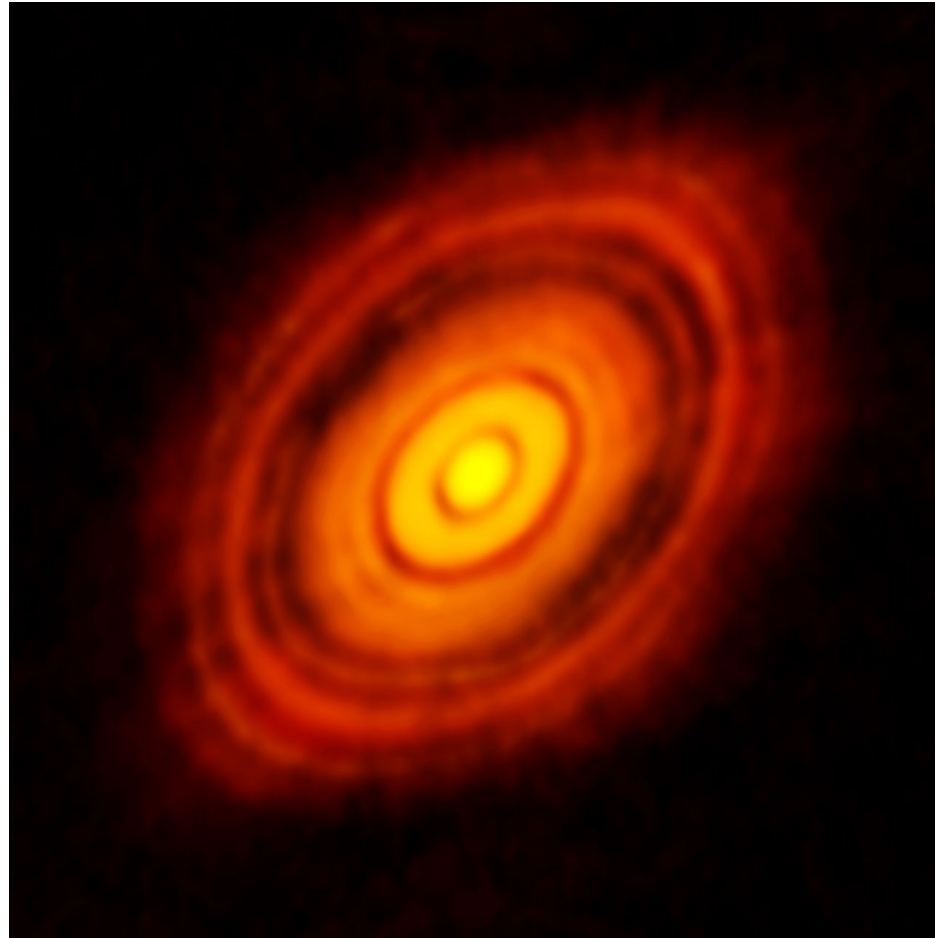


ALMA
 $\sim 84 - 950$ GHz
 $\sim 3 - 0.3$ mm

A photograph showing several large blue parabolic radio telescope dishes at the ALMA observatory, set against a clear sky.

What can you observe?

Protoplanetary discs like this one around HL Tauri!



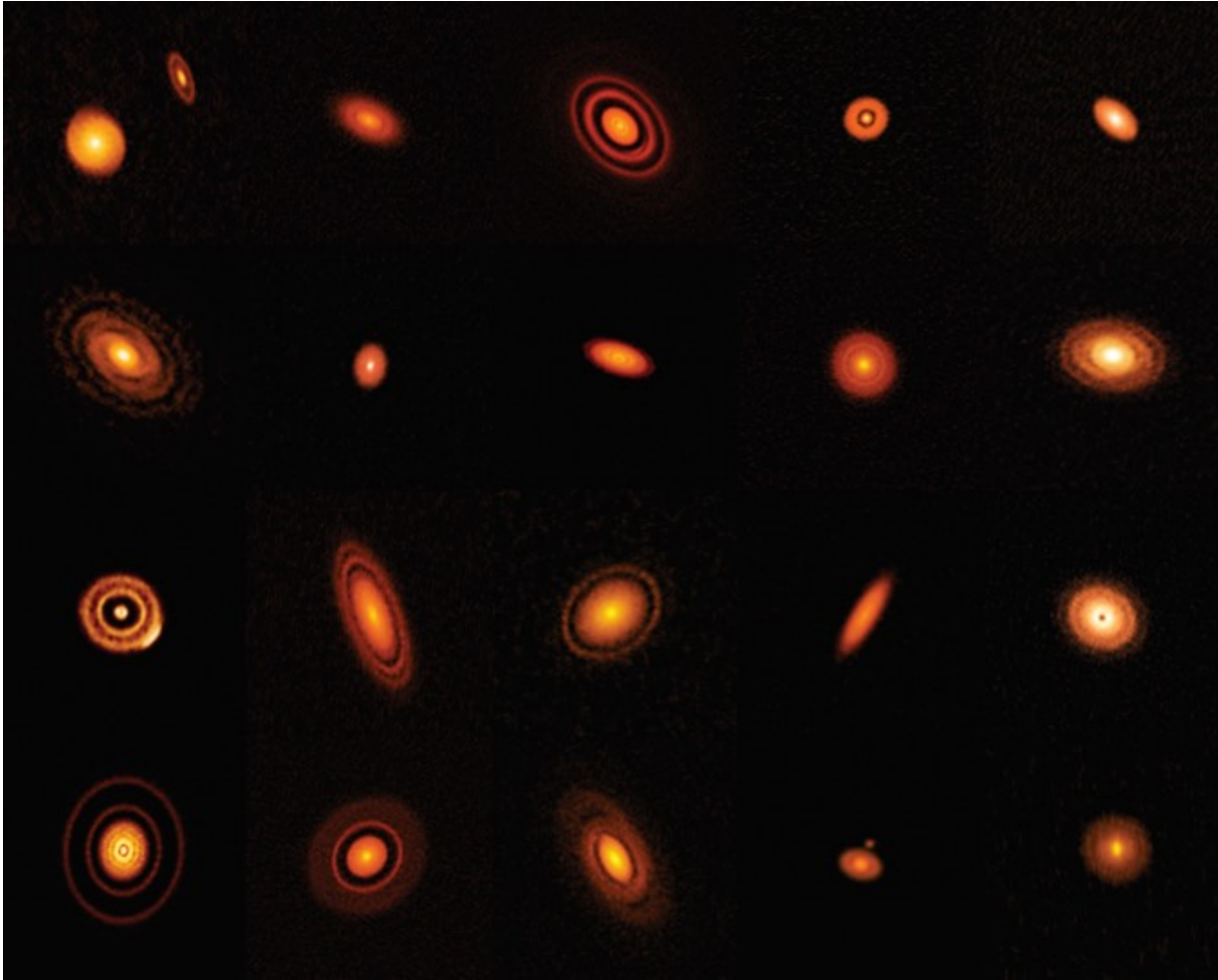
arXiv:1503.02649



Credit: ALMA (NRAO/ESO/NAOJ)

What can you observe?

A Protoplanetary Zoo!



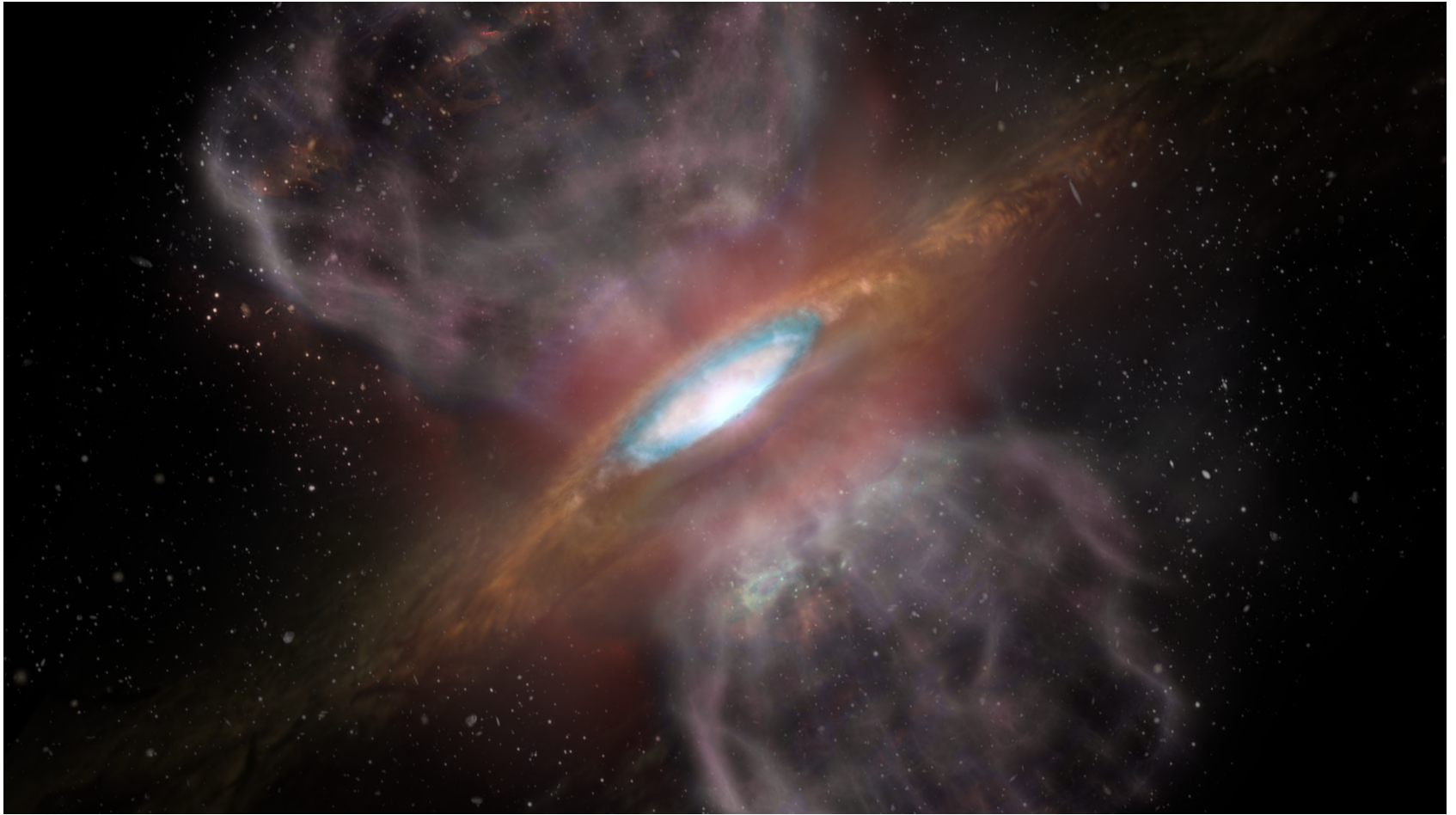
arXiv: 1812.04040



Credit: ALMA (NRAO/ESO/NAOJ)

What can you observe?

A Star sprinkled with salt!



arxiv: 1901.04489

Credit: NRAO/AUI/NSF; S. Dagnello

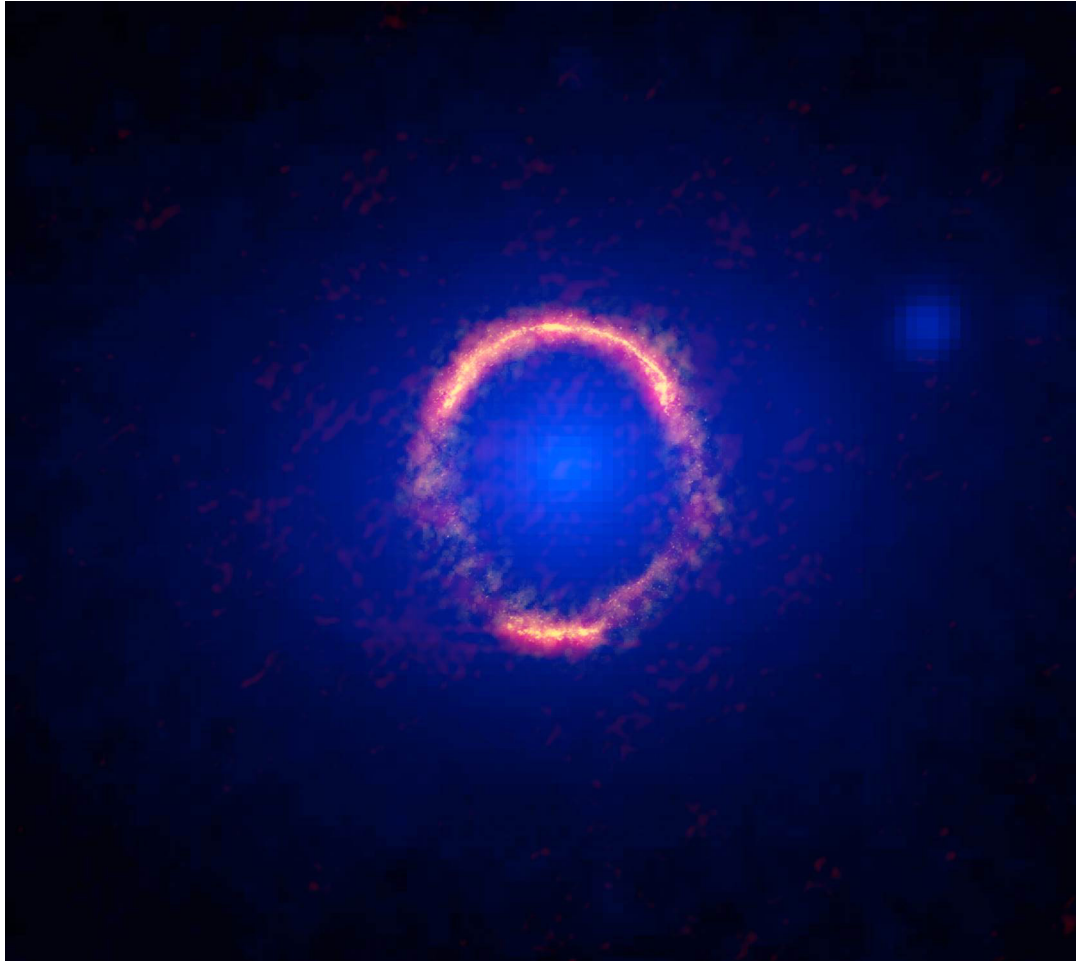
What can you observe?

We can observe a broad range of molecular lines



What can we observe?

Gravitational lensing of high-z galaxies



arXiv:1601.01388



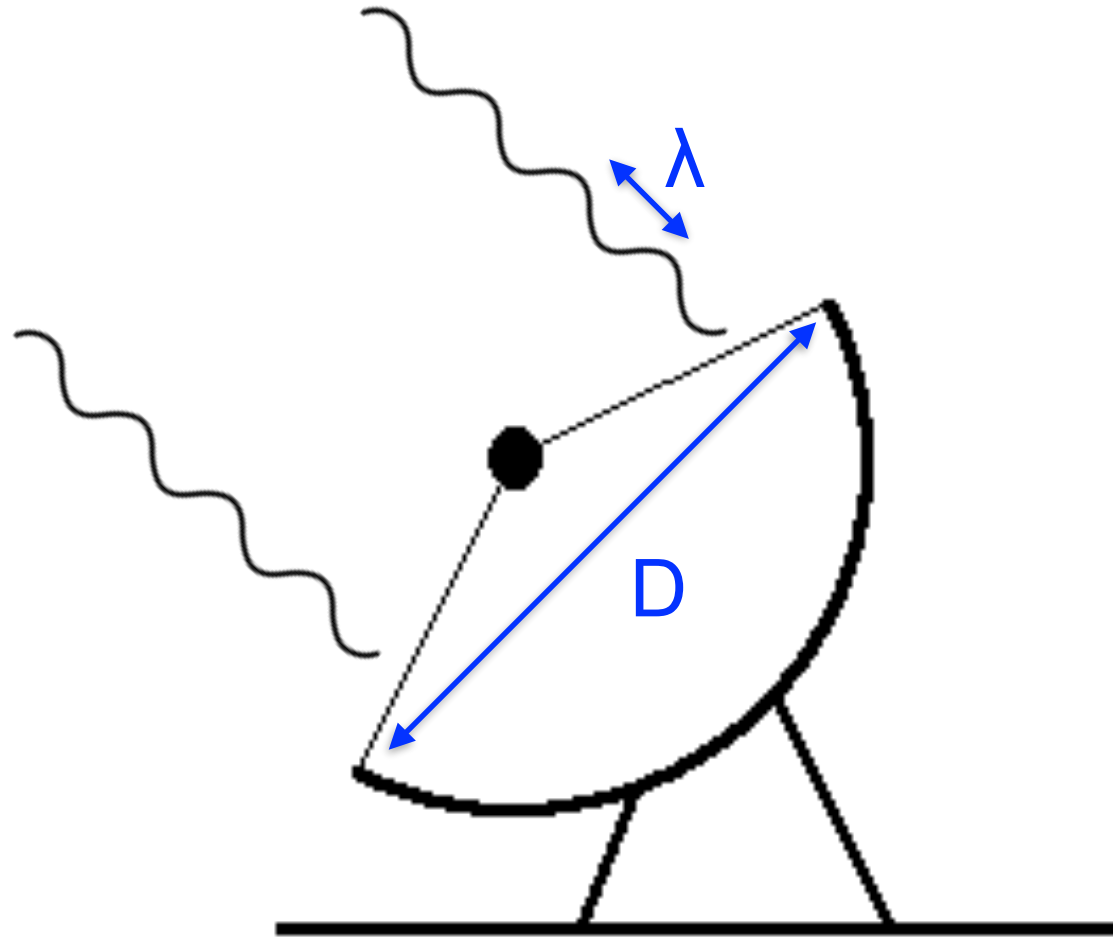
Diffraction theory

A single telescope has
a resolution of $\sim \lambda/D$

For the Hubble Space
Telescope:

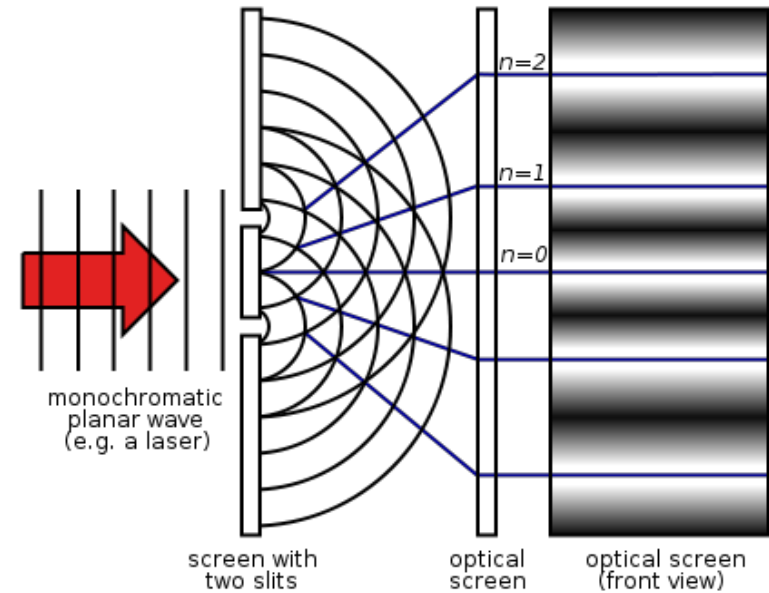
$$\lambda \sim 1\mu\text{m} / D \text{ of } 2.4\text{m} = \\ \text{resolution} \sim 0.13''$$

To reach that
resolution at $\lambda \sim 1\text{mm}$,
we would need a ~ 2
km-diameter dish!



What is an interferometer?

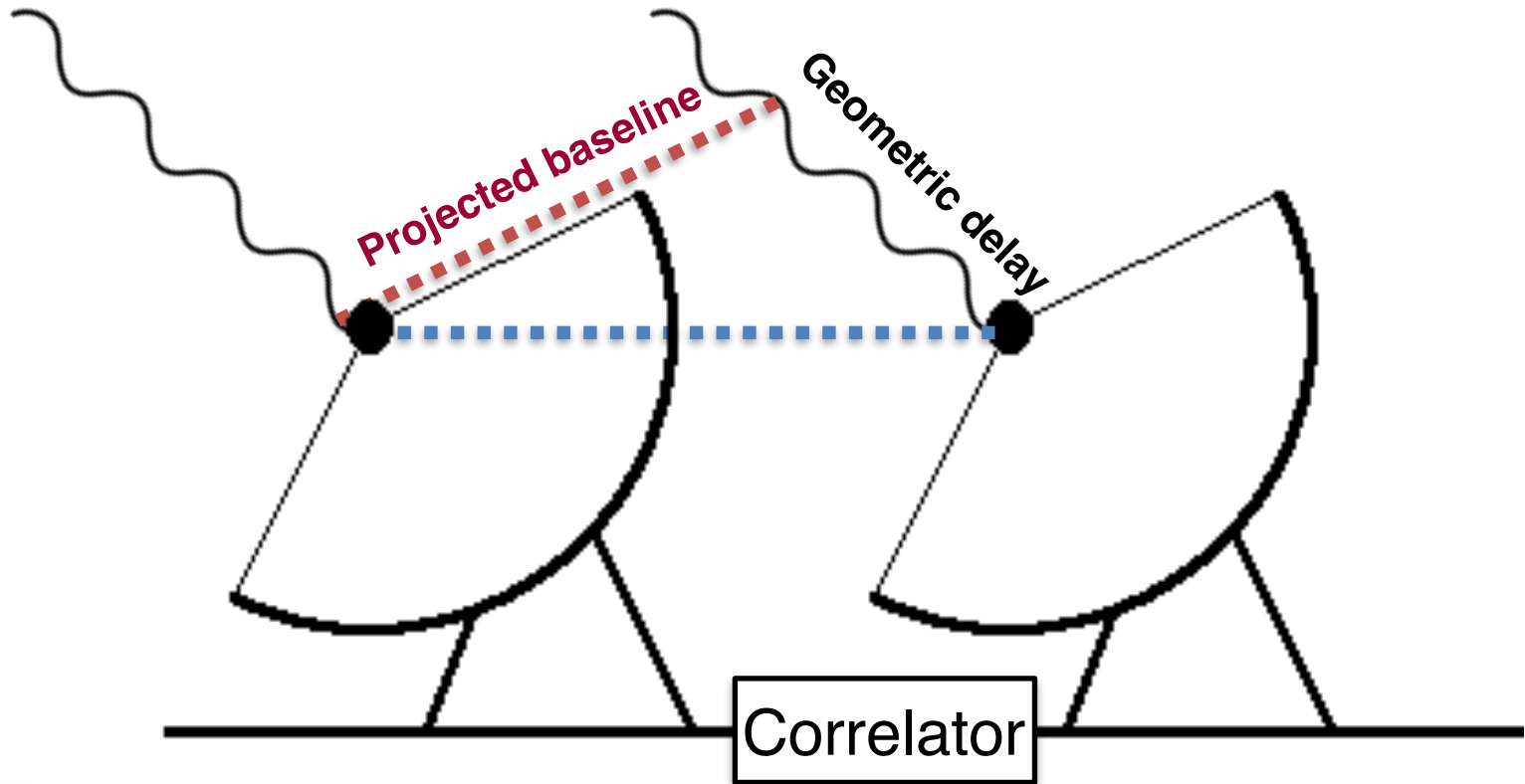
An *interferometer* measures the interference pattern produced by multiple apertures



So, let's add an aperture!

