Simulations and Imaging with CASA!

09:15 - 09:50 -- ALMA Overview talk, ALMA Cycle 5 proposals

09:50 - 10:40 -- Local ALMA Science Highlights:
Brendan Bowler, Yao-Lun Yang,
Jackie Champagne, Sam Factor

10:40 - 11:00 -- Break

11:00 - 11:20 -- ALMA Observing Tool and ALMA data archive

11:20 - 12:30 -- Small group work on ALMA OT and/or archive

12:30 - 13:40 -- Lunch (provided for registered participants)

13:40 - 14:10 -- Introduction to data imaging and ALMA simulations

14:10 - 16:30 -- Small group work on Data Imaging or Simulations





Goals:

- Simulate an ALMA image for your Cycle 5 proposals.
- Simulate ALMA observations for your paper.
- Image ALMA archival data or your own data.
- Learn how cleaning/imaging of interferometer data are done. Reproduce TW Hydra or other famous ALMA observations.
- Other goals?



CASA (Common Astronomy Software Application package):

https://casa.nrao.edu/casa_obtaining.shtml

Downloads

Please follow these links for downloading the code for your specific operating system. Installation instructions are provided, too.

CASA *Pre-releases* are code under development. Use with caution as the code is still undergoing changes, is less tested and not well documented.

Package sizes vary between 0.4-1.1GB.

	CASA		Pipelines	
CASA	CASA Release 4.7.2	CASA Pre-releases	ALMA 4.7.0-1	VLA 4.7.2
Linux Packages				Installation
Red Hat 7		•	•	•
Red Hat 6		•	•	•
Mac OS X Packages				Installation
OS X 10.11 (El Capitan)		•		•
OS X 10.10 (Yosemite)				





Two ways to run CASA tasks

```
CASA <12>: help(importfits)
Help on importfits task:
Convert an image FITS file into a CASA image
```

Scripting interface

importfits(fitsimage='ngc3256.fits', imagename='ngc3256.im', overwrite=True)





Two ways to run CASA tasks

Tasking interface

```
CASA <16>: default(importfits) or
   CASA <14>: tget(importfits)
   Restored parameters from file importfits.last
CASA <17>: inp
----> inp()
# importfits :: Convert an image FITS file into a CASA image
fitsimage
                                    # Name of input image FITS file
imagename
                                   # Name of output CASA image
whichrep
                           0
                                      If fits image has multiple coordinate
                                       reps, choose one.
    CASA <19>: fitsimage='test.fits'
    CASA <20>: go()
    Executing: importfits()
```



Overview of ALMA simulation:

Simobserve

Provide an input "model" and specify a telescope/configuration used for the observations. Provide parameters like source position, integration time, and noise. Simobserve can then generate mock visibility data (measurement set ".ms").

```
CASA <2>: help(simobserve)
Help on simobserve task:
```