Projected baseline width plays the role of D in λ/D

Bigger baselines = better resolution!

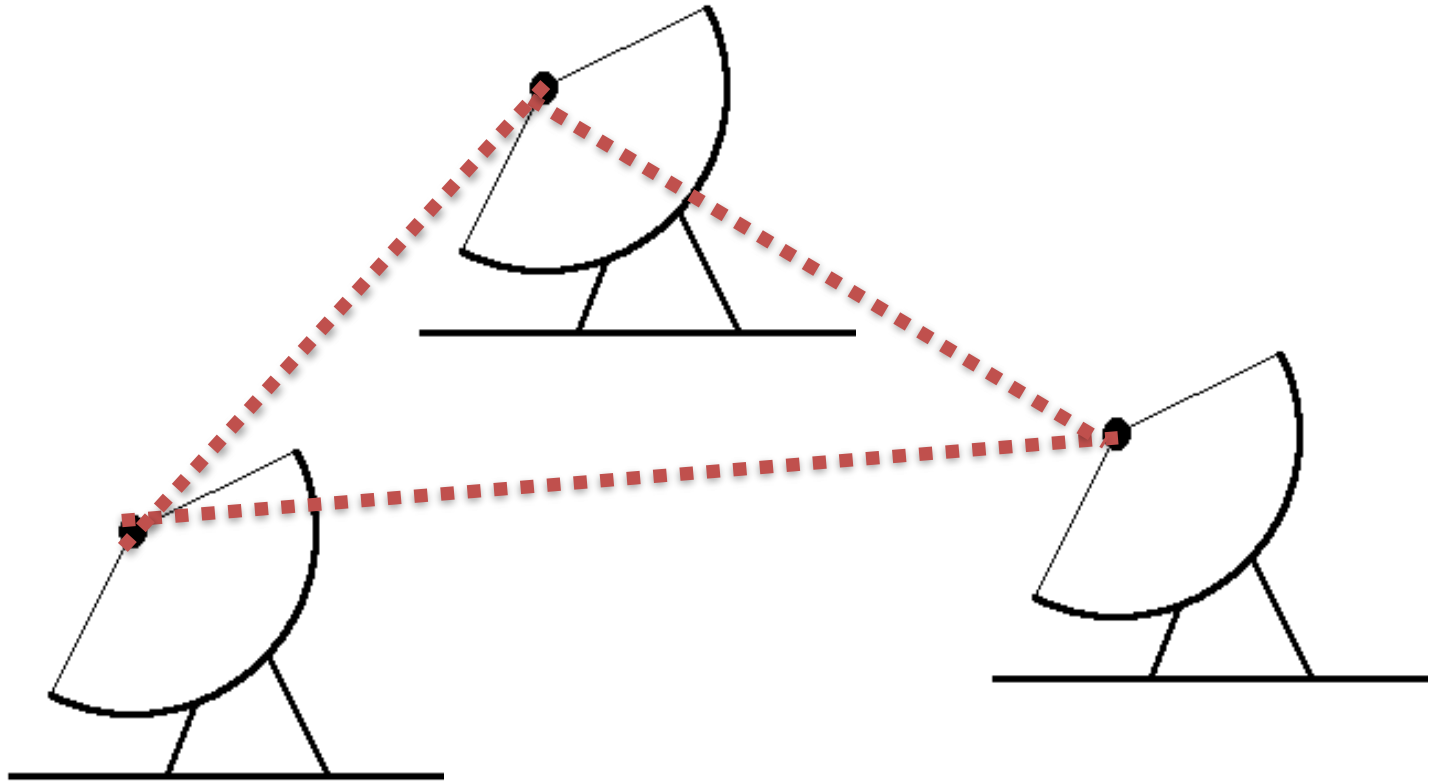


What happens with one more telescope?

One pair of antennas = one baseline

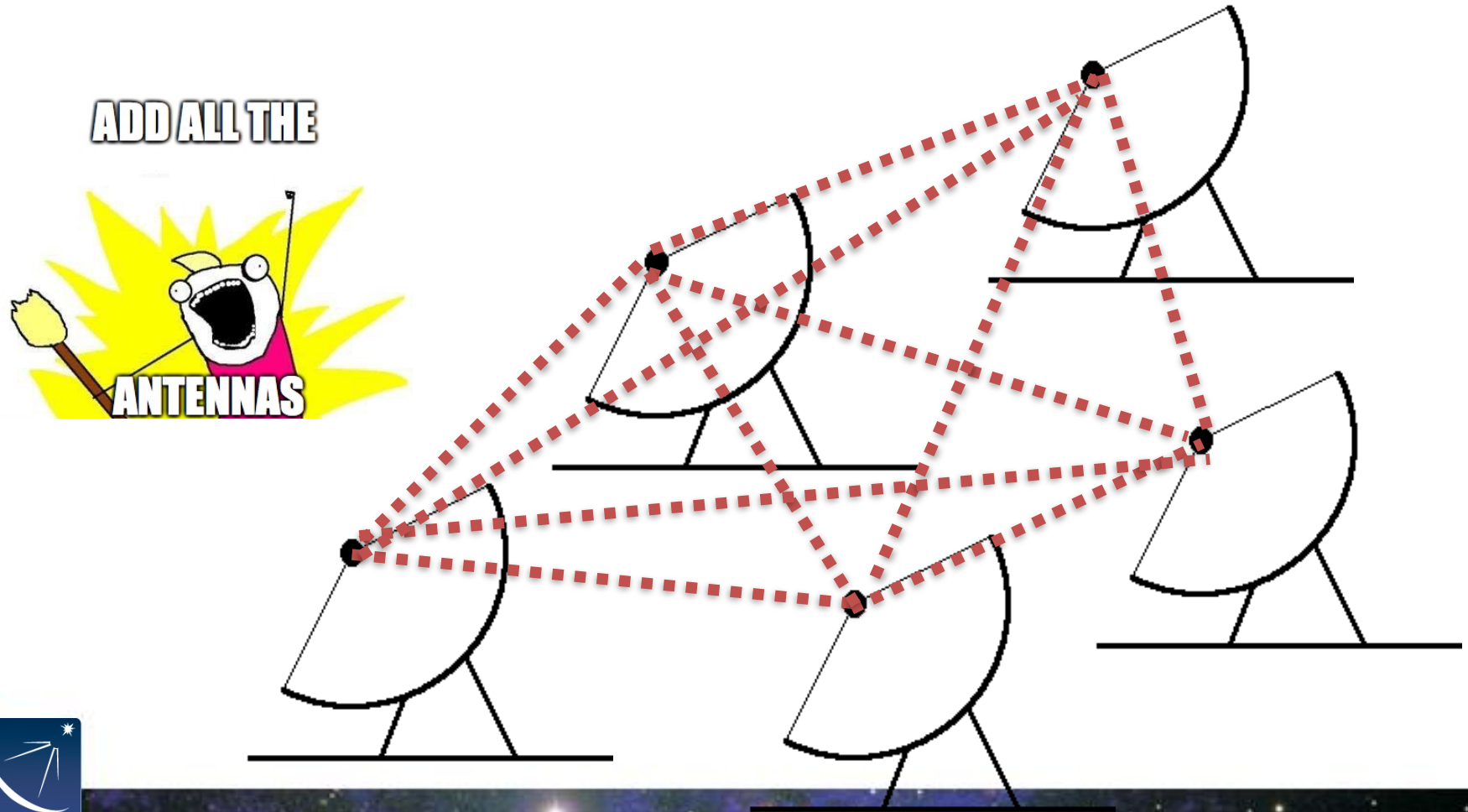
Each pair of antennas samples the source **twice**.

For **3 antennas**, we get **3 baselines**,
so we are sampling the source a total of **6 times**

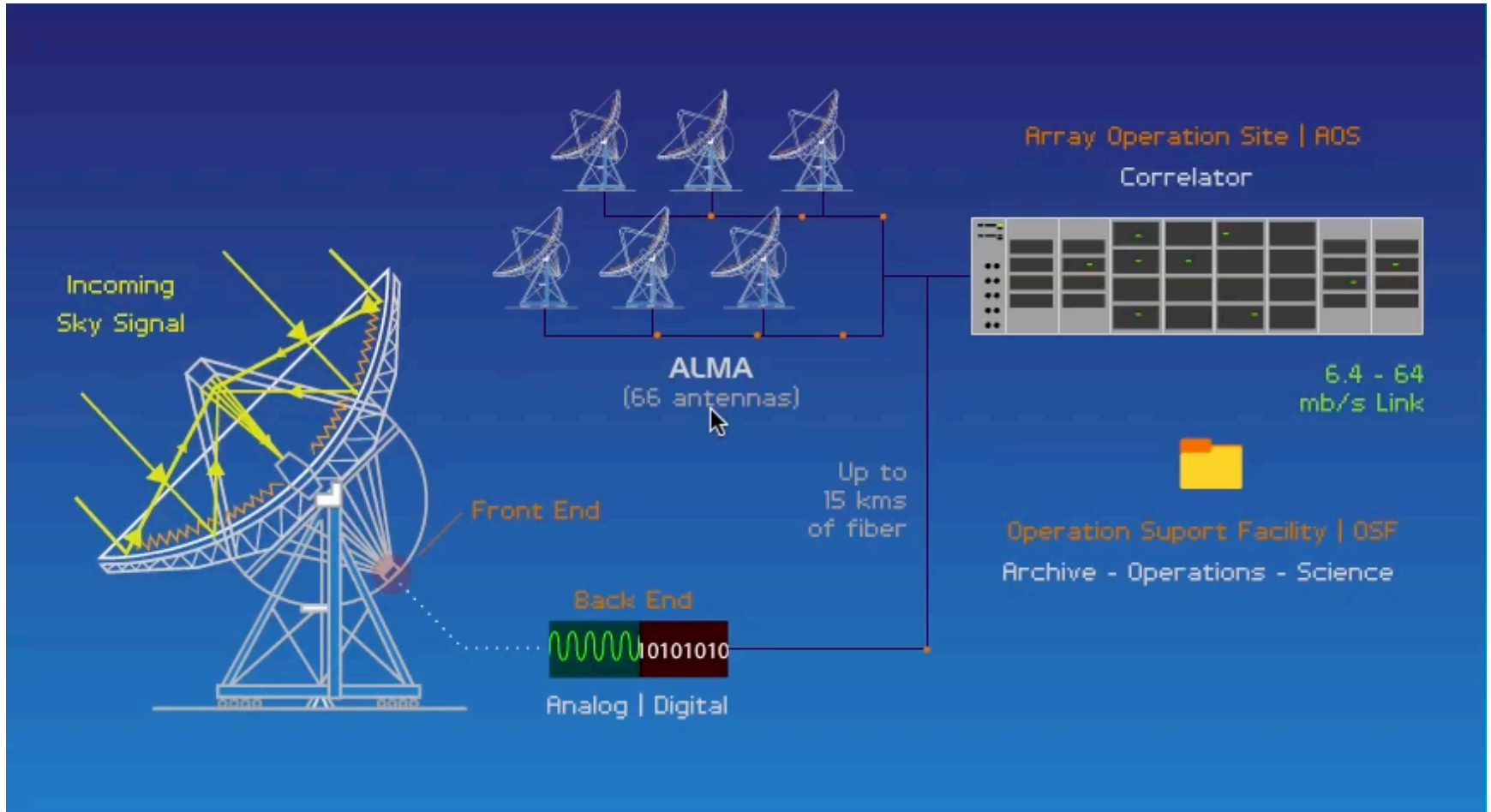


What happens with more telescopes?

For N antennas, we get $N(N-1)$ samples at a time, increasing our sensitivity

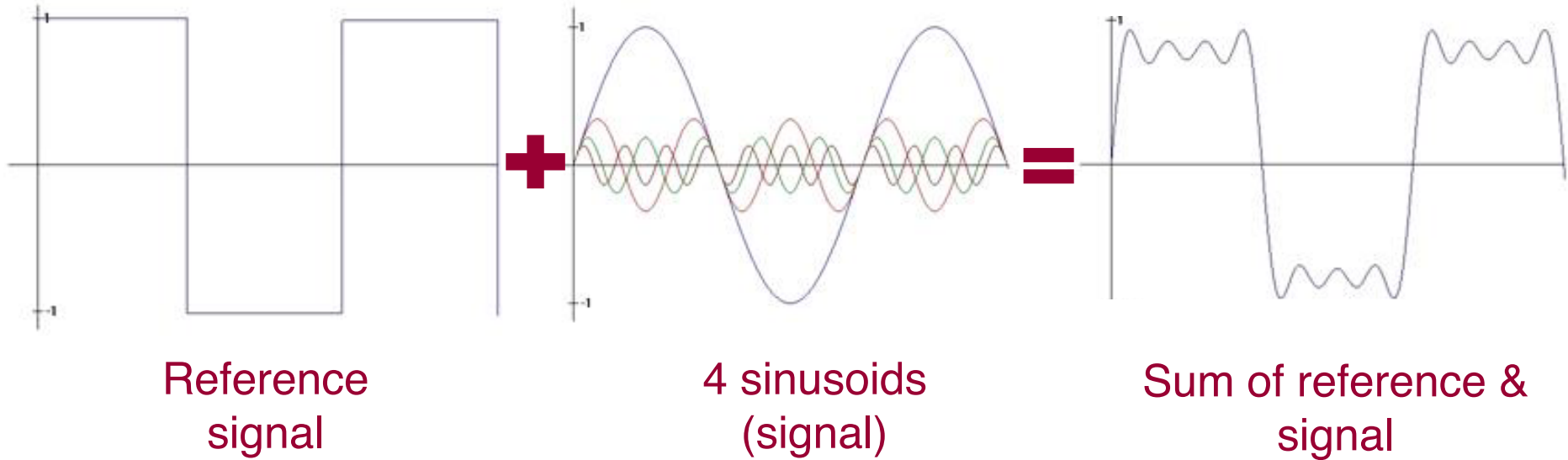


An Interferometer In Action



Introducing the Fourier Transform

Fourier theory states that any well behaved signal (including images) can be expressed as the sum of sinusoids **WITHOUT** loss of information



The Fourier Transform relates the measured interference pattern to the radio intensity on the sky

Fourier space/

$$\dot{V}(u, v) = \int \int T(x, y) e^{2\pi i(ux+vy)} dx dy$$

Image space/

$$\dot{T}(x, y) = \int \int V(u, v) e^{-2\pi i(ux+vy)} du dv$$

(for more info, see e.g.
Thompson, Moran & Swenson)

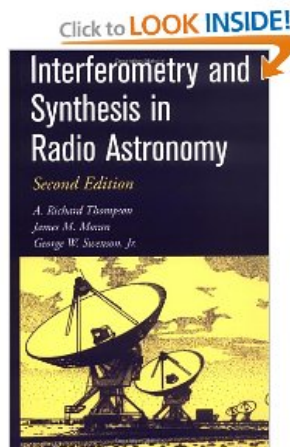
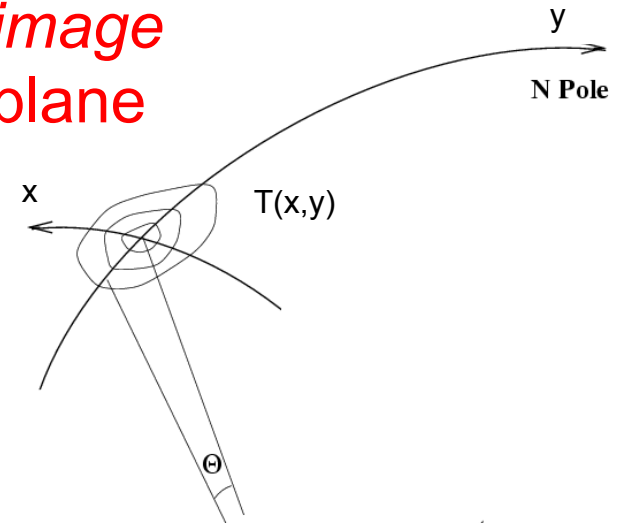
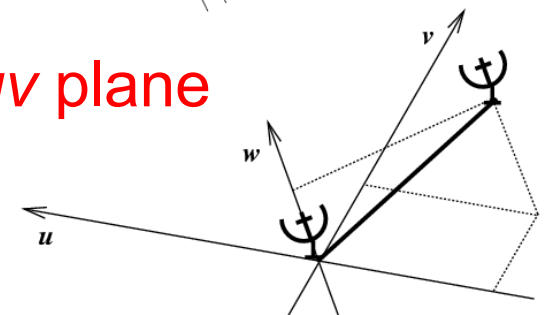


image plane



uv plane



What Are Visibilities?

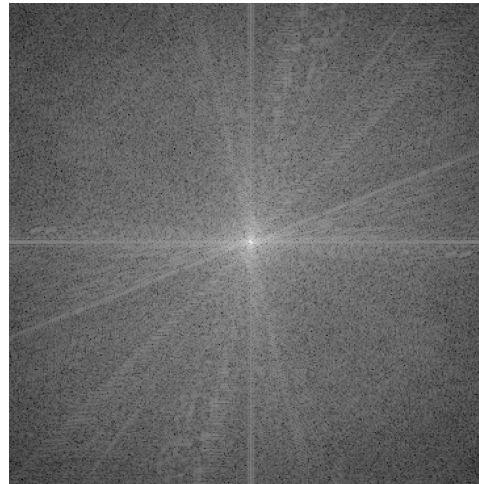
Each $V(u,v)$ contains information on $T(x,y)$ everywhere

Each $V(u,v)$ is a complex quantity

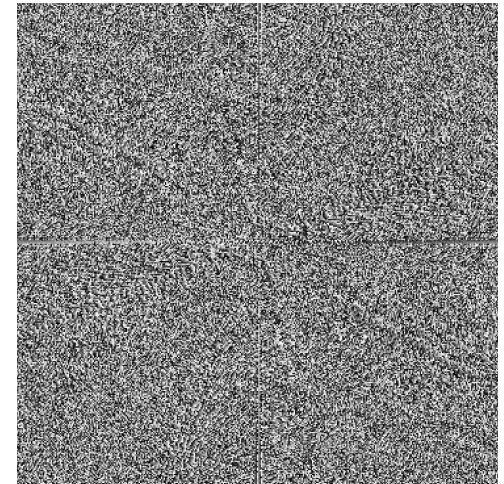


$T(x,y)$

FT
→



$V(u,v)$ amplitude



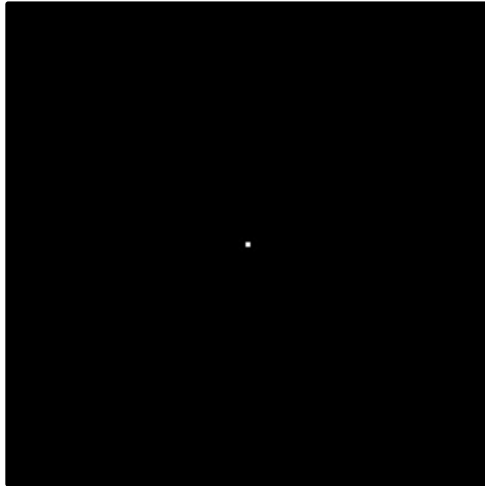
$V(u,v)$ phase

Examples of 2D Fourier Transforms

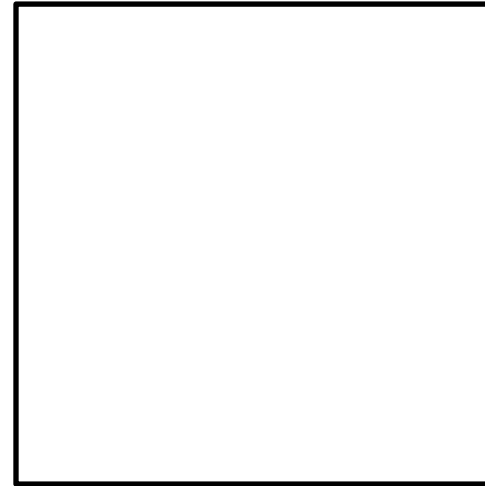
$T(x,y)$

$V(u,v)$ amplitude

δ Function



FT
→



Constant

Elliptical
Gaussian



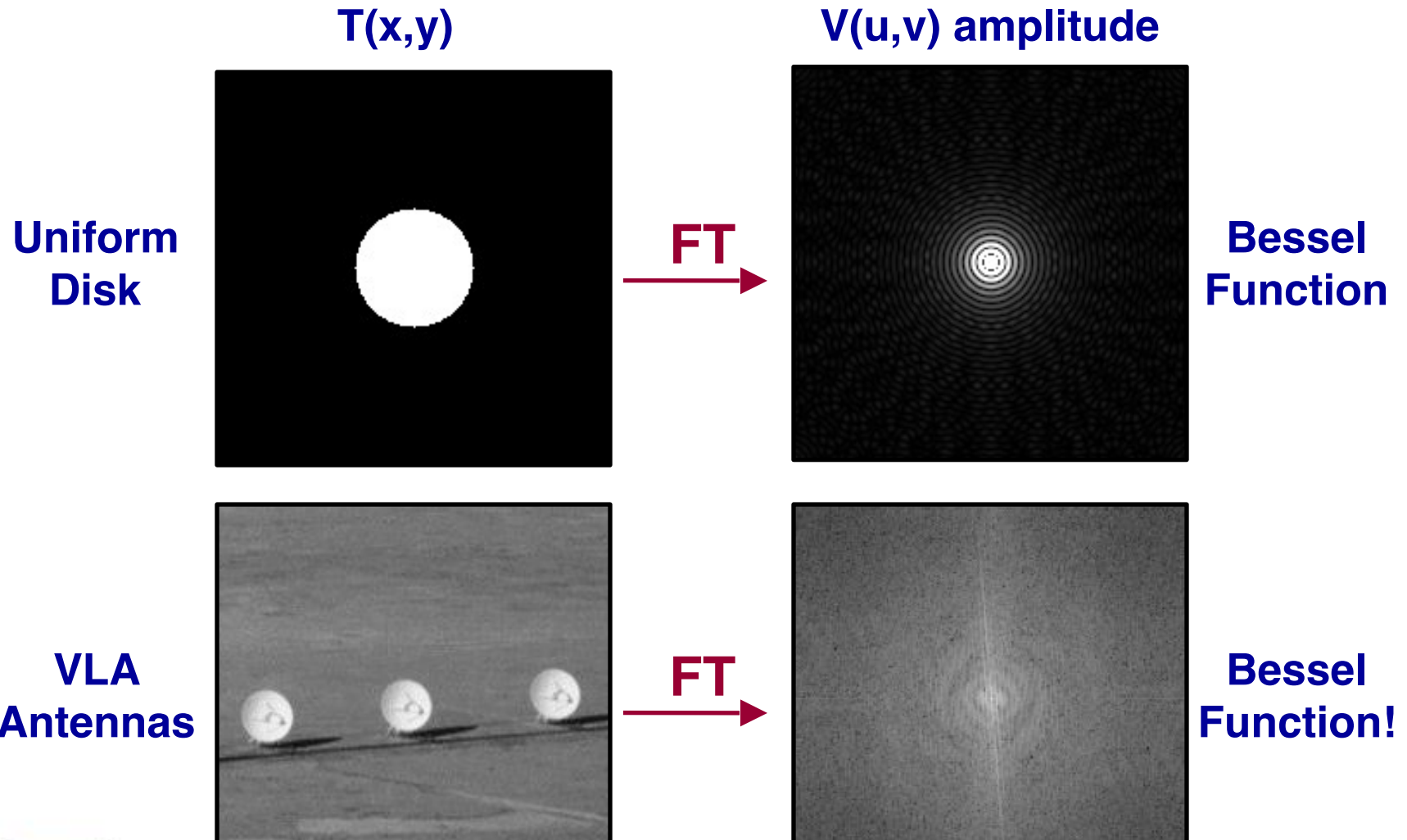
FT
→



Elliptical
Gaussian

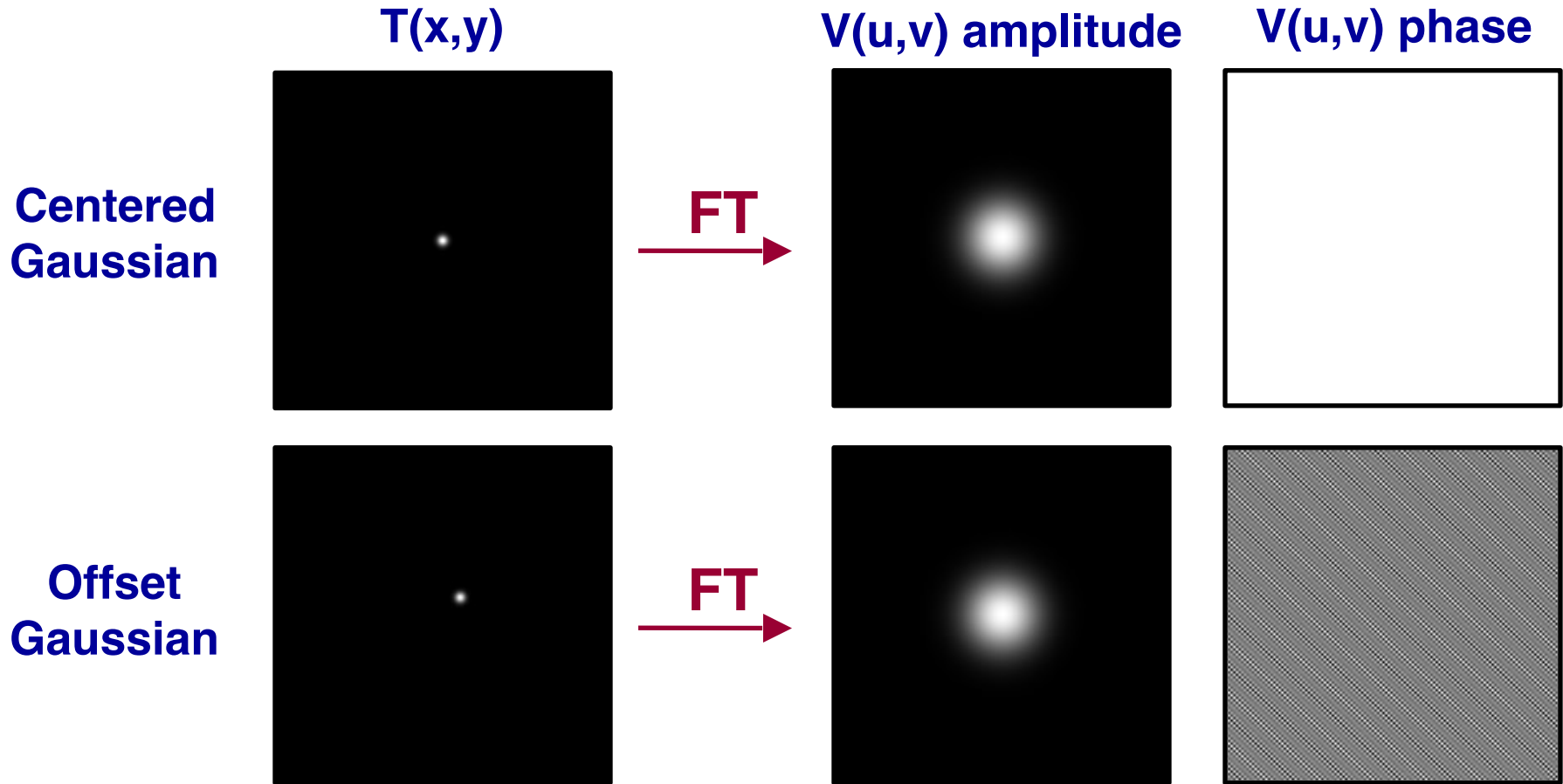
Rule of Thumb #1:
Narrow features \leftrightarrow Wide features

Examples of 2D Fourier Transforms



Rule of thumb #2:
Edges → high spatial features

Examples of 2D Fourier Transforms



Rule of thumb #3:
Amplitude = 'how much'
Phase = 'where'

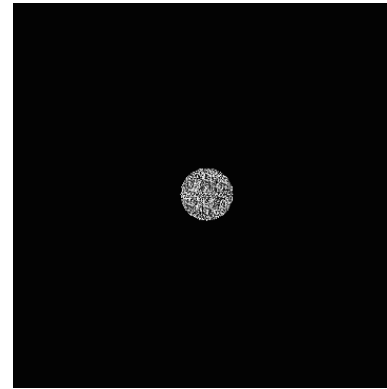
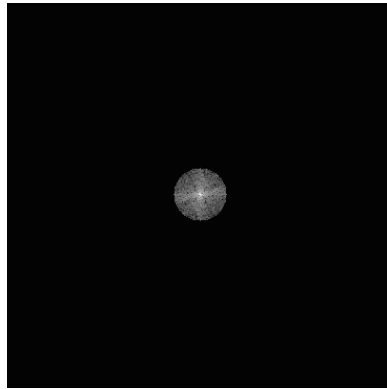
Implications of (u,v) Coverage

$V(u,v)$ amplitude

$V(u,v)$ phase

$T(x,y)$

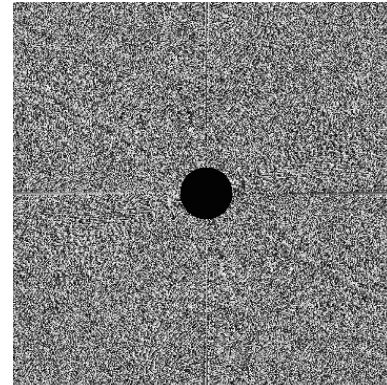
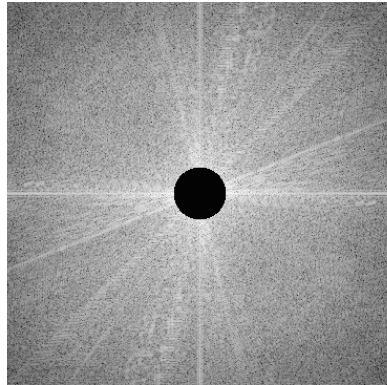
Missing High
Spatial
Frequencies



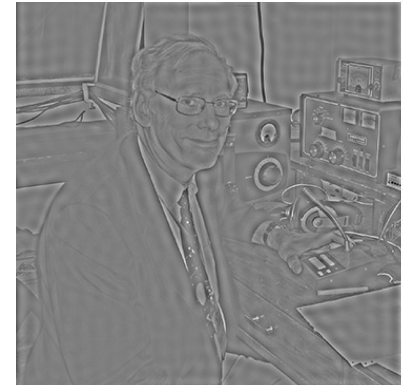
FT
→



Missing Low
Spatial
Frequencies



FT
→

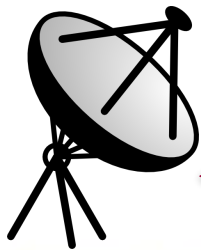


Basics of Aperture Synthesis

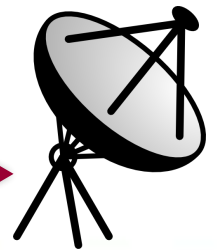
One pair of antennas = one baseline

For **N antennas**, we get **$N(N-1)$ samples** at a time

How do we fill in the rest of the (u,v) plane?



One baseline = 2 (u,v) points



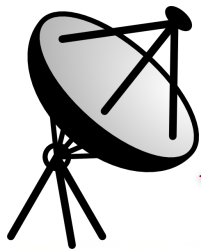
Basics of Aperture Synthesis

One pair of antennas = one baseline

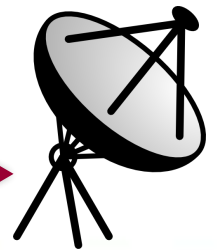
For **N antennas**, we get **$N(N-1)$ samples** at a time

How do we fill in the rest of the (u,v) plane?

1. Rearrange the antennas



One baseline = 2 (u,v) points



Basics of Aperture Synthesis

One pair of antennas = one baseline

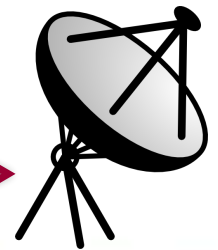
For **N antennas**, we get **$N(N-1)$ samples** at a time

How do we fill in the rest of the (u,v) plane?

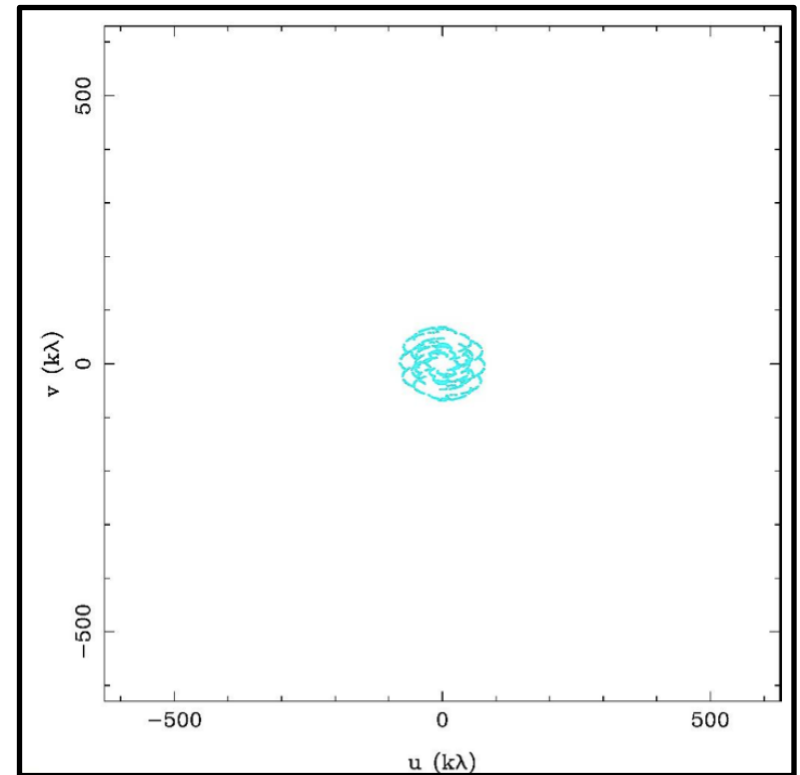
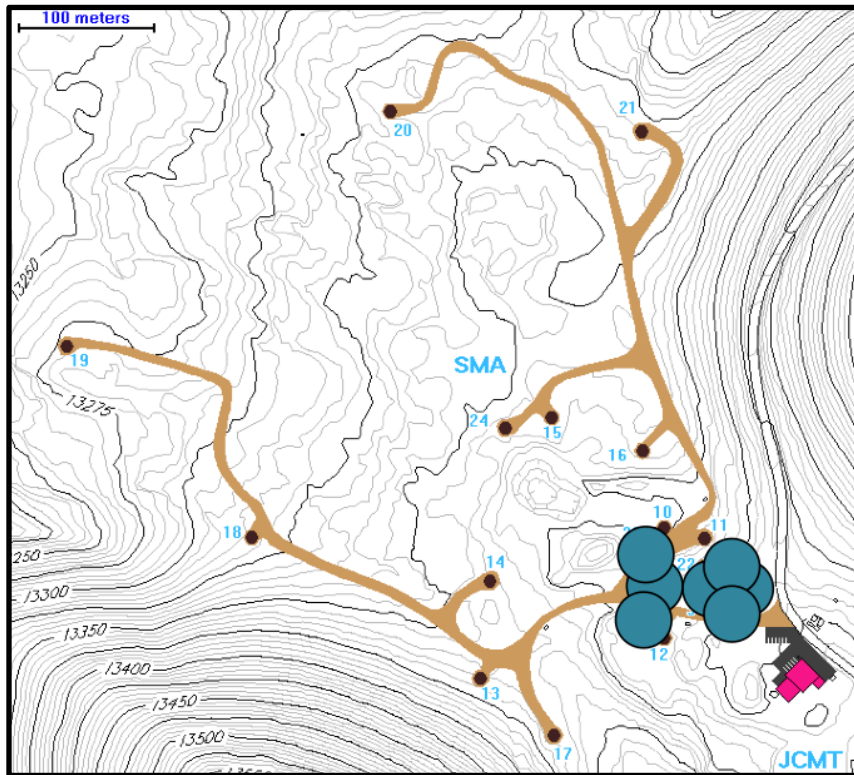
1. Rearrange antennas
2. Earth's rotation



One baseline = 2 (u,v) points

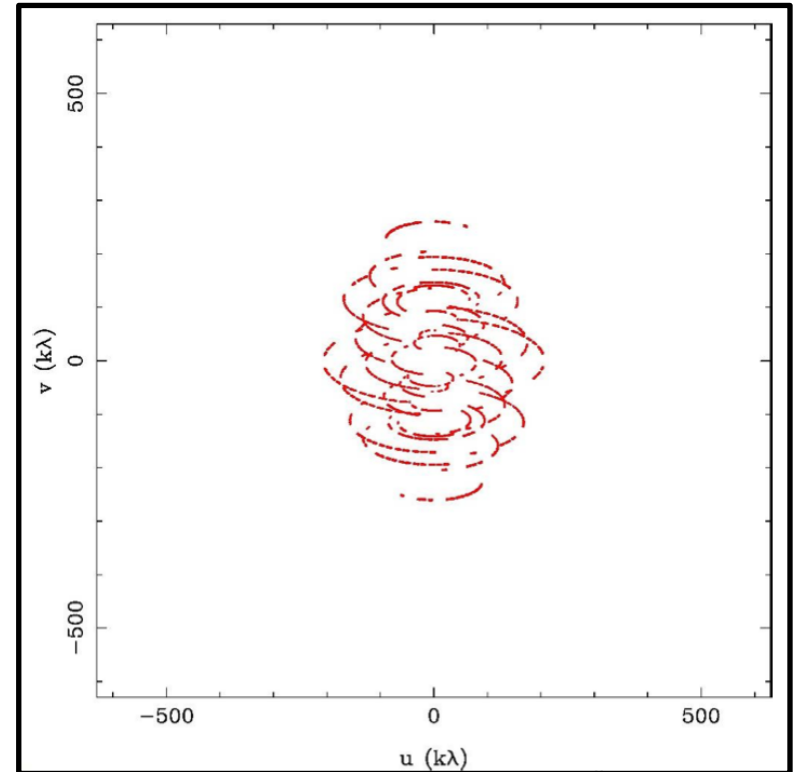
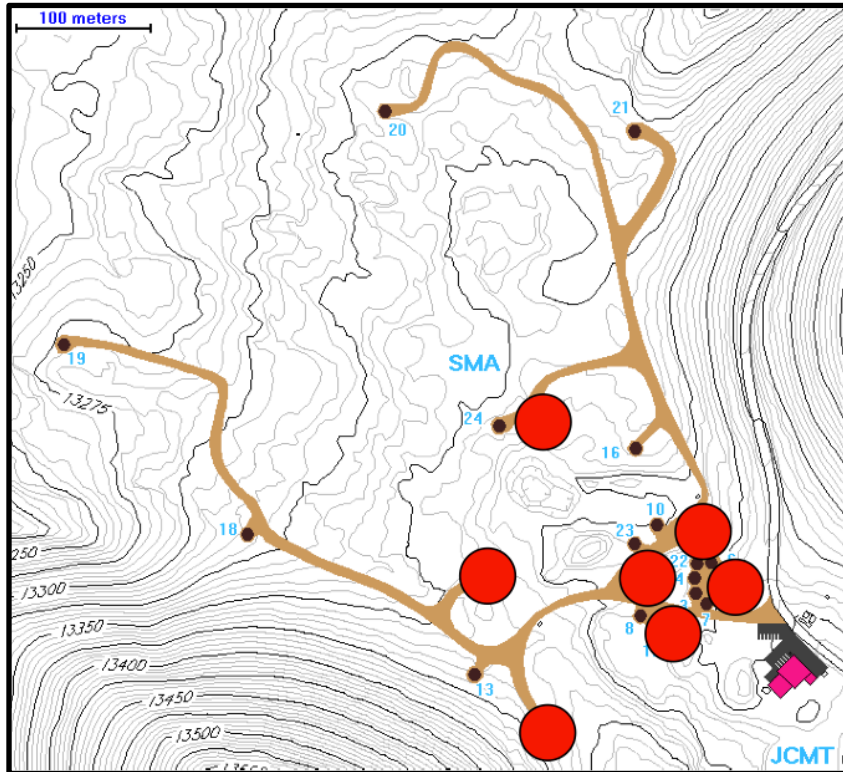


Method 1: Reconfigure your antennas



Compact SMA configuration
(compact baselines)
345 GHz, DEC = +22

Method 1: Reconfigure your antennas

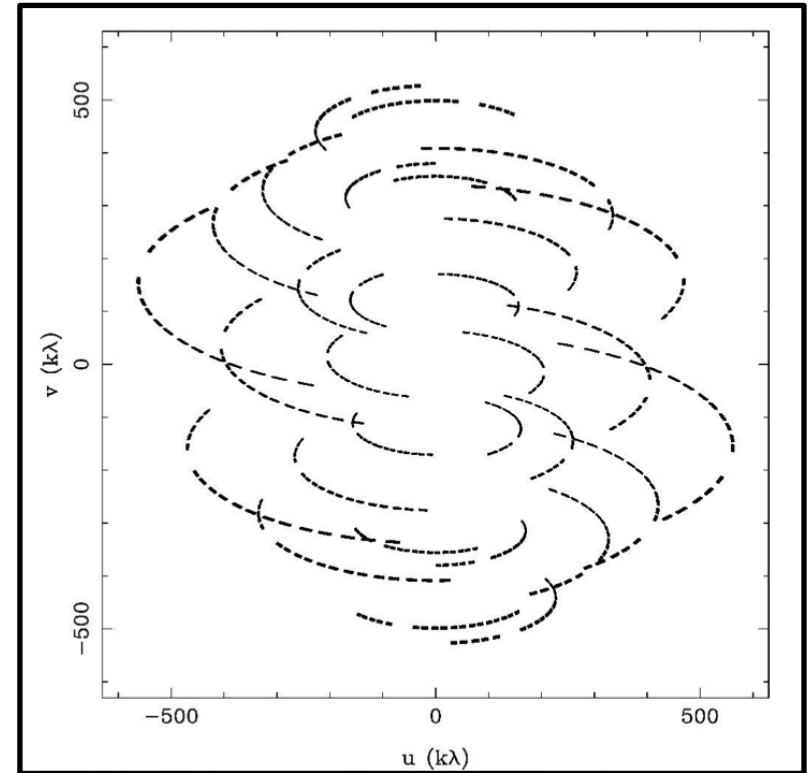
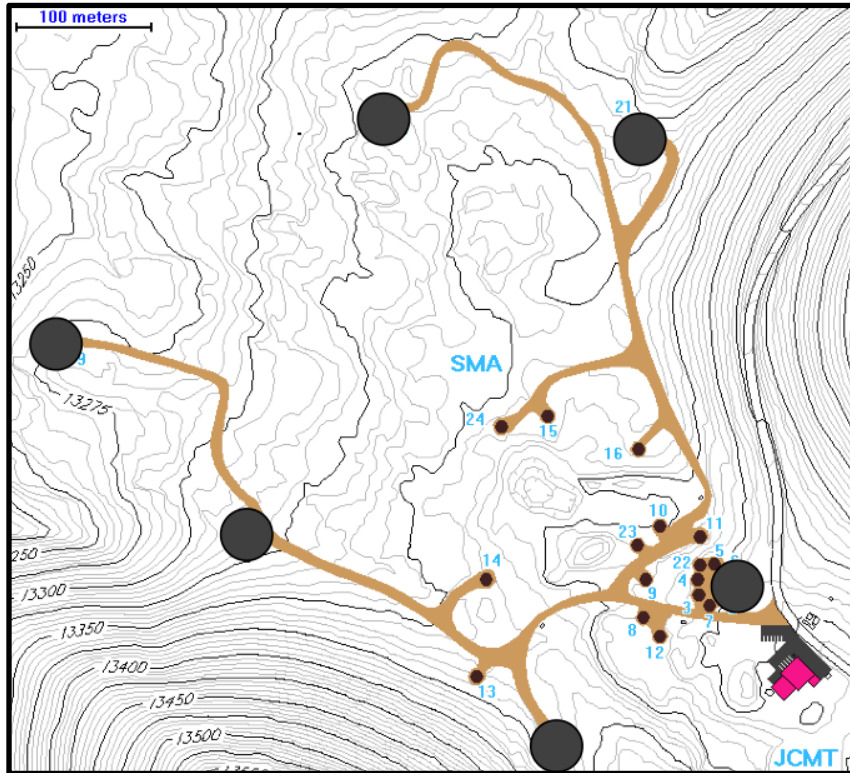


Extended SMA configuration

(extended baselines)

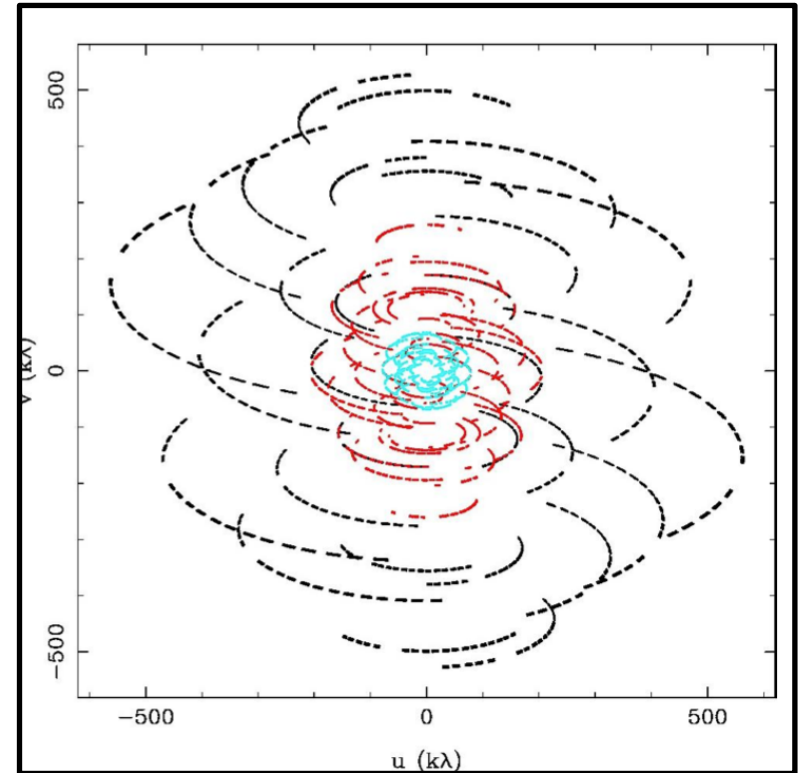
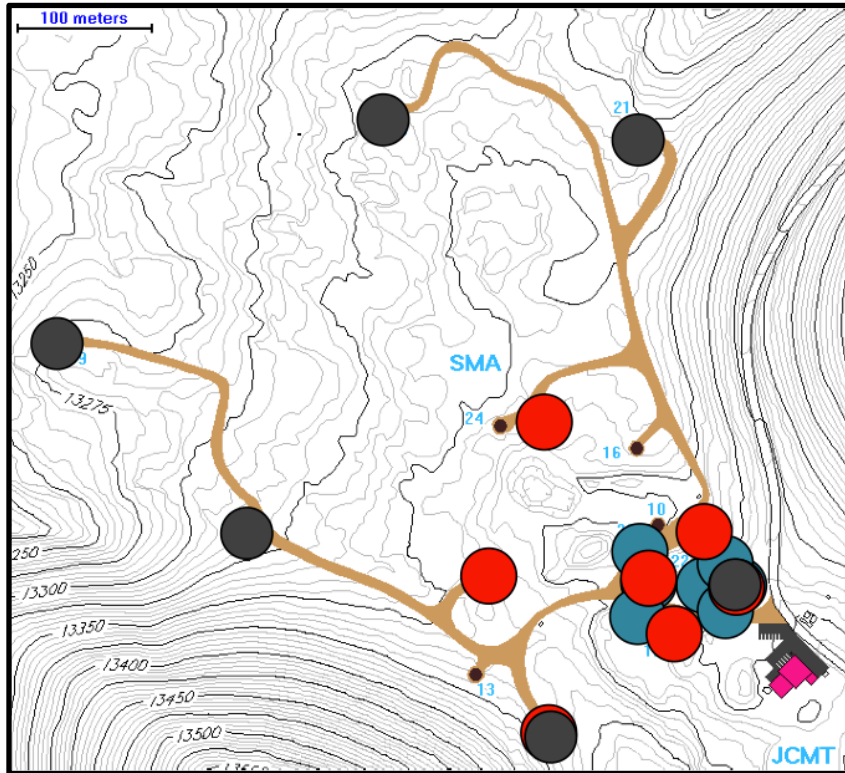
345 GHz, DEC = +22