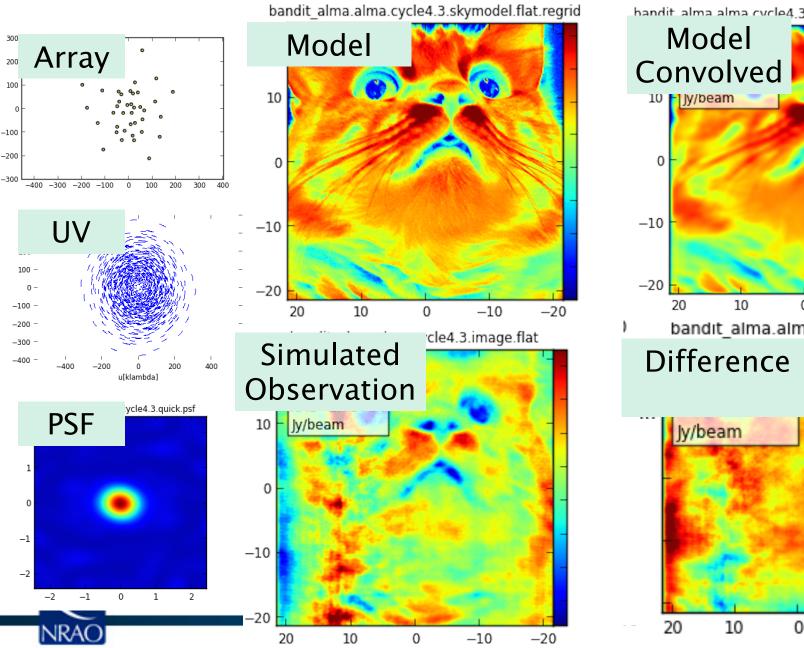
Simanalyze

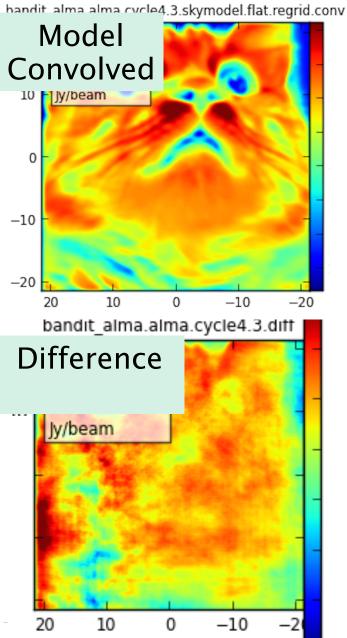
"Clean" the visibility data generated from Simbobserve using CASA's clean task. It also calculates the differences between simulated observations and the original model data.

```
CASA <4>: help(simanalyze)
Help on simanalyze task:
```



Overview of ALMA simulation:







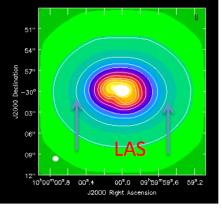
Purpose of simulation:

- Check the fidelity of image (more important in the earlier cycles).
- Demonstrate how well you can recover the flux. Help the reviewer to visualize the expected outcome.
- Properly fit models to your data (e.g., fitting in the uv plane).

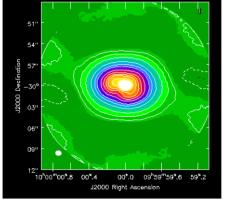
• Others?

Images using 12-m C2 array with a resolution of 0.8"x0.7" in pa 80d

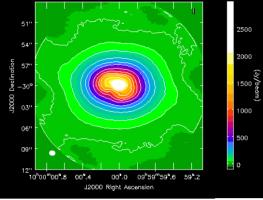
MODEL 12-m image 12m+7m Image







7000 Jy



9000 Jy

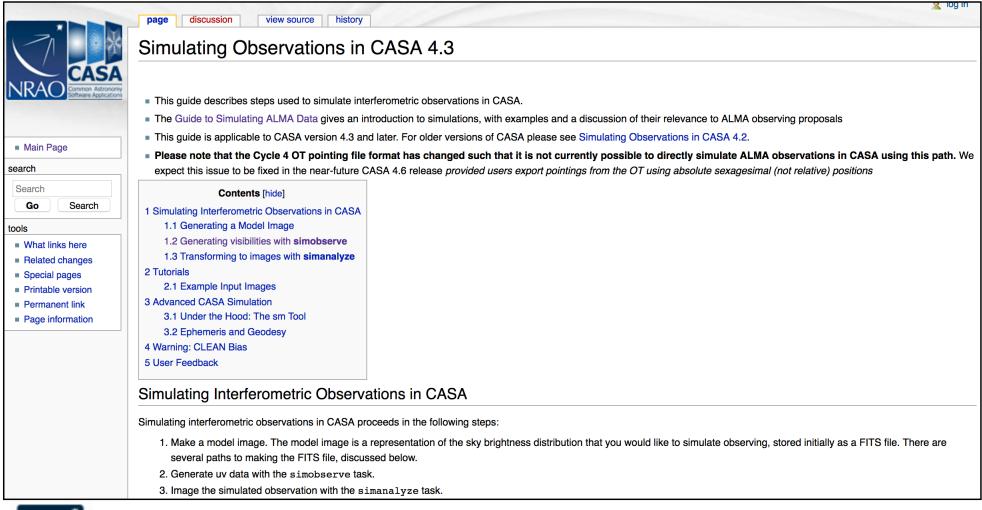
Primary beam corrected: 20% cutoff: Contours: -20,20,50,100,200,300,400,600,800,1000,1200,1600,2000