Method 1: Reconfigure your antennas



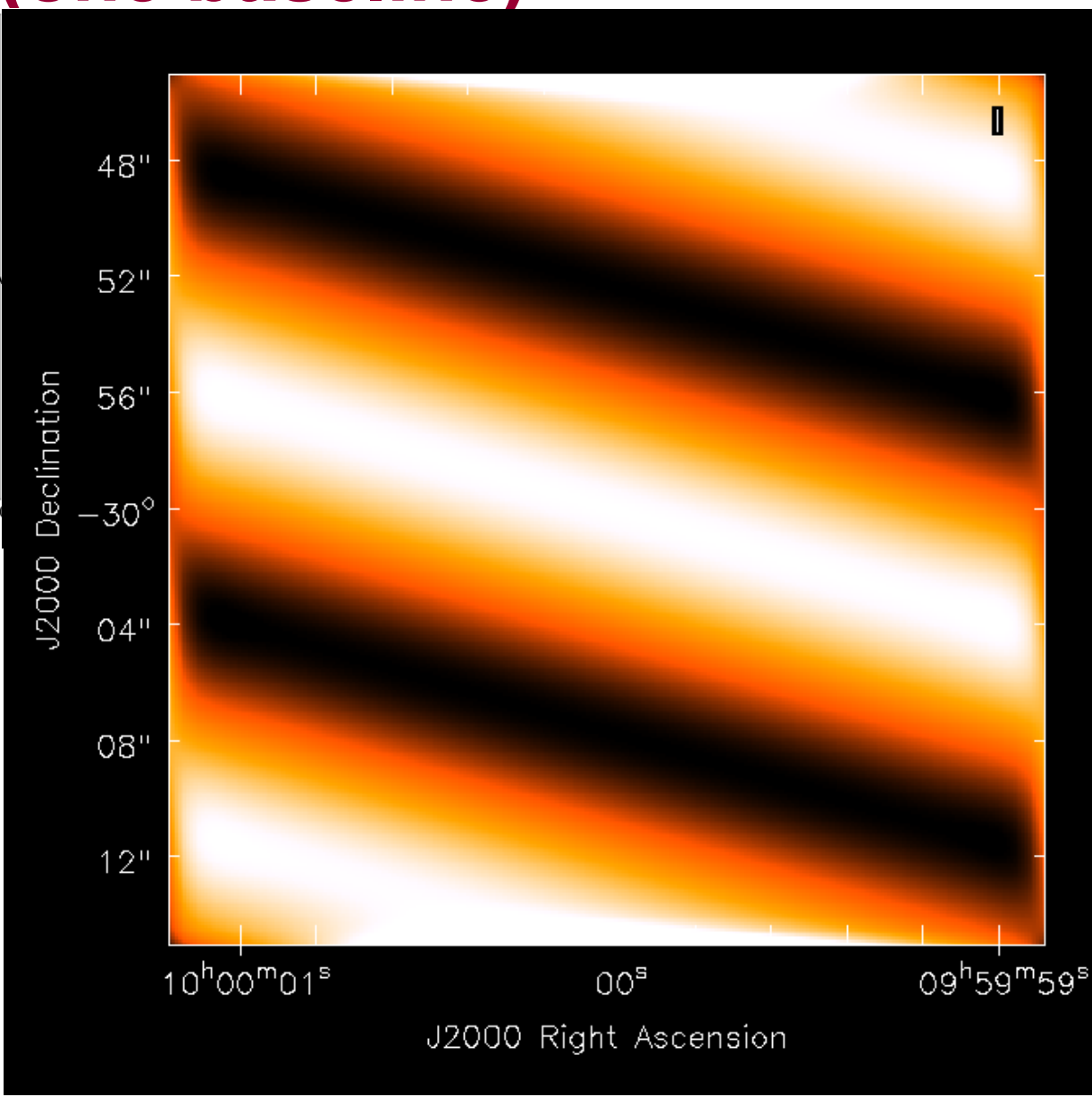
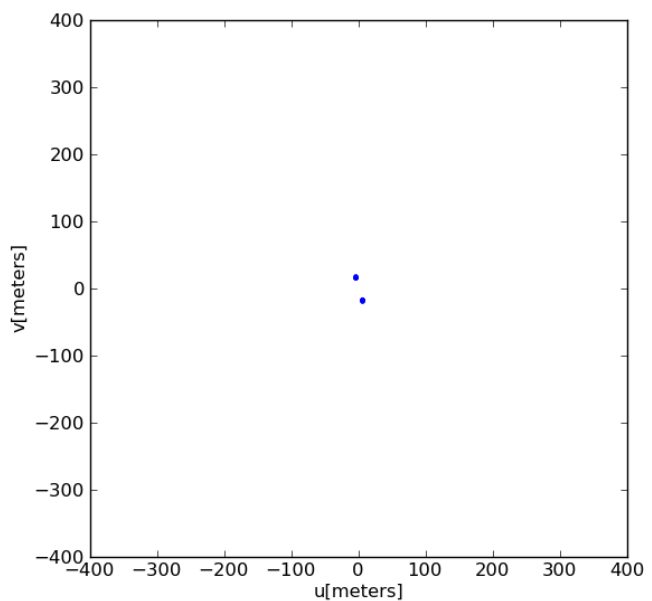
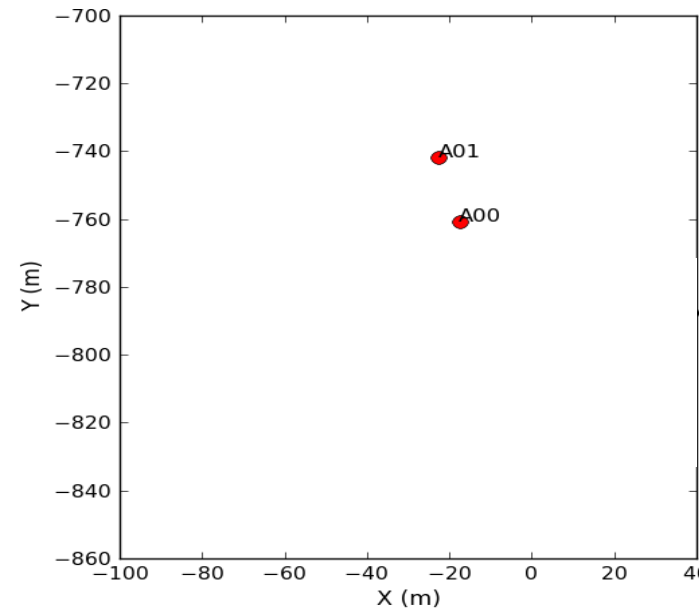
Very Extended SMA configuration
(most extended baselines)
345 GHz, DEC = +22

Method 1: Reconfigure your antennas

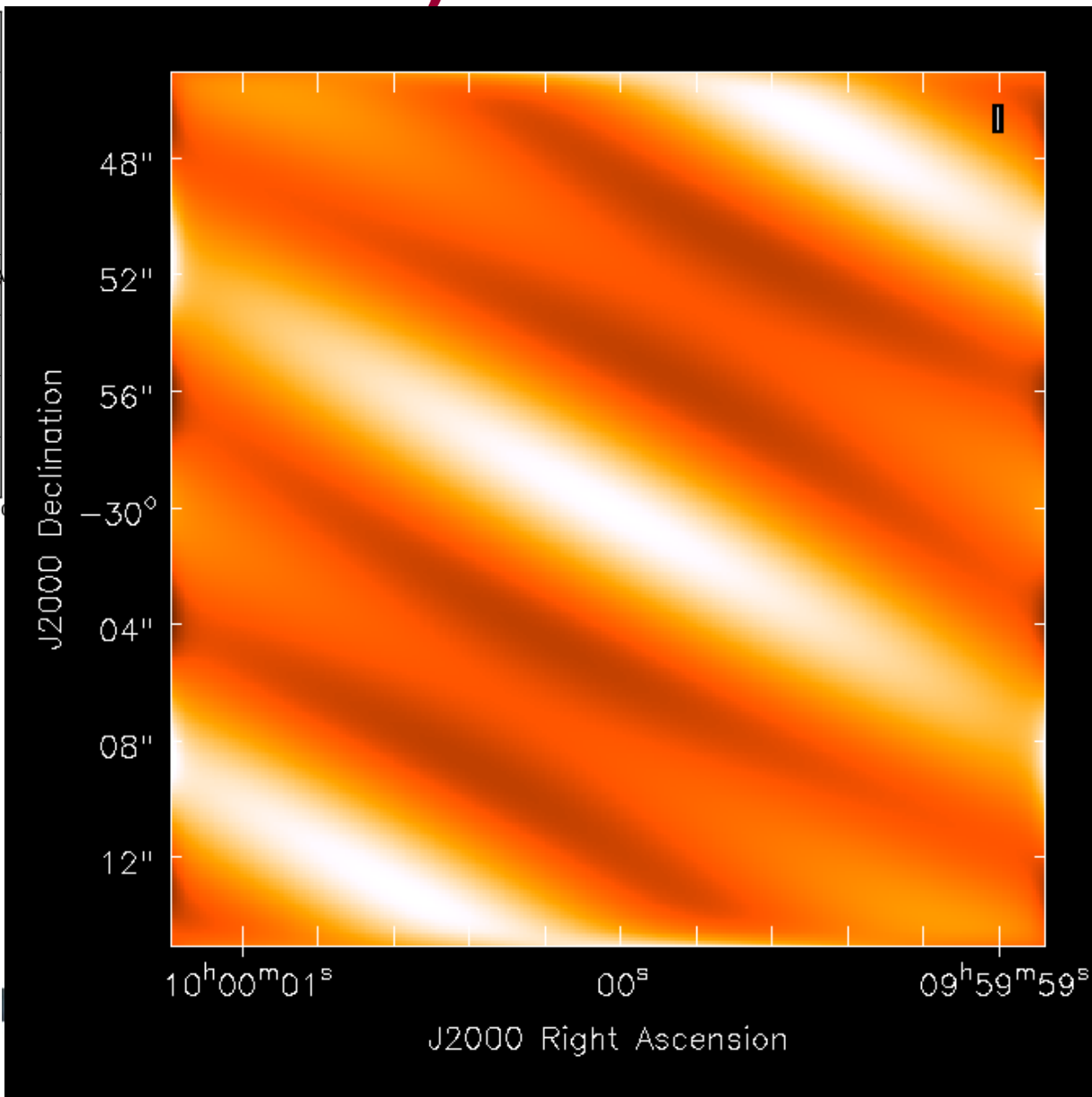
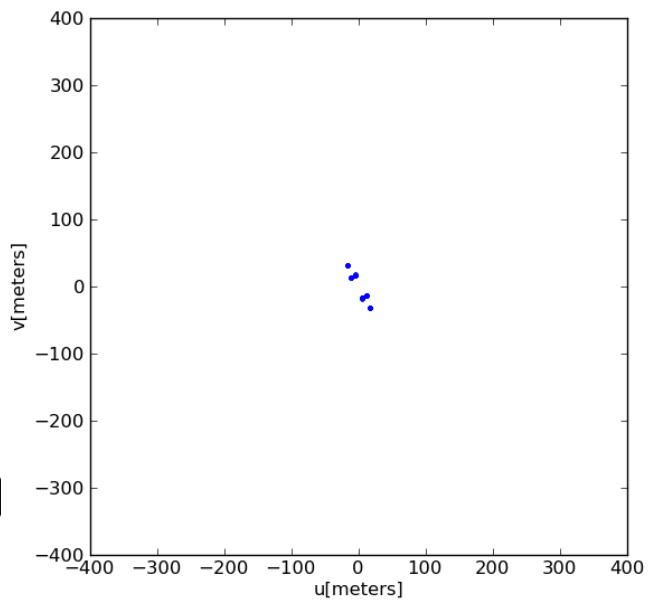
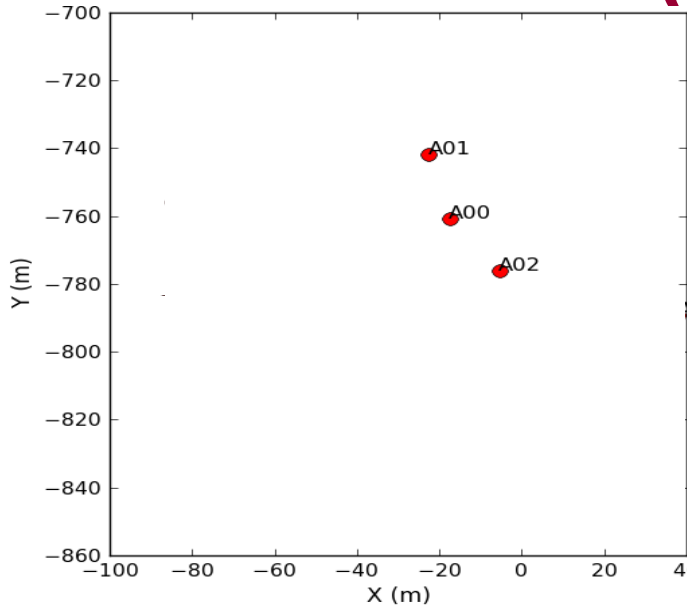


Combine multiple configurations to get the most complete coverage of the (u, v) plane

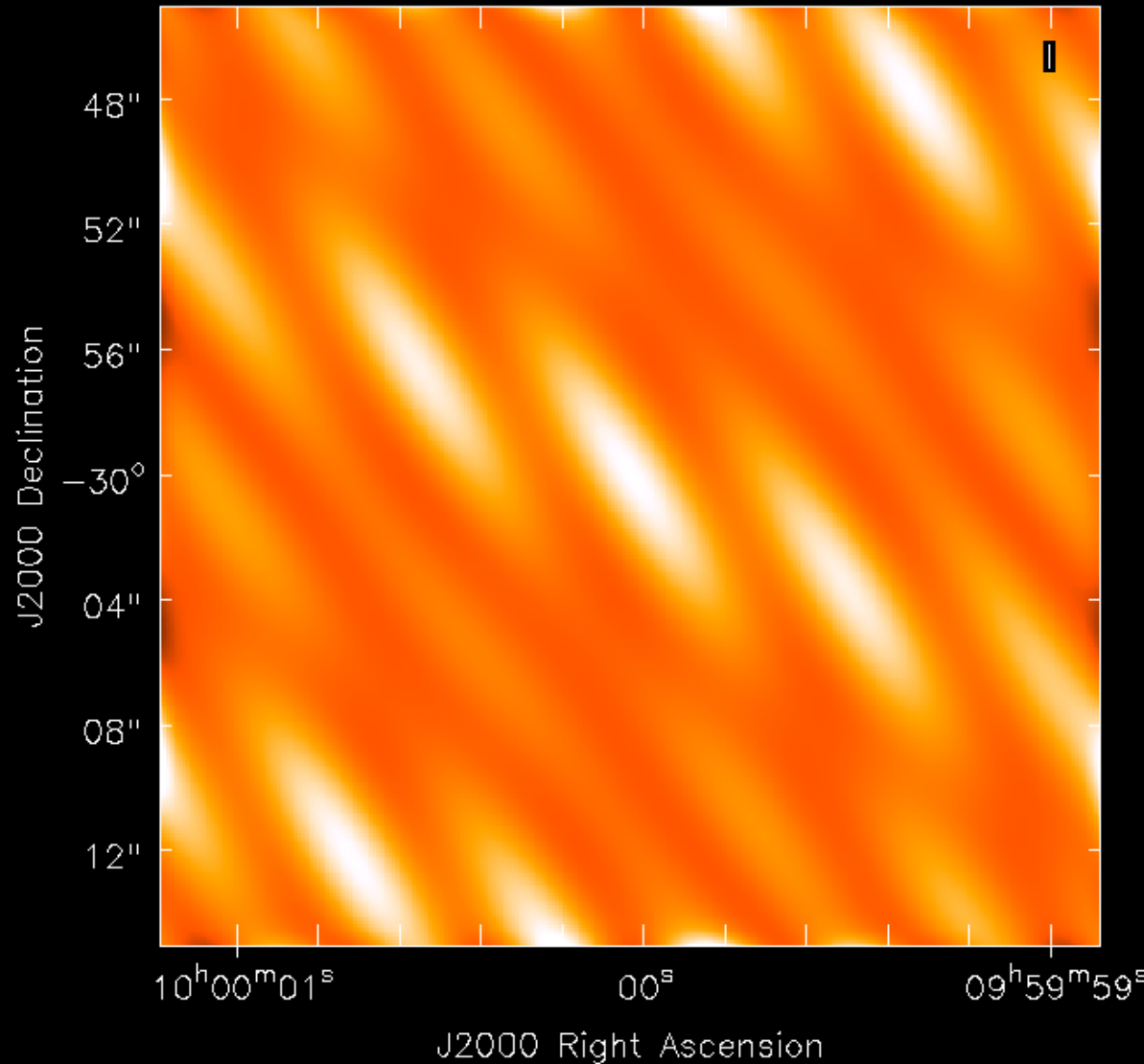
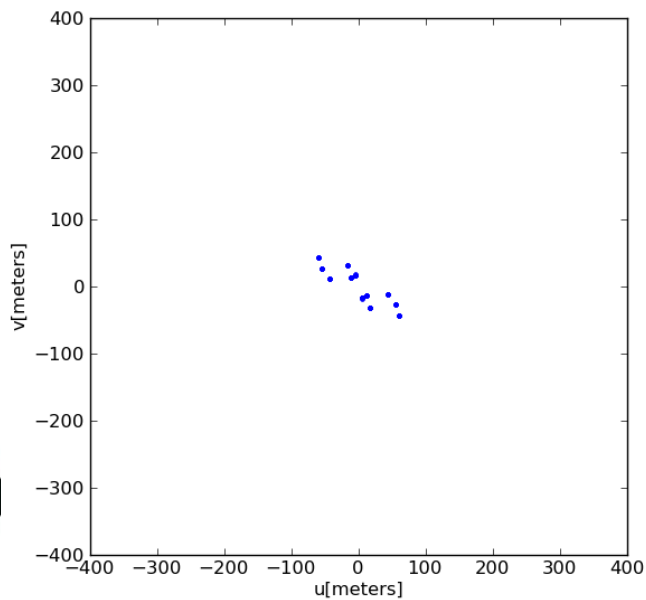
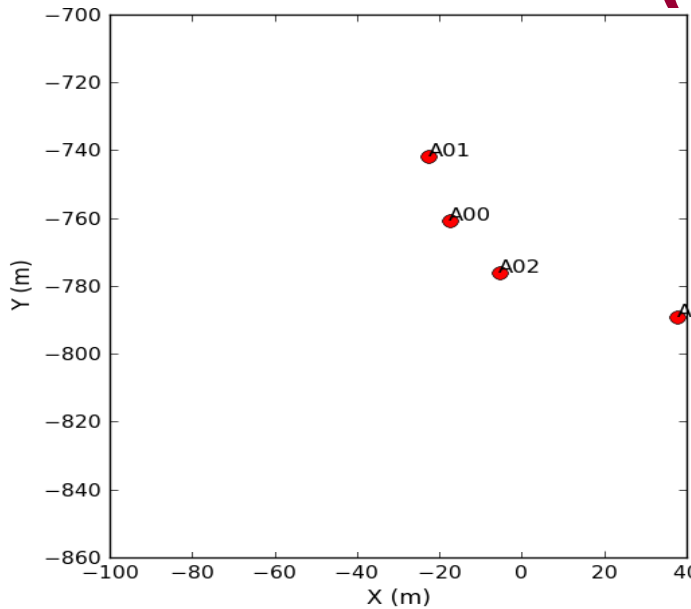
Example: Fringe pattern with 2 Antennas (one baseline)



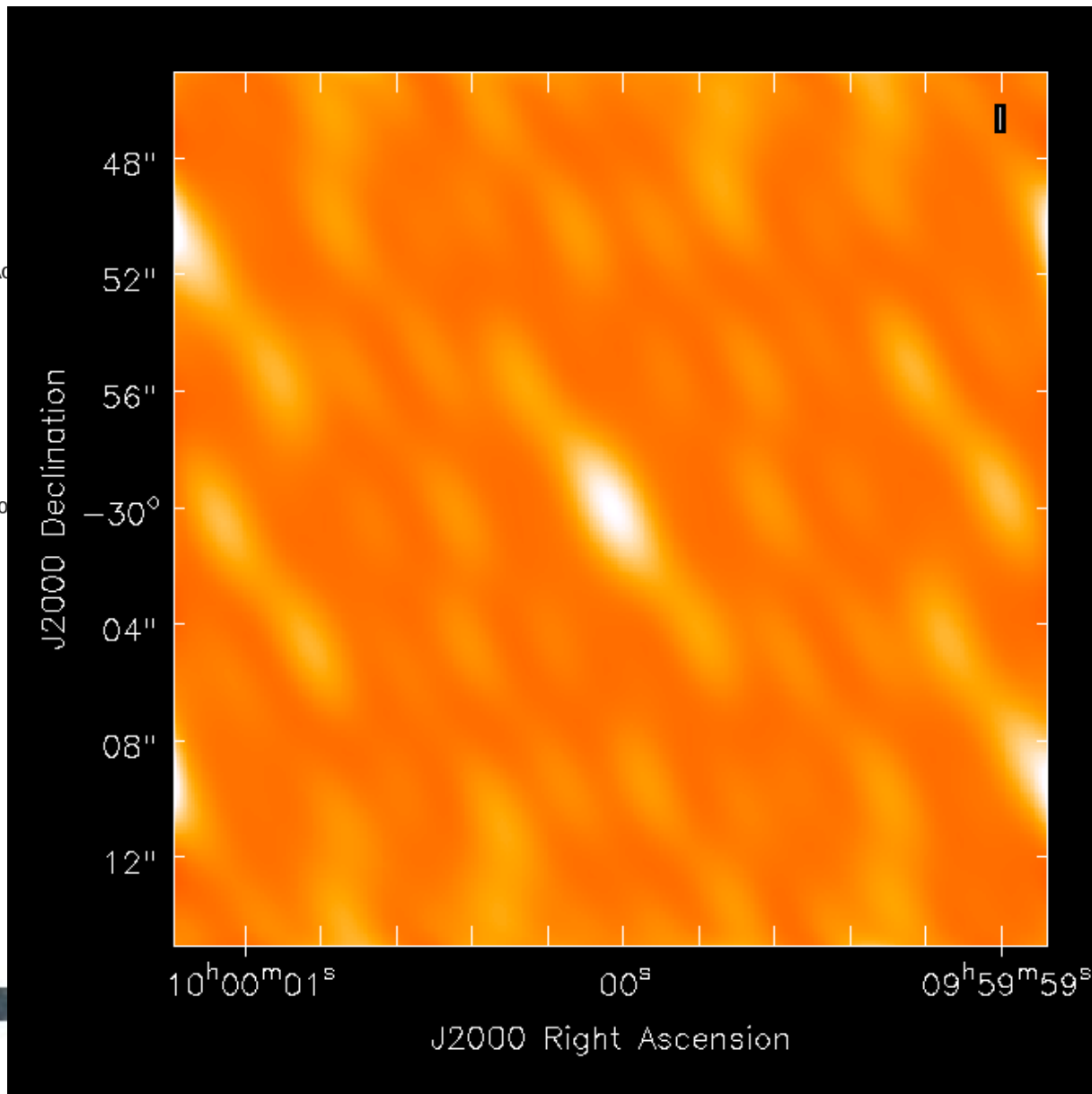
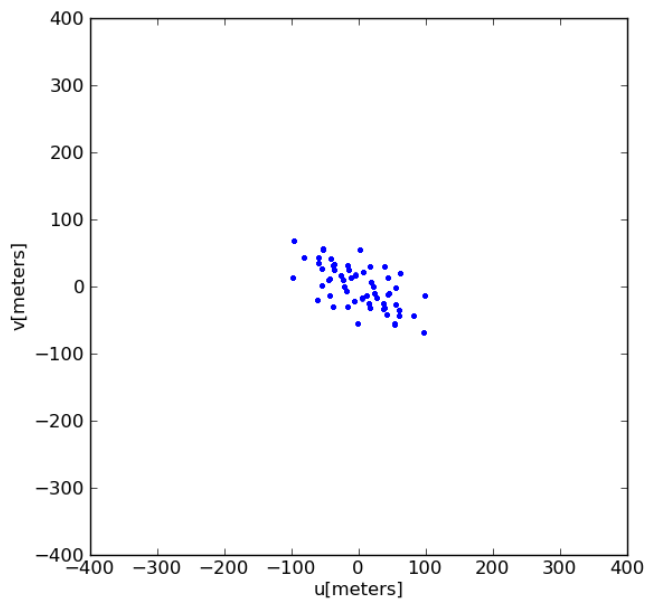
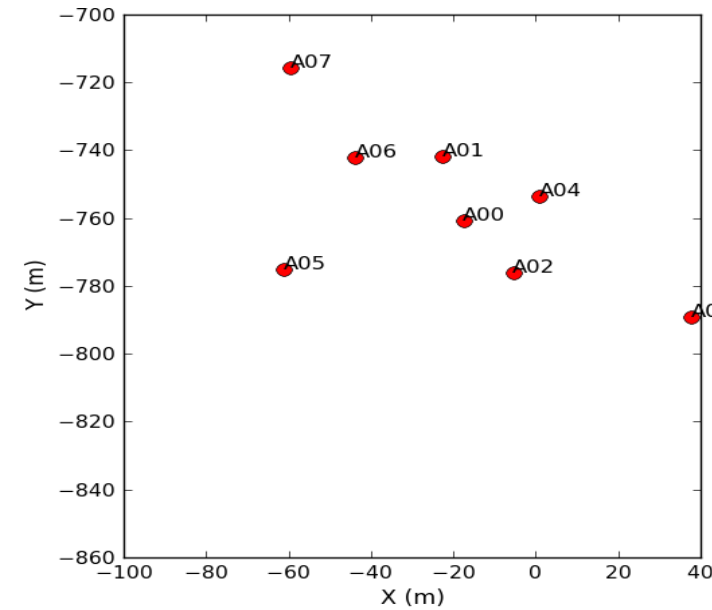
Example: Fringe pattern with 3 Antennas (3 baselines)



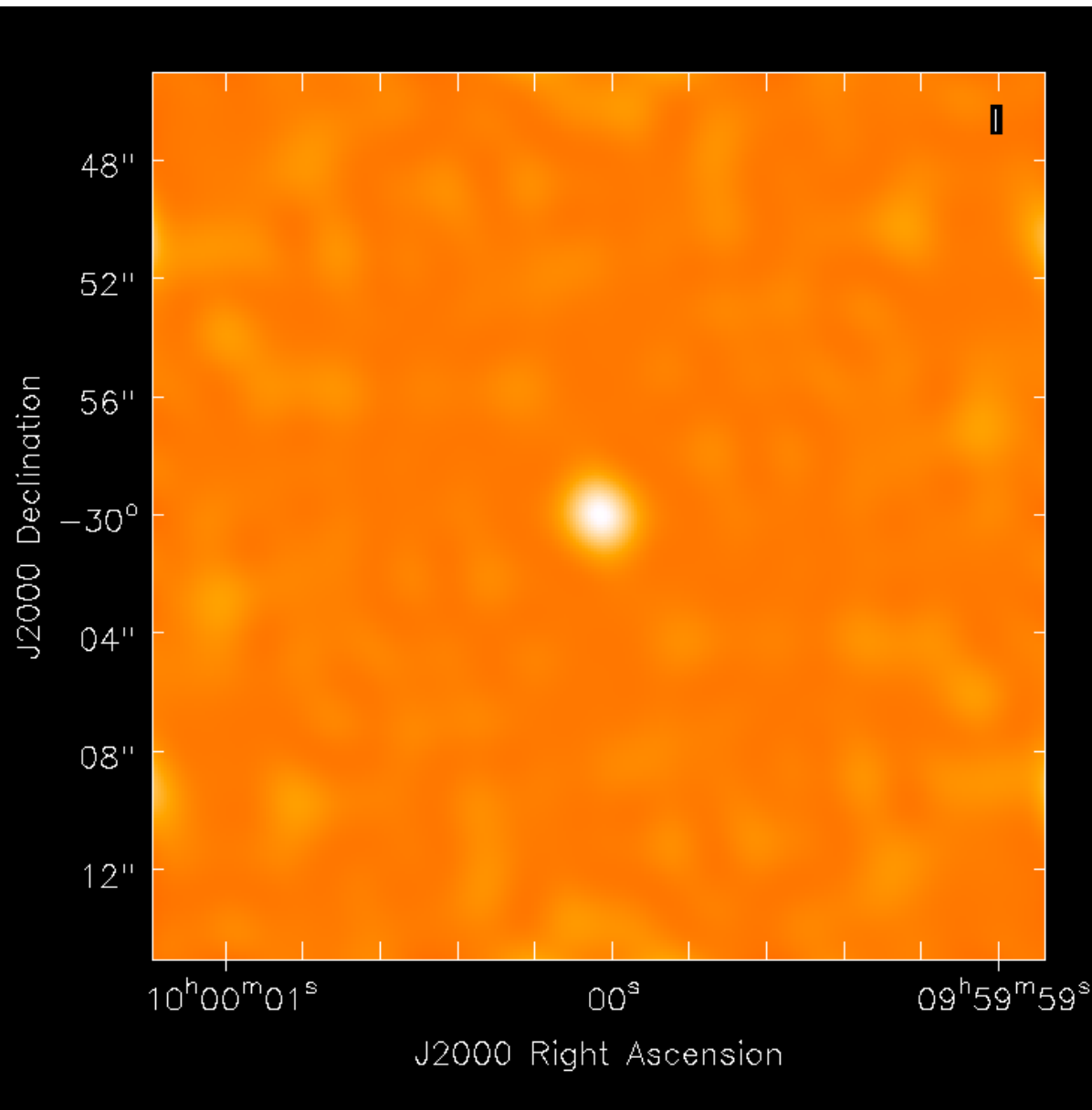
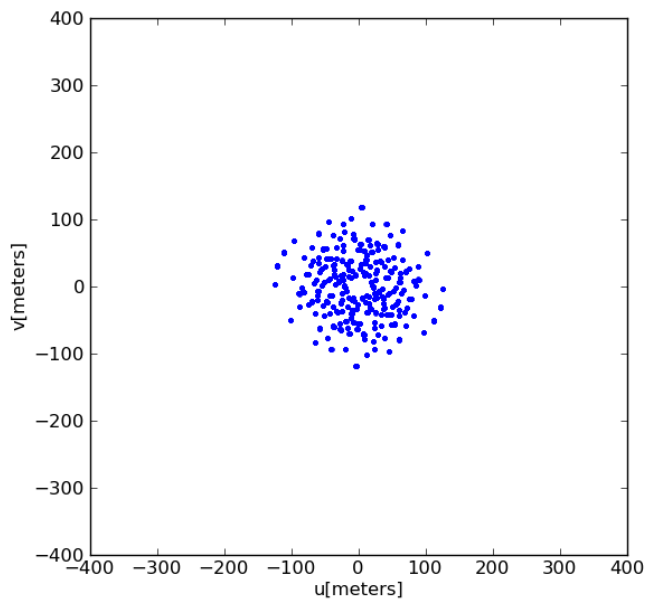
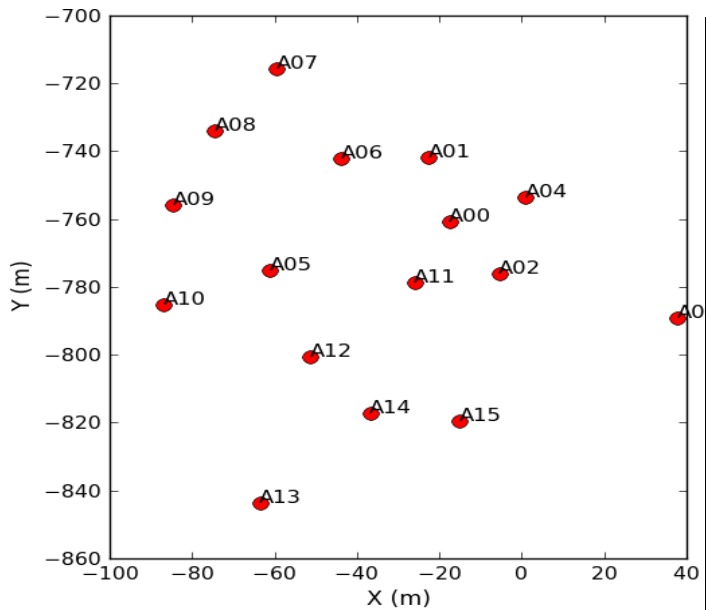
Example: Fringe pattern with 4 Antennas (6 baselines)



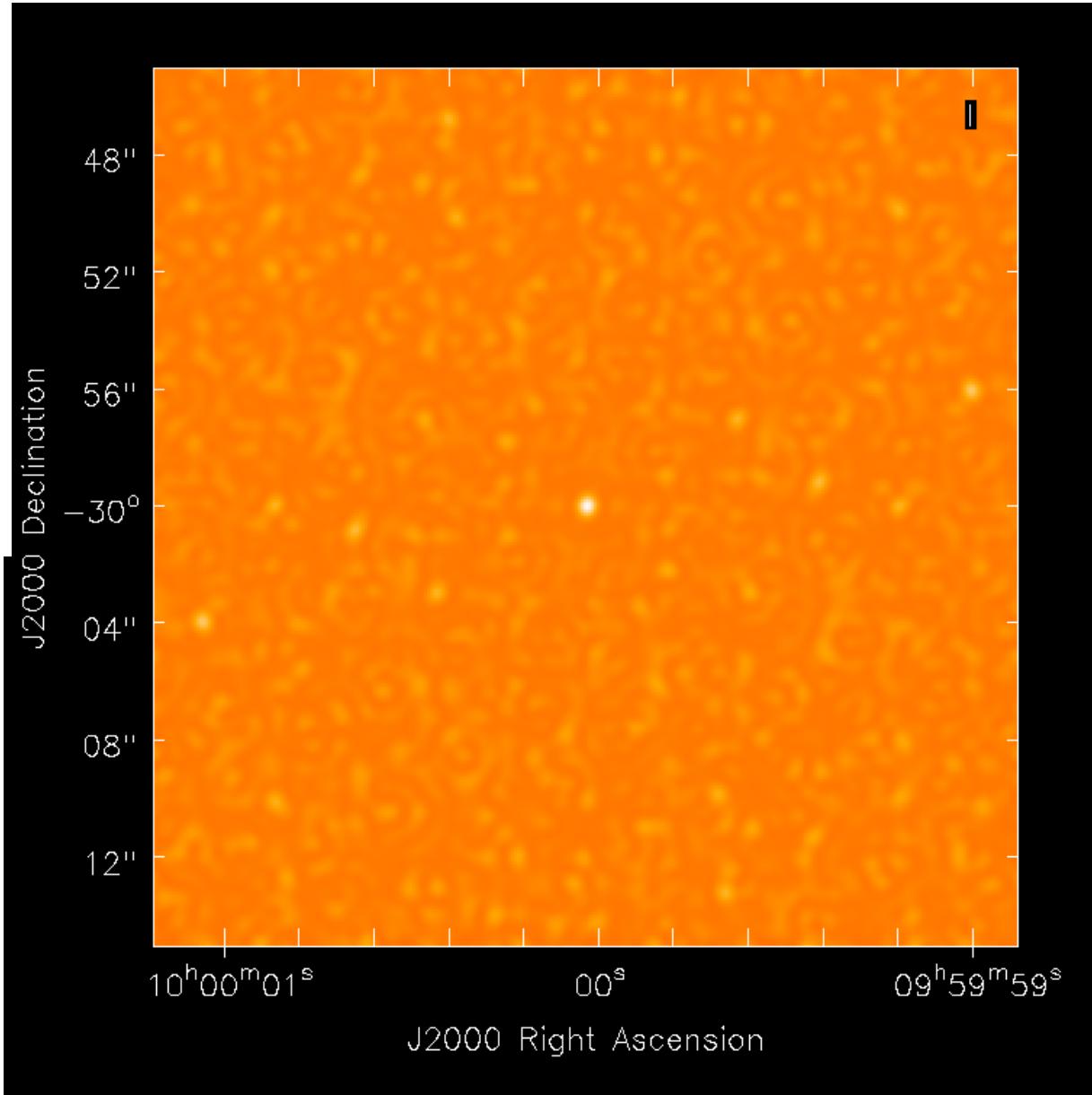
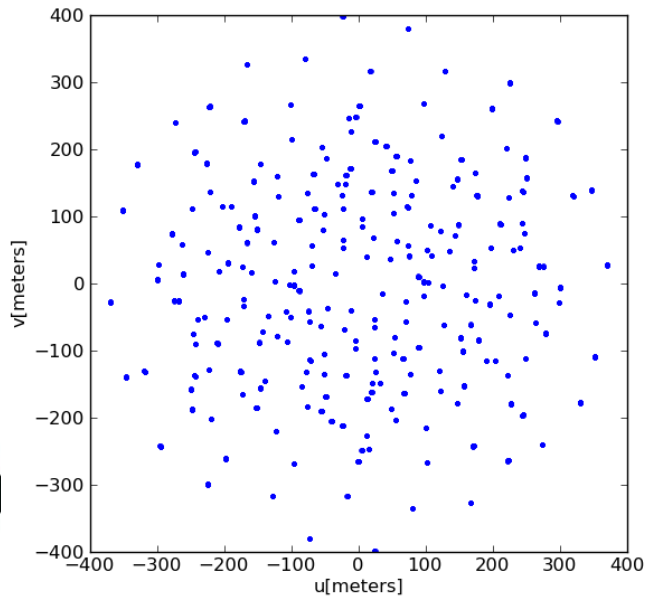
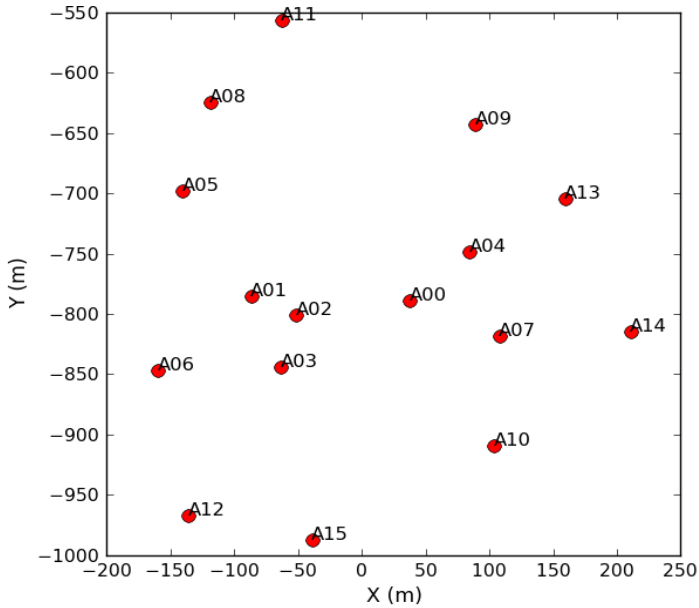
Example: Fringe pattern with 8 Antennas (28 baselines)



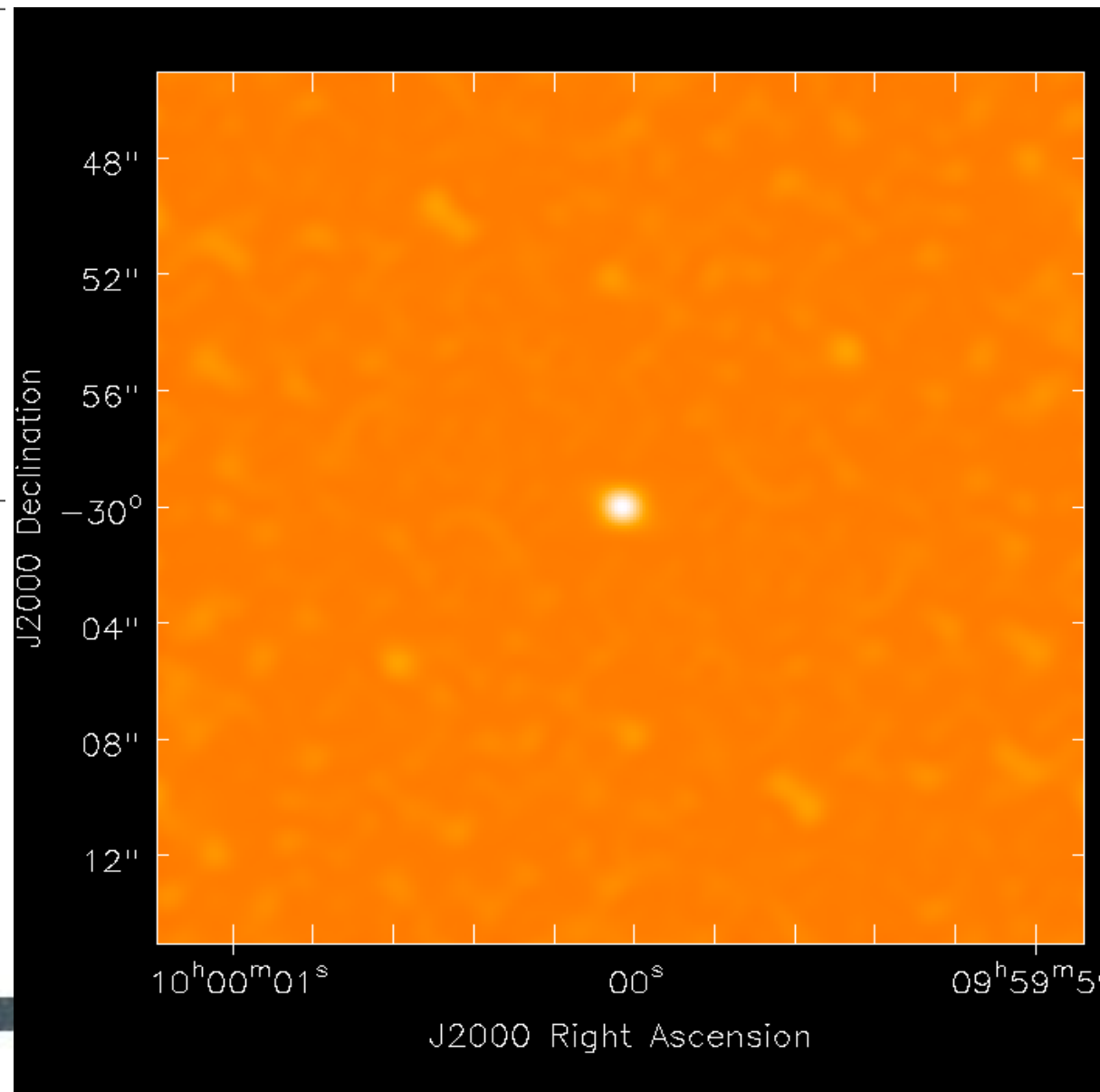
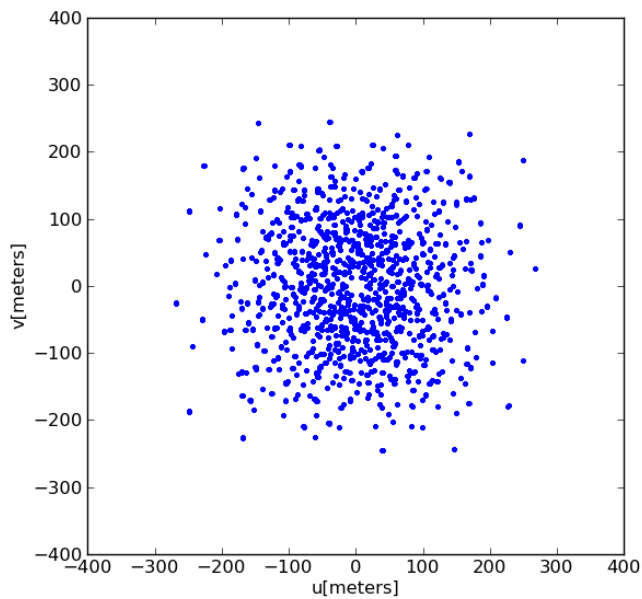
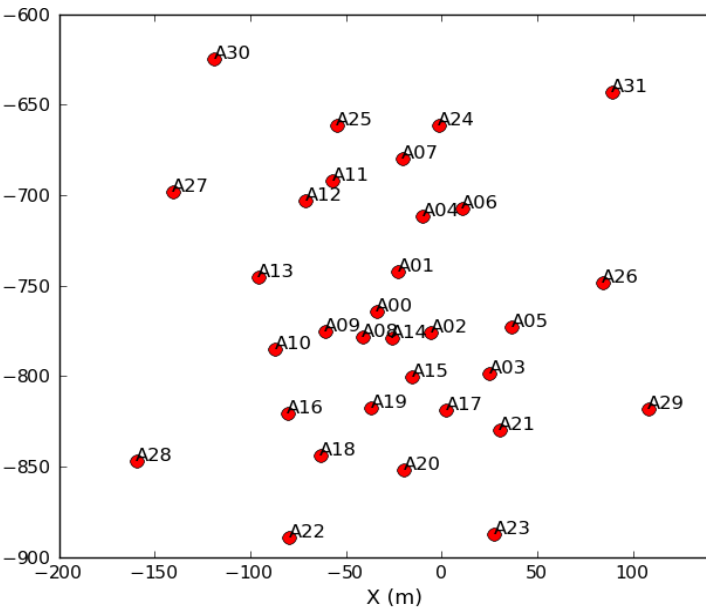
16 Antennas – Compact Configuration



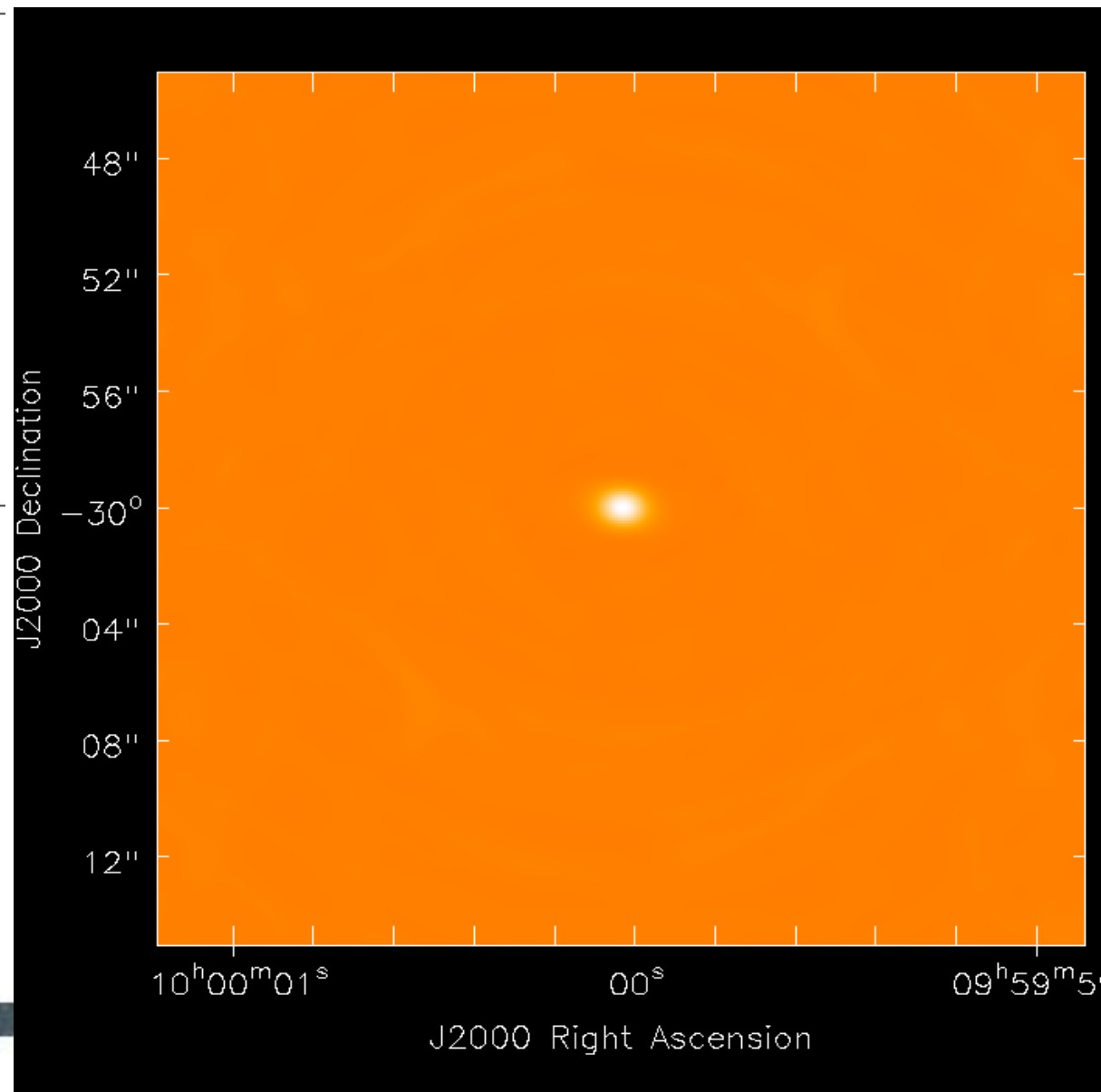
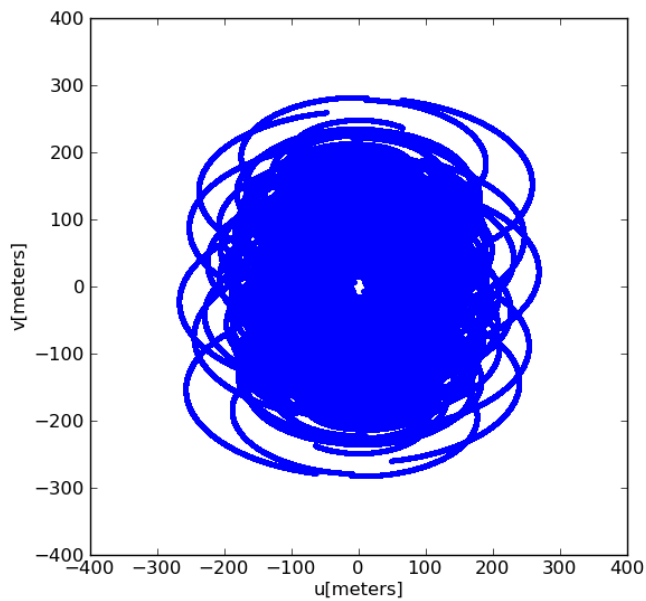
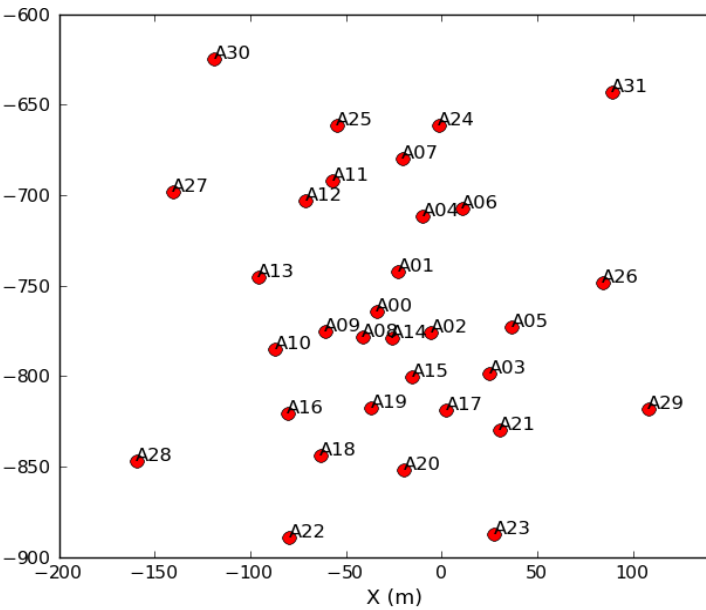
16 Antennas – Extended Configuration



32 Antennas – Instantaneous



32 Antennas – 8 hours



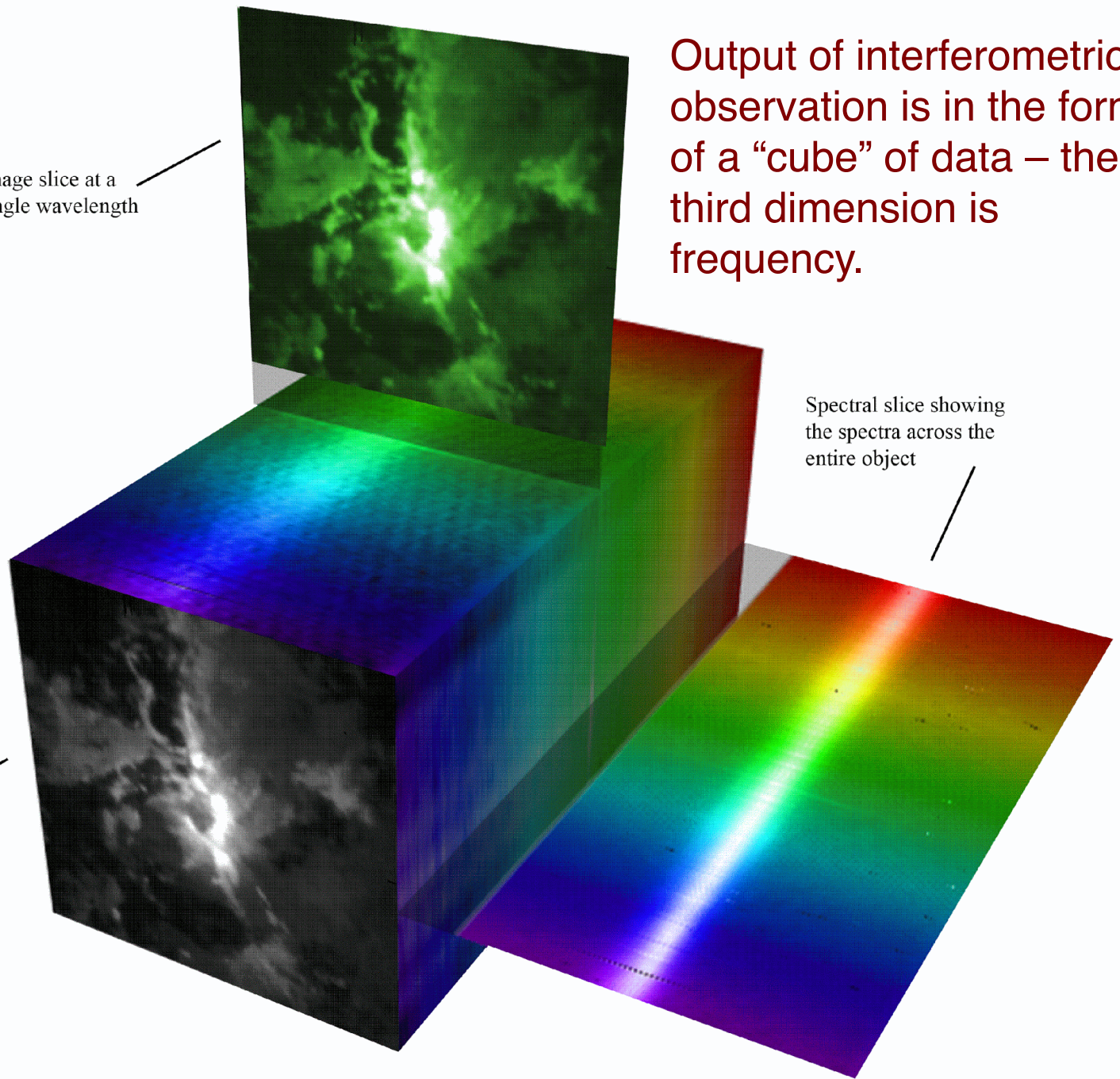
Not only 2D imaging, but 3D

Output of interferometric observation is in the form of a “cube” of data – the third dimension is frequency.

Image slice at a single wavelength

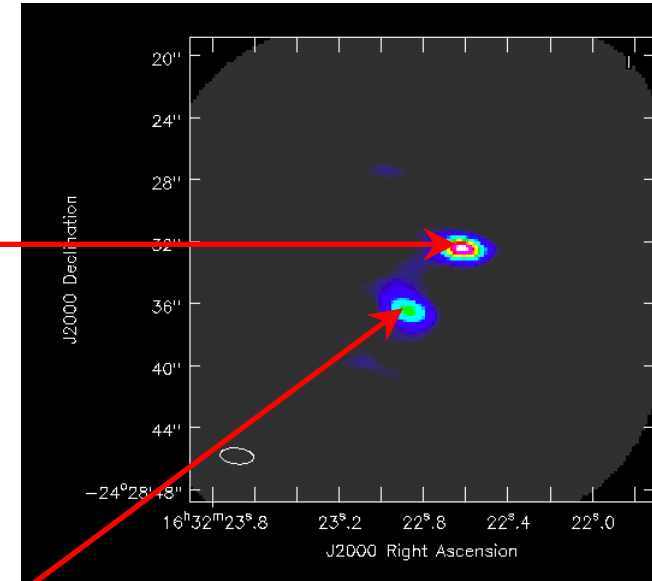
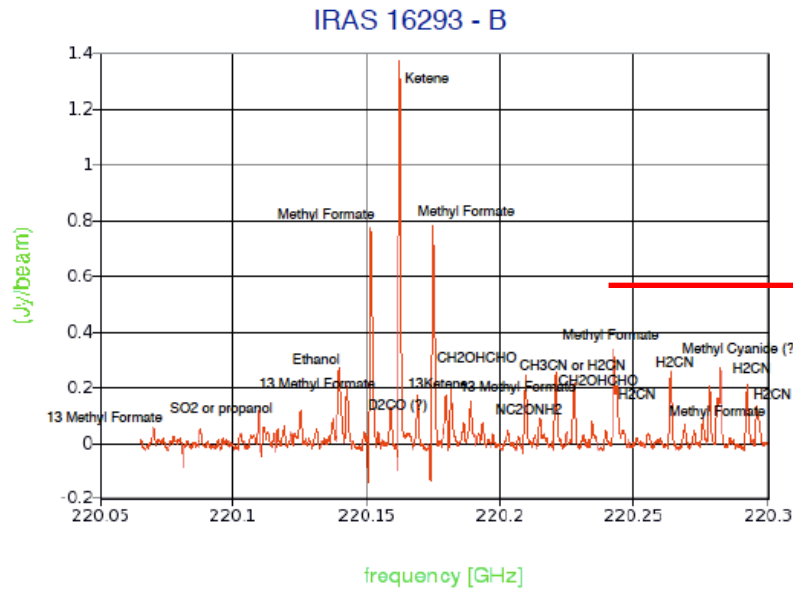
Spectral slice showing the spectra across the entire object

Object seen in combined light

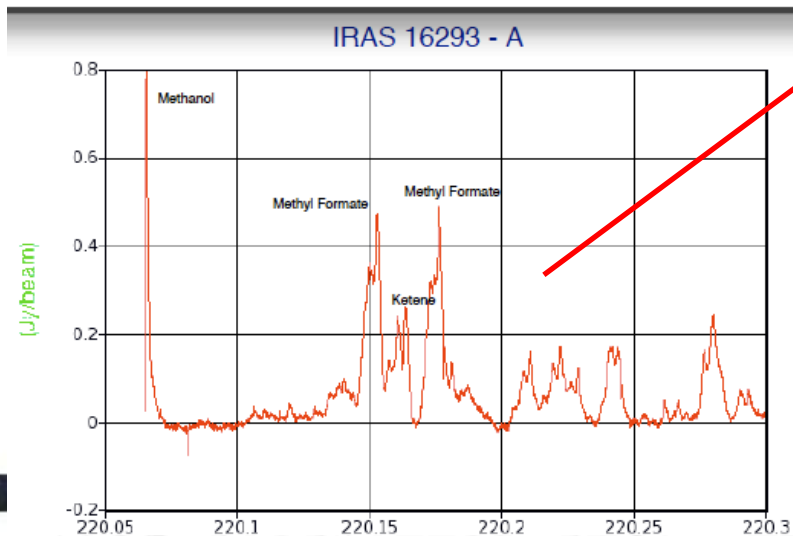


Sometimes the most interesting science lies in the third dimension

Band 6

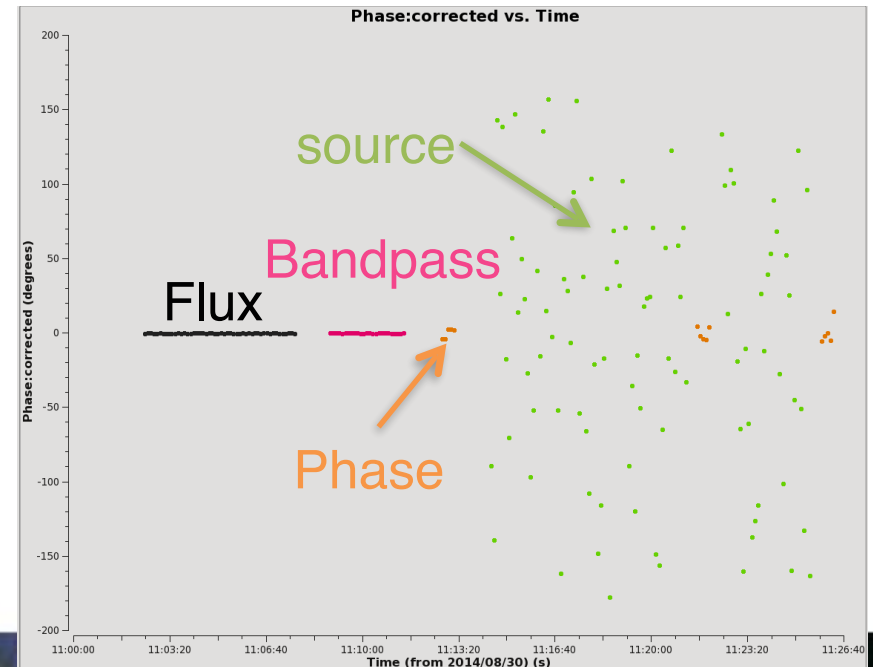
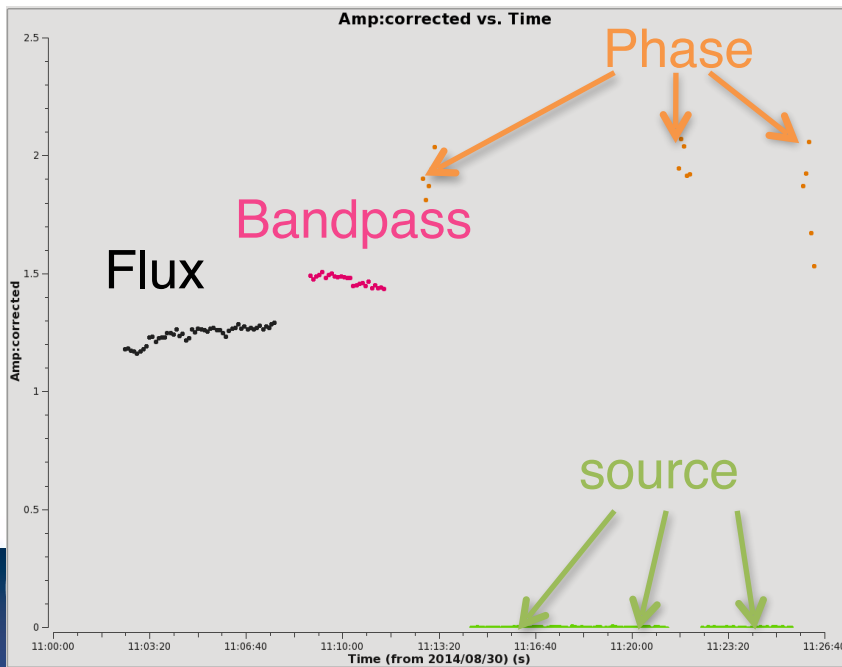


J. Turner & ALMA CSV team



A Brief Word on Calibration

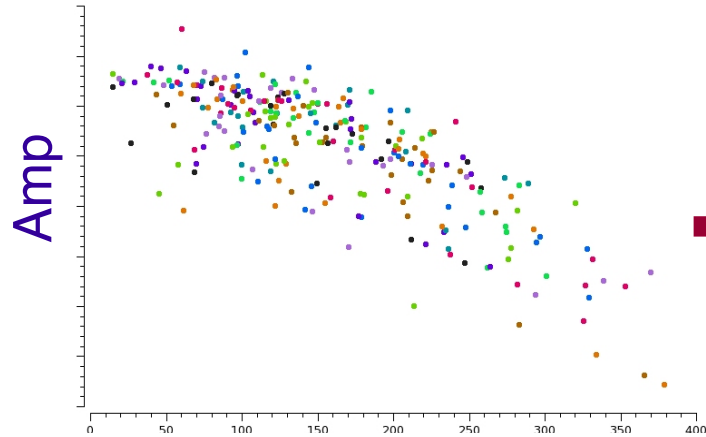
- Interferometers measure visibilities of real telescopes as a function of time and frequency.
- We need to take into account instrument differences between antennas, changing weather conditions, etc.



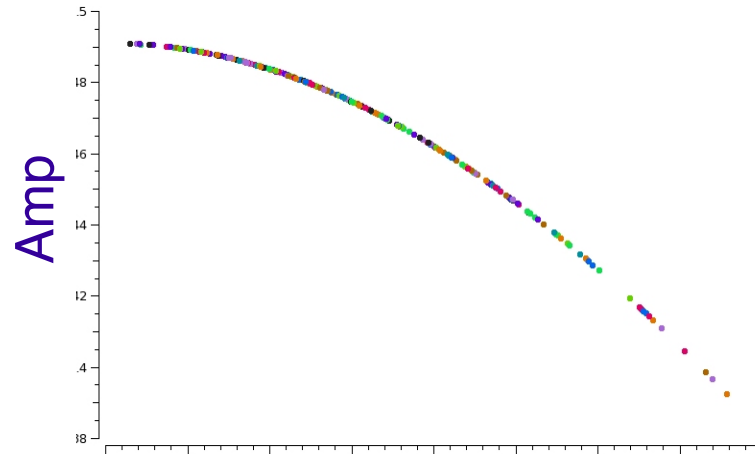
Flux (or Amplitude) Calibration

Flux calibration takes into account your absolute scaling

Uncalibrated data



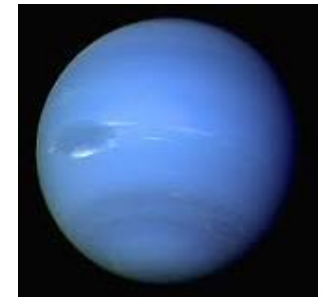
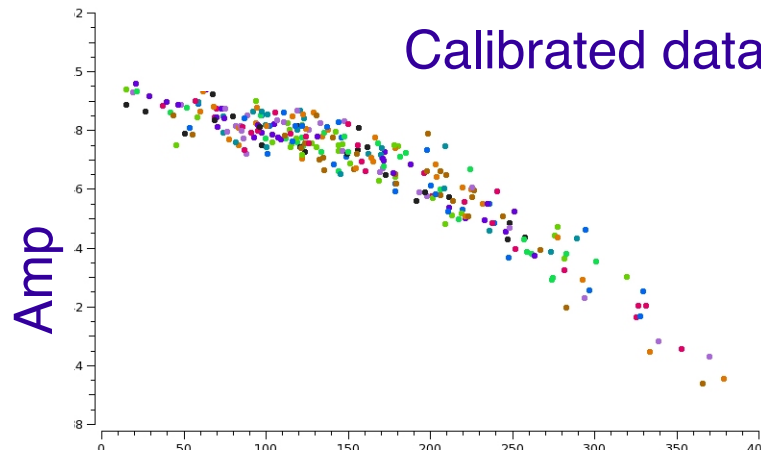
UV model



UV dist

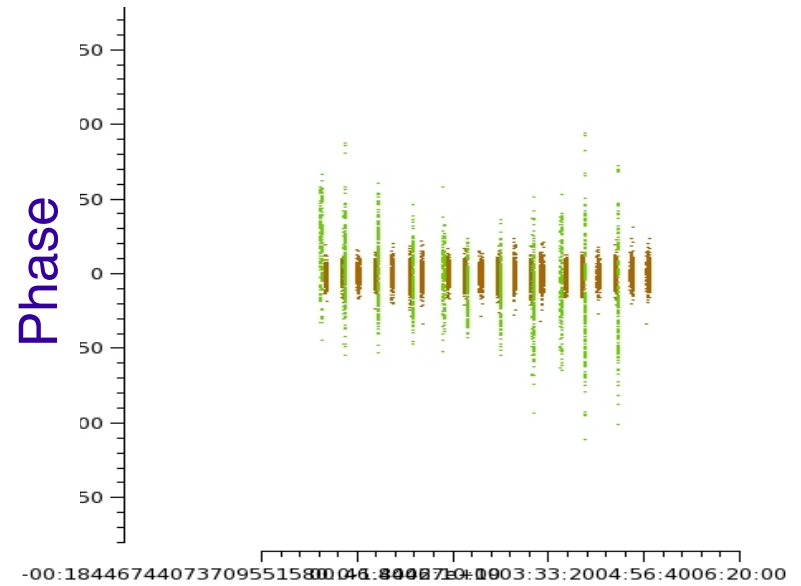
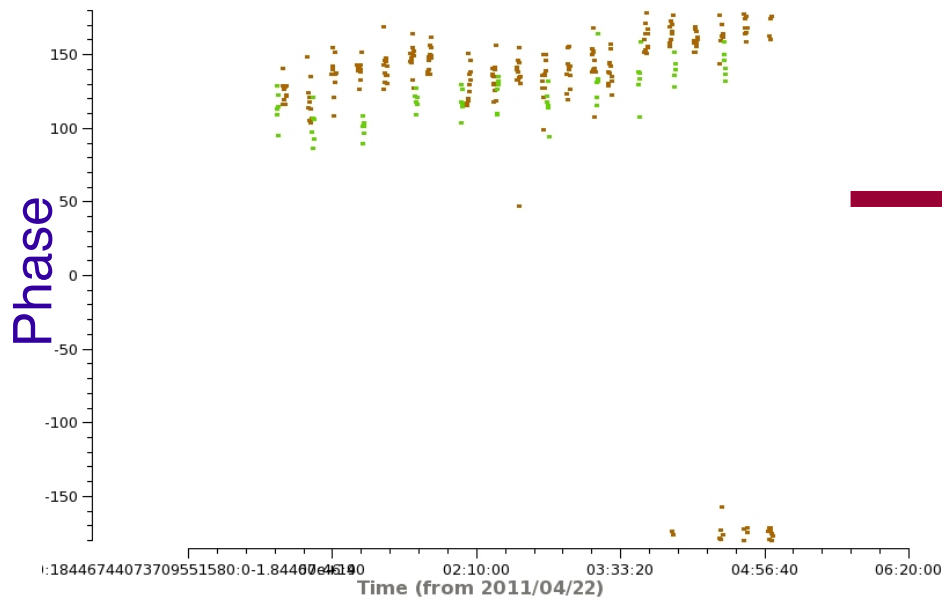
UV dist

Calibrated data



Phase Calibration

Phase calibration takes into account how your flux varies throughout your observation

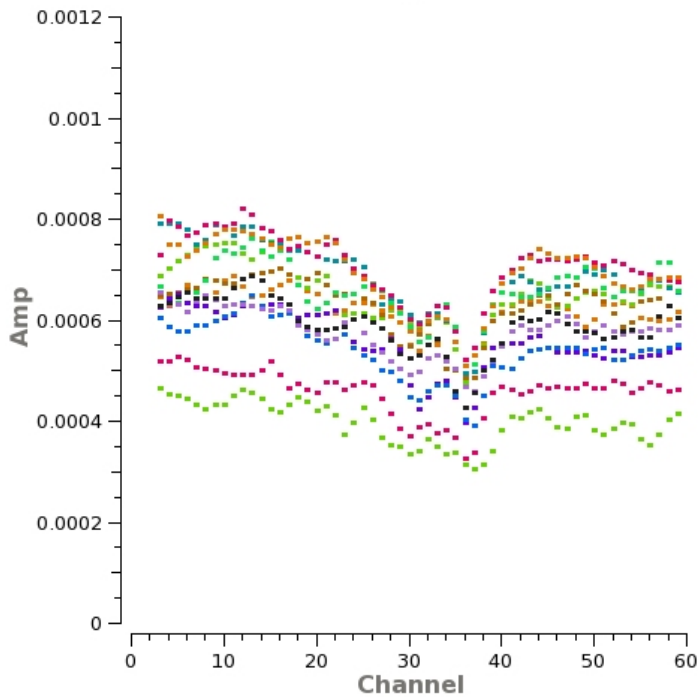


Time

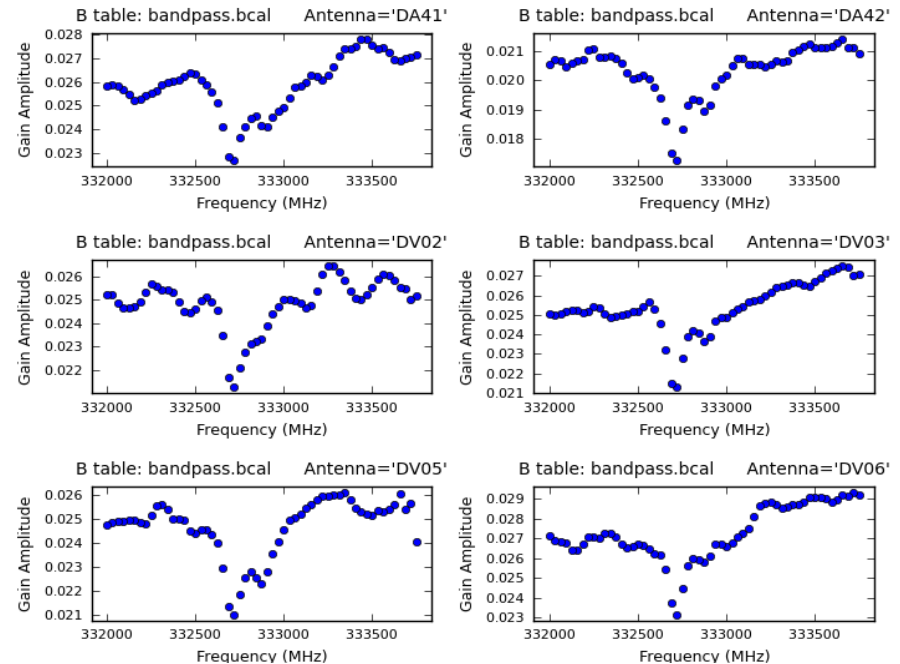
Time

Bandpass Calibration (Amplitude)

Primarily correcting for frequency dependent telescope response (i.e. in the correlator/spectral windows)



Before calibration

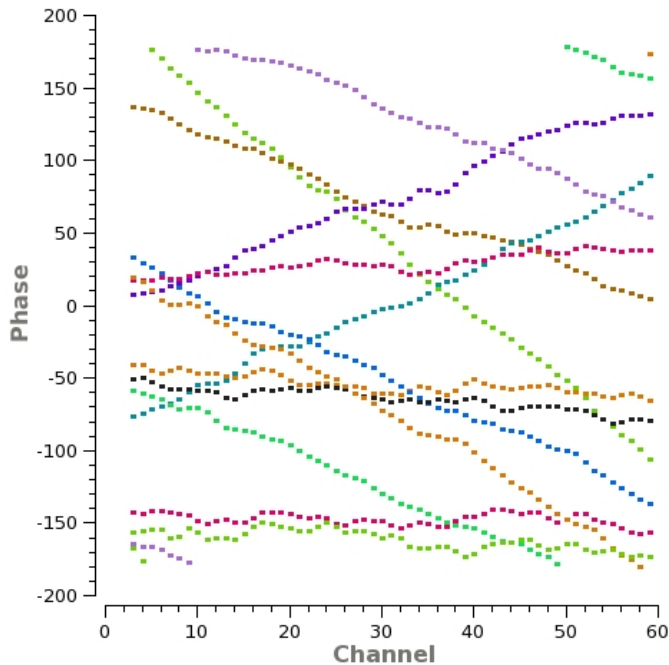


Solutions for individual antennas

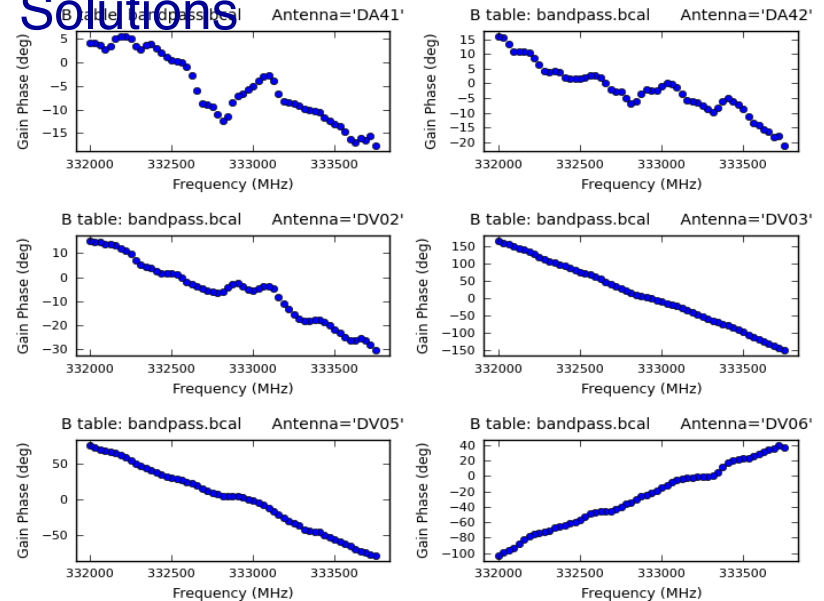
Bandpass Calibration (Phase)

Primarily correcting for frequency dependent telescope response (i.e. in the correlator/spectral windows)

Baselines to one antenna



Antenna-based Bandpass Solutions



Good Future References

Thompson, A.R., Moran, J.M., Swensen, G.W. 2017
“Interferometry and Synthesis in Radio Astronomy”, 3rd edition
(Springer)

<http://www.springer.com/us/book/9783319444291>

Perley, R.A., Schwab, F.R., Bridle, A.H. eds. 1989 ASP Conf.
Series 6 “Synthesis Imaging in Radio Astronomy” (San
Francisco: ASP)

www.aoc.nrao.edu/events/synthesis

IRAM Interferometry School proceedings

www.iram.fr/IRAMFR/IS/IS2008/archive.html





www.nrao.edu
science.nrao.edu

*The National Radio Astronomy Observatory is a facility of the National
Science Foundation
operated under cooperative agreement by Associated Universities, Inc.*



Back up slides

Calibration Process

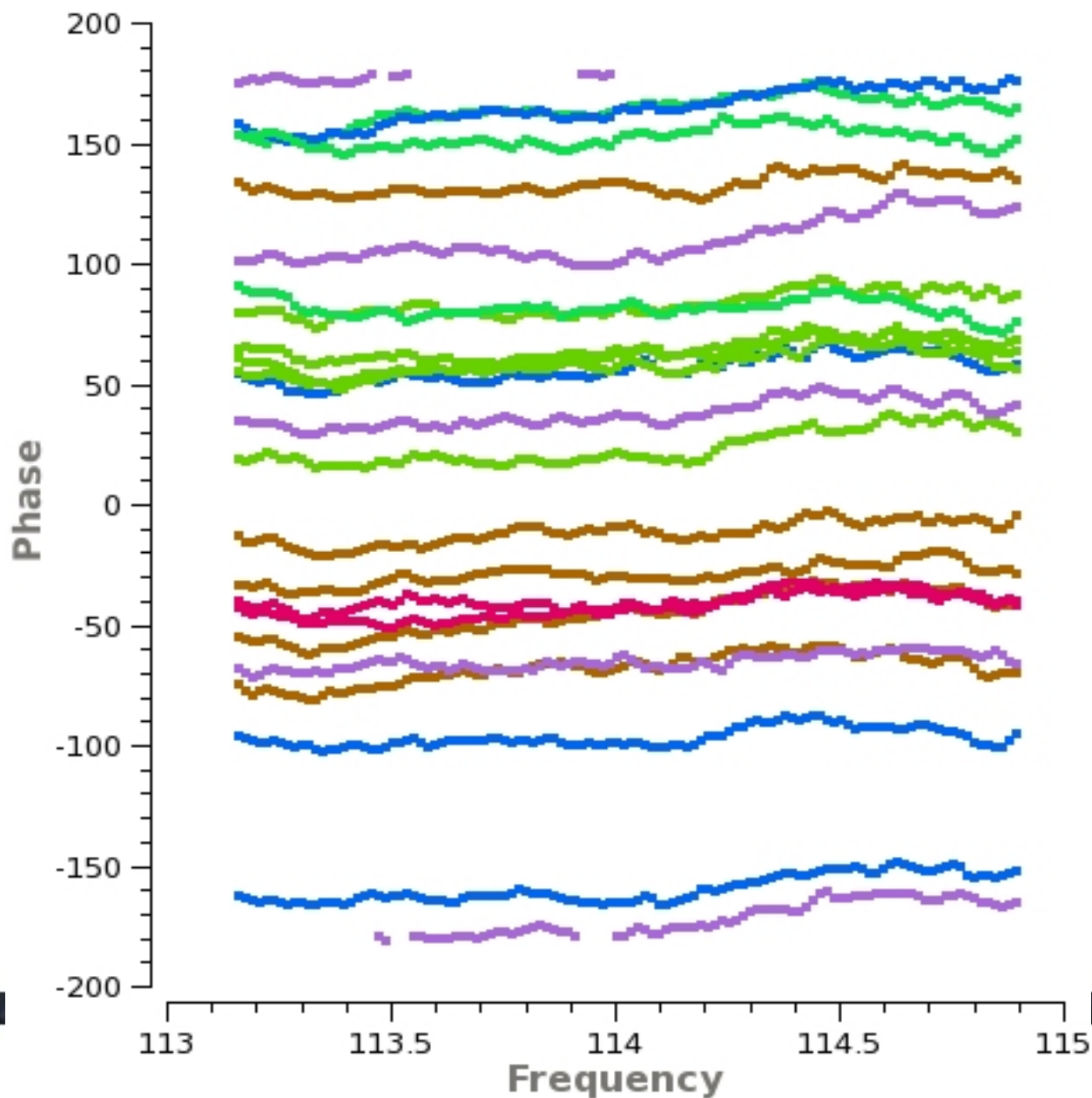
Calibration is the effort to measure and remove the time-dependent and frequency-dependent atmospheric and instrumental variations.

Steps in calibrating interferometric data:

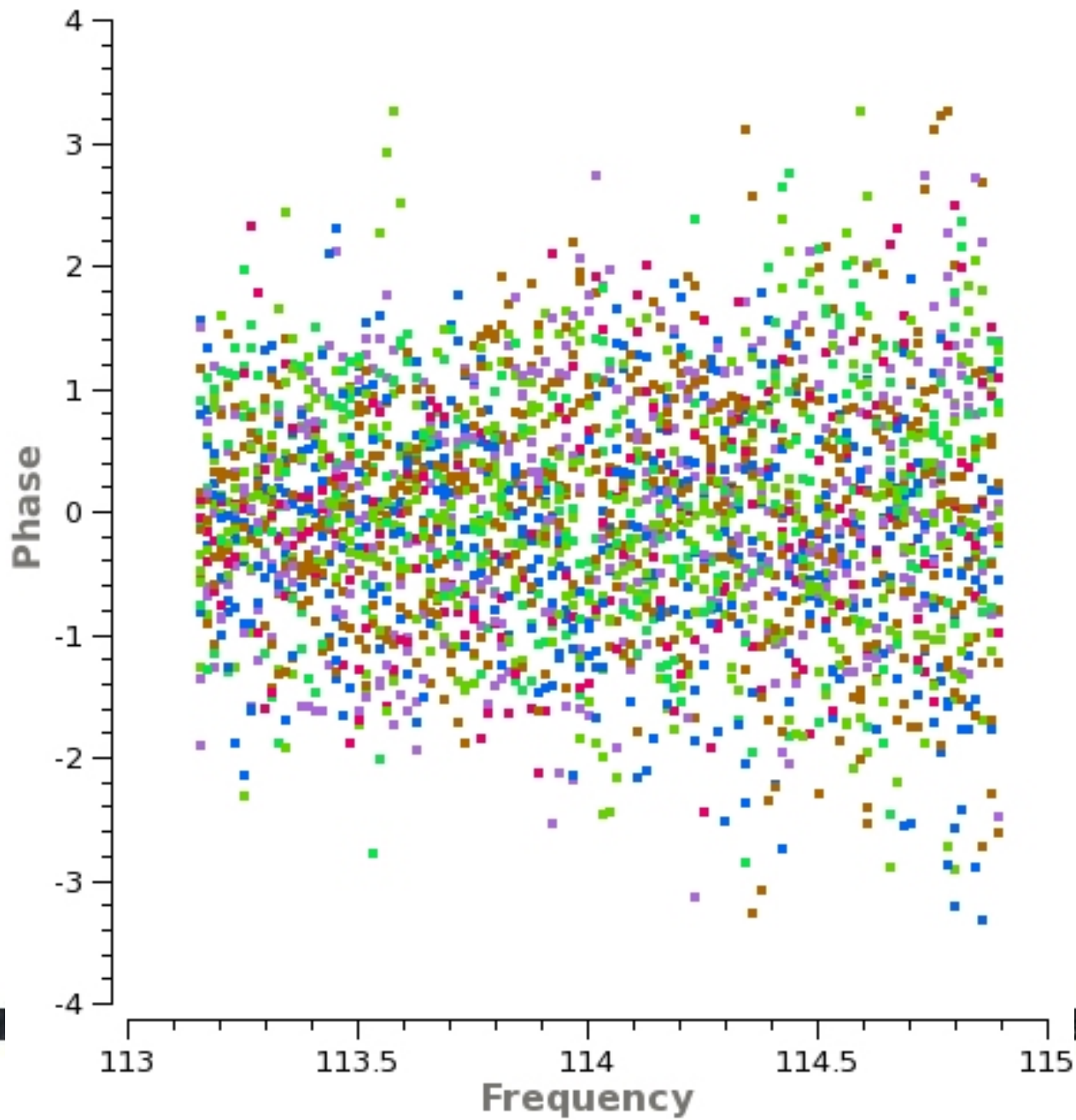
(Note: You don't have to worry about these in your observational set up!)

- Bandpass calibration (correct frequency-dependent telescope response)
- Phase and amplitude gain calibration (remove effects of atmospheric water vapor and correct time-varying phases/amplitudes)
- Set absolute flux scale

Bandpass Phase vs. Frequency (Before)



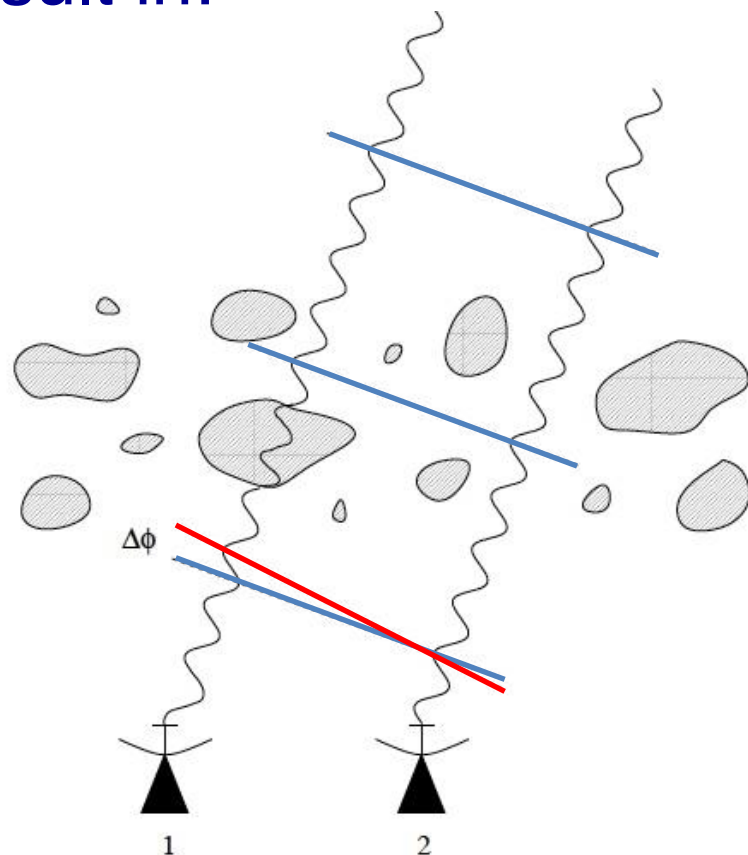
Bandpass Phase vs. Frequency (After)



Atmospheric Phase Correction

- Variations in the amount of precipitable water vapor cause phase fluctuations that result in:
 - Low coherence (loss of sensitivity)
 - Radio “seeing” of 1 arcsec at 1mm
 - Anomalous pointing offsets
 - Anomalous delay offsets

Patches of air with different water vapor content (and hence index of refraction) affect the incoming wave front differently.

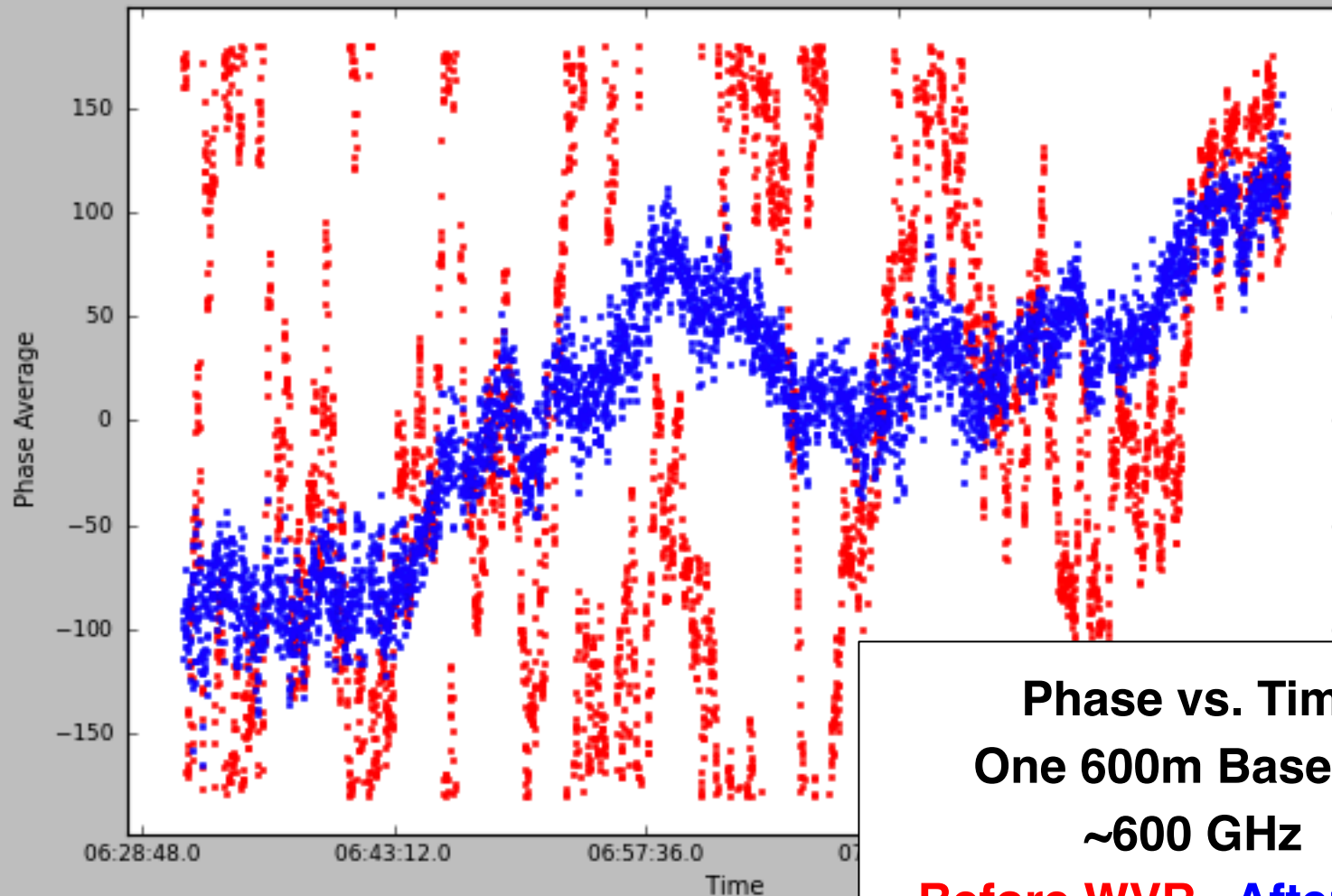


Phase & Amplitude Gain Calibration

Determines the variations of phase and amplitude over time

- First pass is atmospheric correction from Water Vapor Radiometers readings
- Final correction from gain calibrator (point source near to target) that is observed every few minutes throughout the observation (analogous to repeat trips to a standard star)

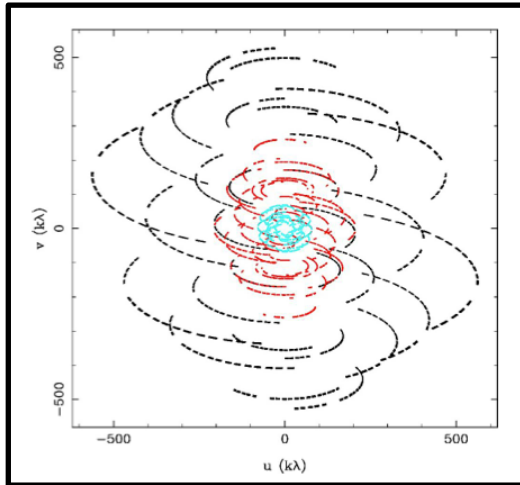
Water Vapor Correction on ALMA



Phase vs. Time
One 600m Baseline
~600 GHz
Before WVR, After WVR

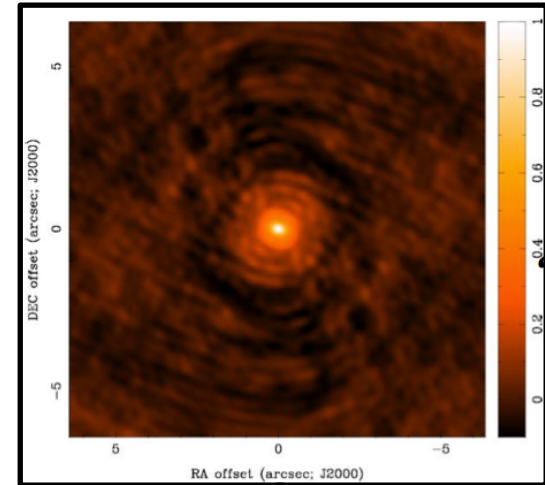
The Dirty Beam

$S(u,v)$

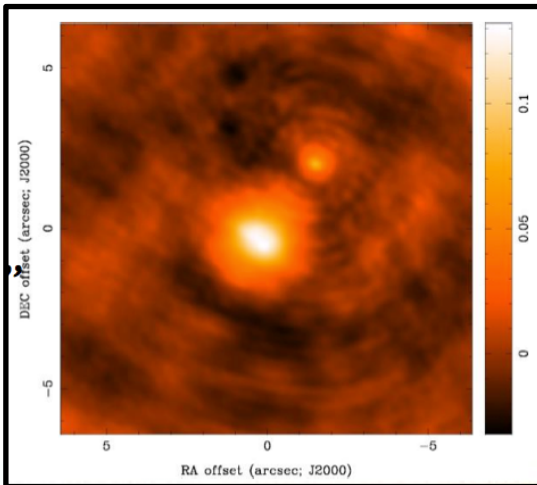


FT
→

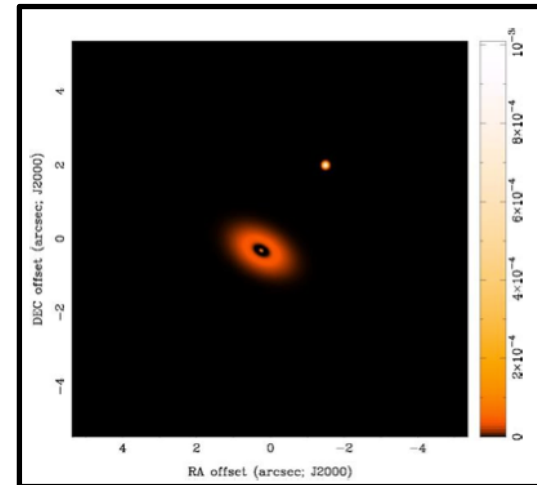
$s(x,y)$
“Dirty Beam”



*(Convolution)



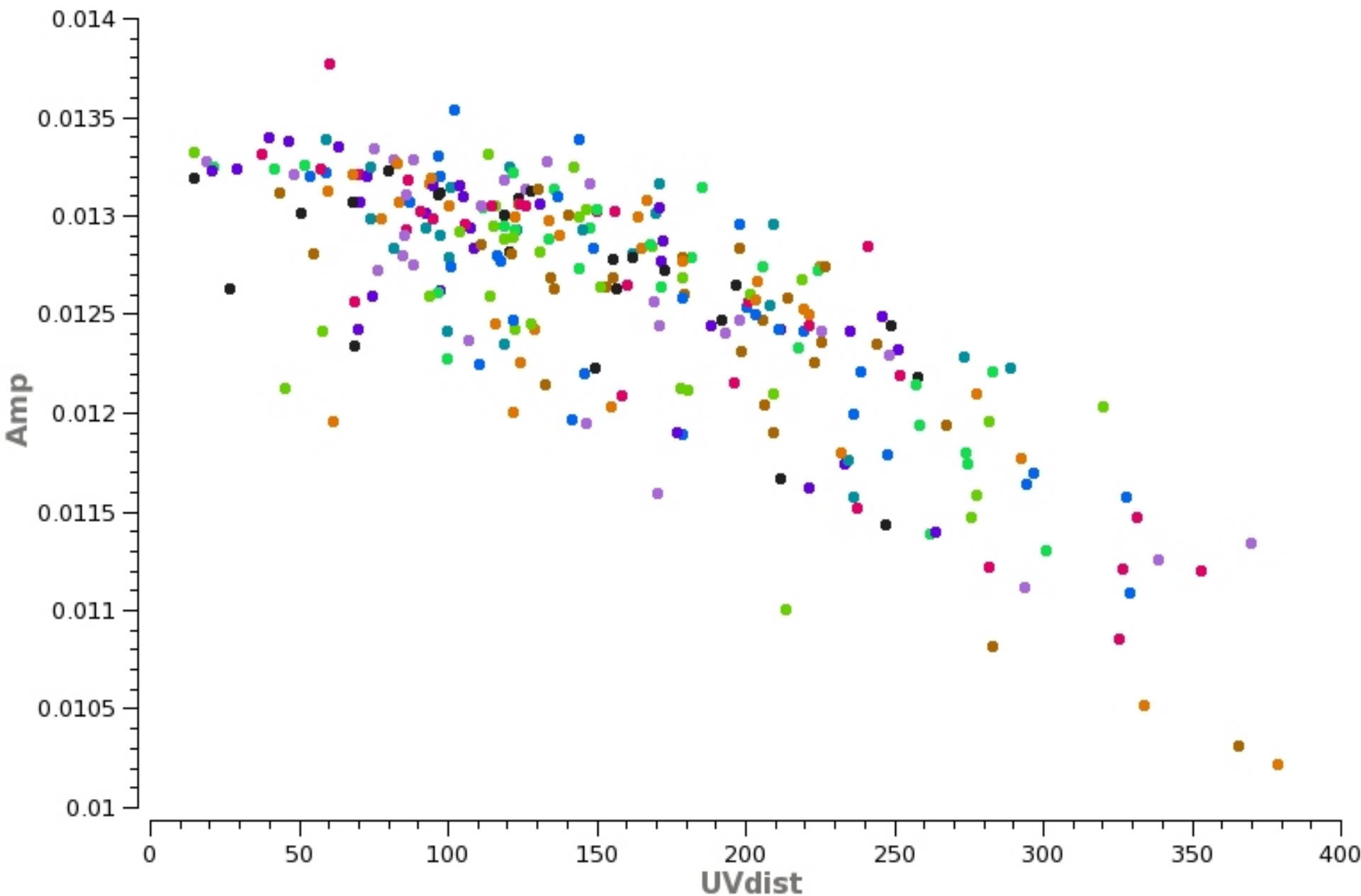
←



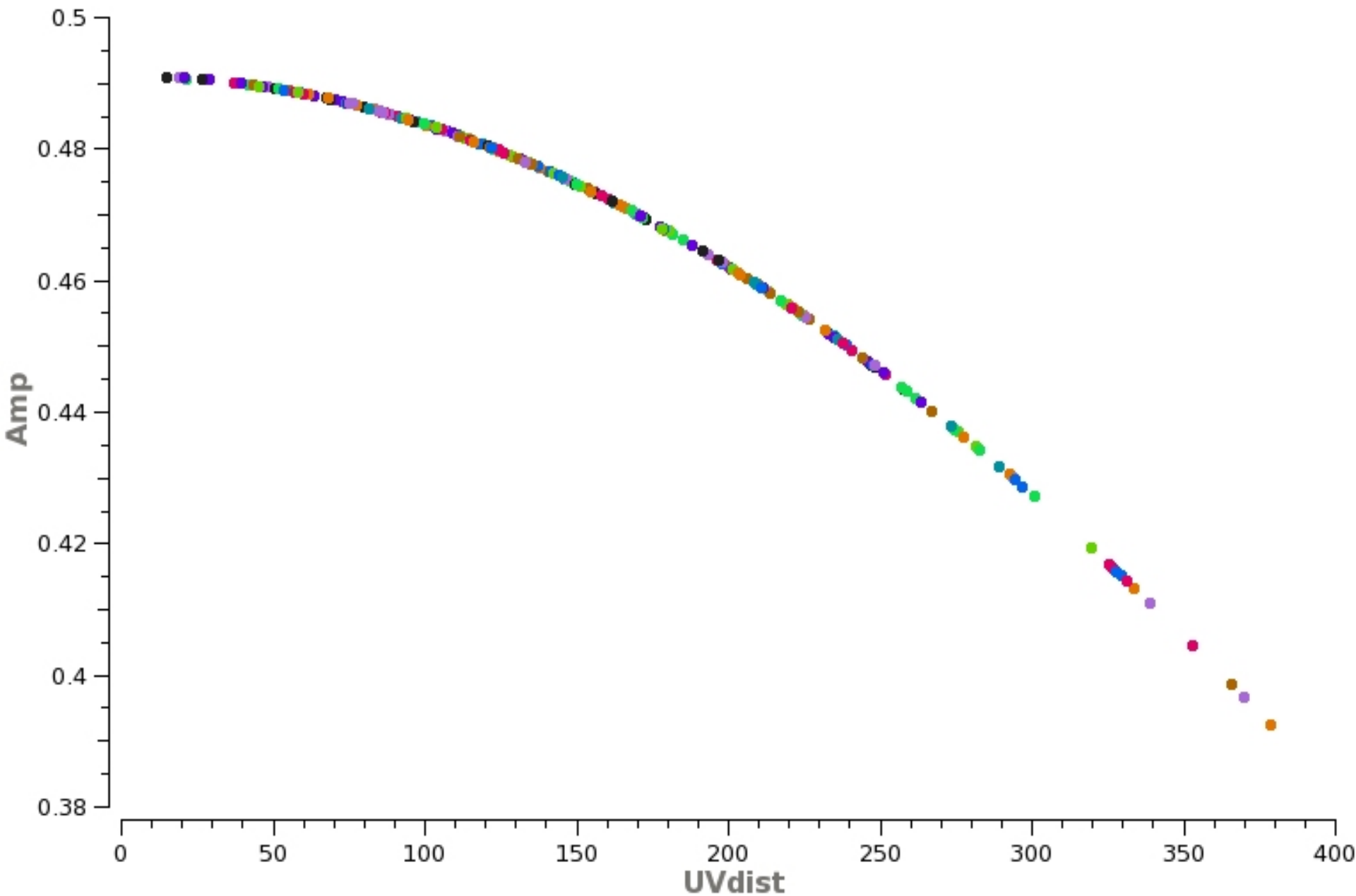
$T_D(x,y)$
“Dirty Image”

$T(x,y)$

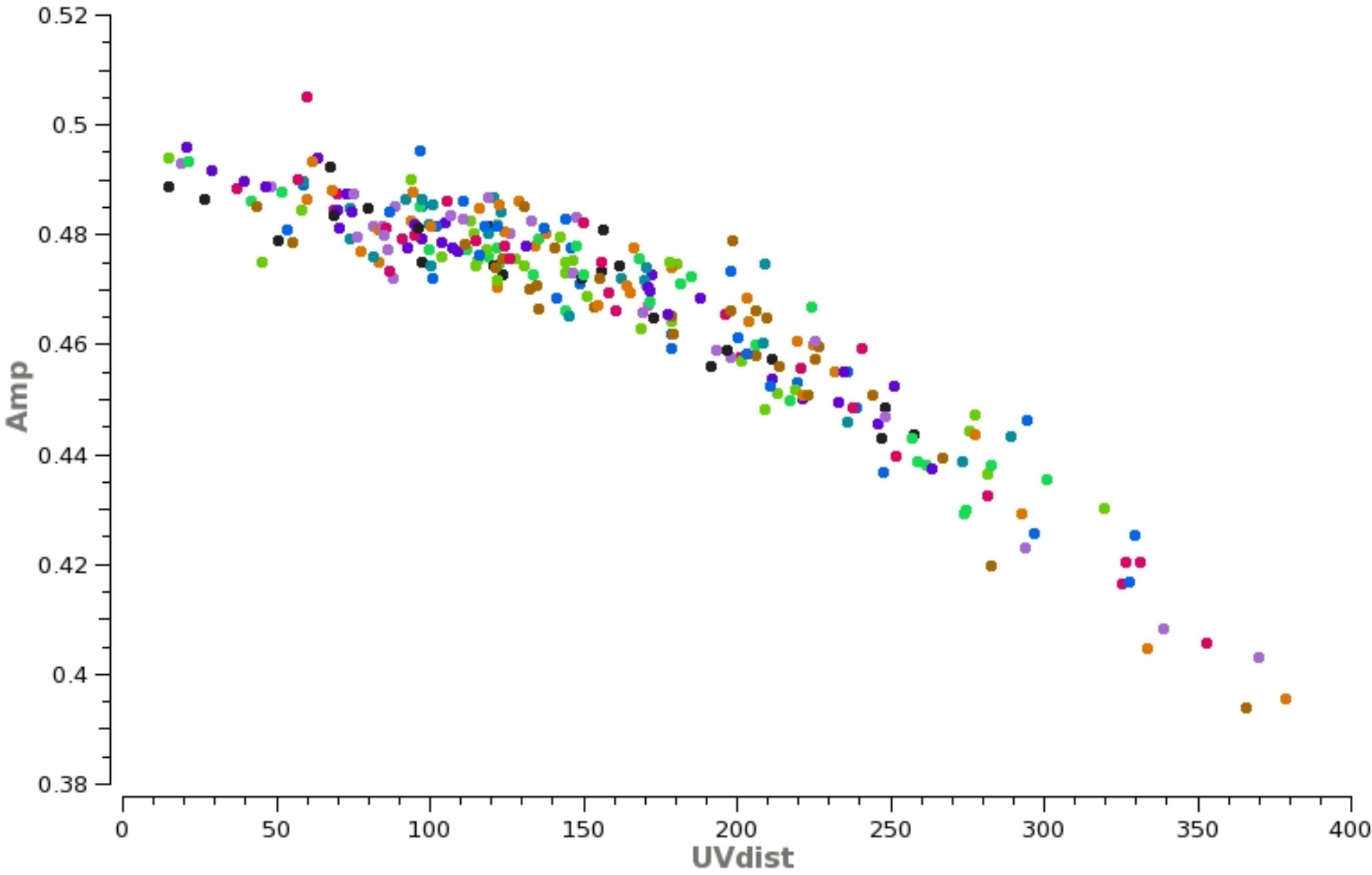
Amp-Calibrators Amp vs. uv-distance (Before)



Amp-Calibrators Amp vs. uv-distance (Model)



Amp-Calibrators Amp vs. uv-distance (After)



Penetrates Earth Atmosphere?



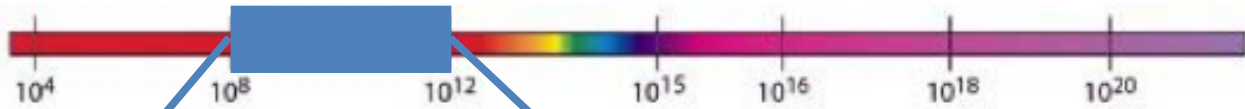
Wavelength (meters)



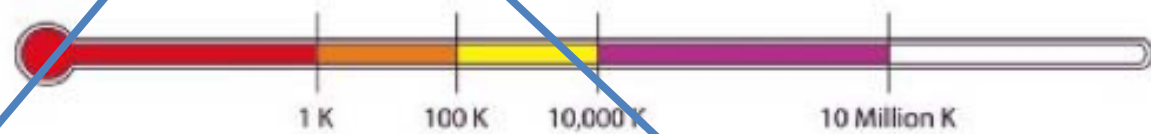
About the size of...



Frequency (Hz)



Temperature of bodies emitting the wavelength (K)



VLA
~1 - 50 GHz
~300 - 6 mm

ALMA
~84 - 950 GHz
~3 - 0.3 mm

Angular Scales – A Proposal Tip!

Interferometers act as spatial filters - shorter baselines are sensitive to larger targets, so remember ...

Spatial scales larger than the smallest baseline cannot be imaged

Spatial scales smaller than the largest baseline cannot be resolved

Config	Lmax		Band 3	Band 4	Band 5	Band 6	Band 7	Band 8	Band 9	Band 10
	Lmin		100 GHz	150 GHz	183 GHz	230 GHz	345 GHz	460 GHz	650 GHz	870 GHz
7-m Array	45 m	AR	12.5"	8.4"	6.8"	5.4"	3.6"	2.7"	1.9"	1.4"
	9 m	MRS	66.7"	44.5"	36.1"	29.0"	19.3"	14.5"	10.3"	7.7"
C43-1	161 m	AR	3.4"	2.3"	1.8"	1.5"	1.0"	0.74"	0.52"	0.39"
	15 m	MRS	28.5"	19.0"	15.4"	12.4"	8.3"	6.2"	4.4"	3.3"
C43-2	314 m	AR	2.3"	1.5"	1.2"	1.0"	0.67"	0.50"	0.35"	0.26"
	15 m	MRS	22.6"	15.0"	12.2"	9.8"	6.5"	4.9"	3.5"	2.6"
C43-3	500 m	AR	1.4"	0.94"	0.77"	0.62"	0.41"	0.31"	0.22"	0.16"
	15 m	MRS	16.2"	10.8"	8.7"	7.0"	4.7"	3.5"	2.5"	1.9"
C43-4	784 m	AR	0.92"	0.61"	0.50"	0.40"	0.27"	0.20"	0.14"	0.11"
	15 m	MRS	11.2"	7.5"	6.1"	4.9"	3.3"	2.4"	1.7"	1.3"
C43-5	1.4 km	AR	0.54"	0.36"	0.30"	0.24"	0.16"	0.12"	0.084"	0.063"
	15 m	MRS	6.7"	4.5"	3.6"	2.9"	1.9"	1.5"	1.0"	0.77"
C43-6	2.5 km	AR	0.31"	0.20"	0.16"	0.13"	0.089"	0.067"	0.047"	0.035"
	15 m	MRS	4.1"	2.7"	2.2"	1.8"	1.2"	0.89"	0.63"	0.47"
C43-7	3.6 km	AR	0.21"	0.14"	0.11"	0.092"	0.061"	0.046"	0.033"	0.024"
	64 m	MRS	2.6"	1.7"	1.4"	1.1"	0.75"	0.56"	0.40"	0.30"
C43-8	8.5 km	AR	0.096"	0.064"	0.052"	0.042"	0.028"	N/A	N/A	N/A
	110 m	MRS	1.4"	0.95"	0.77"	0.62"	0.41"	N/A	N/A	N/A
C43-9	13.9 km	AR	0.057"	0.038"	0.031"	0.025"	N/A	N/A	N/A	N/A
	368 m	MRS	0.81"	0.54"	0.44"	0.35"	N/A	N/A	N/A	N/A
C43-10	16.2 km	AR	0.042"	0.028"	0.023"	0.018"	N/A	N/A	N/A	N/A
	244 m	MRS	0.50"	0.33"	0.27"	0.22"	N/A	N/A	N/A	N/A

From the ALMA Cycle 6 Proposal Guide



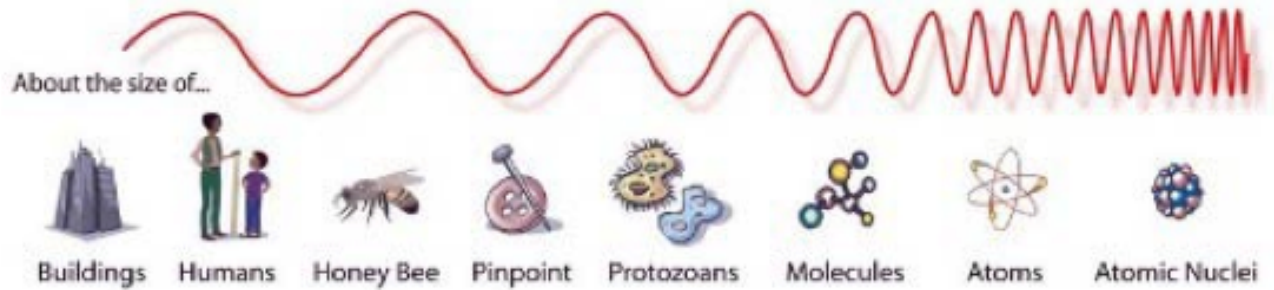
Penetrates Earth Atmosphere?



Wavelength (meters)



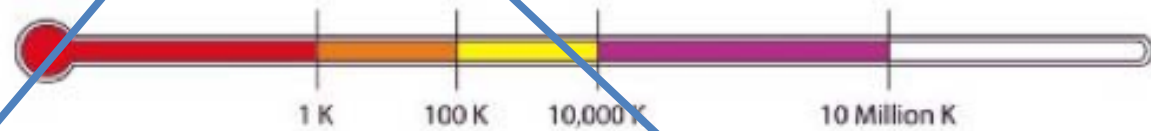
About the size of...



Frequency (Hz)



Temperature of bodies emitting the wavelength (K)



ngVLA
1.2-116GHz
3-30 mm

ALMA
~84 - 950 GHz
~3 - 0.3 mm