ALMA simulation tutorial:

https://casaguides.nrao.edu/index.php/Simulating_Observations_in_CASA_4.3







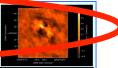
ALMA simulation tutorial:

https://casaguides.nrao.edu/index.php/Simulating_Observations_in_CASA_4.3

Tutorials

Simulation Guide for New Users (CASA 4.3)

A fully annotated tutorial that uses a Spitzer SAGE 8 micron continuum image of 30 Doradus and scales it to greater distance. A good place for new users to start



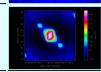
Protoplanetary Disk Simulation (CASA 4.3)

A sky model with a lightly annotated script that simulates a protoplanetary disk. Uses a theoretical model of dust continuum from Sebastian Wolff, scaled to the distance of a nearby star. This is another fairly generic simulation - if you're short on time, you probably don't need to go through this one and the New Users guide, but it can be useful to go through multiple examples.



Simulation Guide Component Lists (CASA 4.3)

Tutorial for simulating data based on multiple sources (using both a FITS image and a component list). If you are interested in simulating from a list of simple sources (point, Gaussian, disk), rather than or in addition to a sky model image, then read the considerations here.



Einstein-Face (CASA 4.3)

A sky model and lightly annotated script that simulates the face of Einstein as seen by ALMA. This simulation is particularly useful for those who wish to better understand spatial filtering by an interferometer, but doesn't demonstrate new capabilities of the simulation tasks beyond those described above.



ACA Simulation (CASA 4.3)

A tutorial for simulating ALMA observations that use multiple configurations or use the 12-meter array in combination with the ALMA Compact Array. This tutorial demonstrates combining data from each ALMA component "by hand". This guide is of particular interest to those wishing to explore using the 12-m array in combination with the ACA, and those interested in combining data from multiple 12-m array configurations.



Simalma (CASA 4.3)

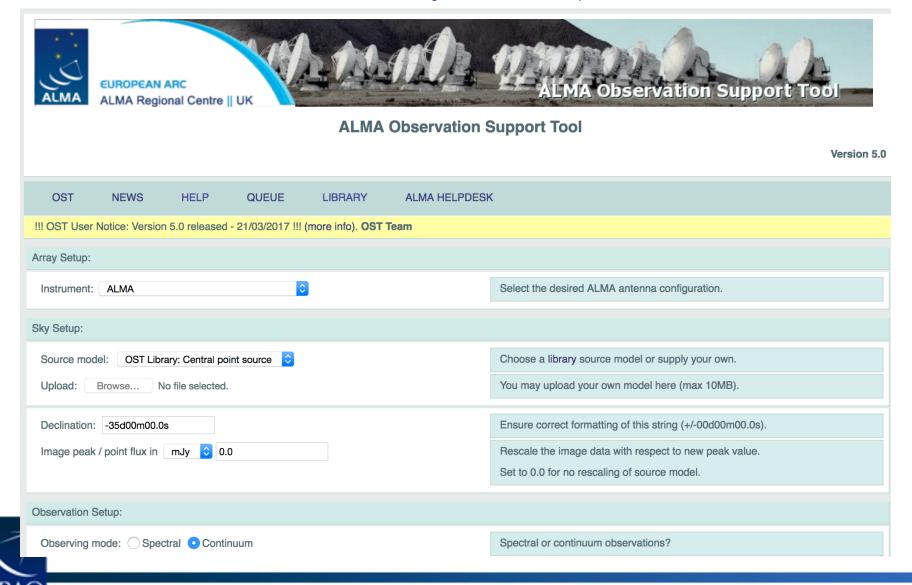
This tutorial demonstrates how to use **simalma**, a task that simplifies simulations that include the main 12-m array plus the ACA. Like the previous guide, this one is of particular interest to those wishing to explore multi-component ALMA observations.







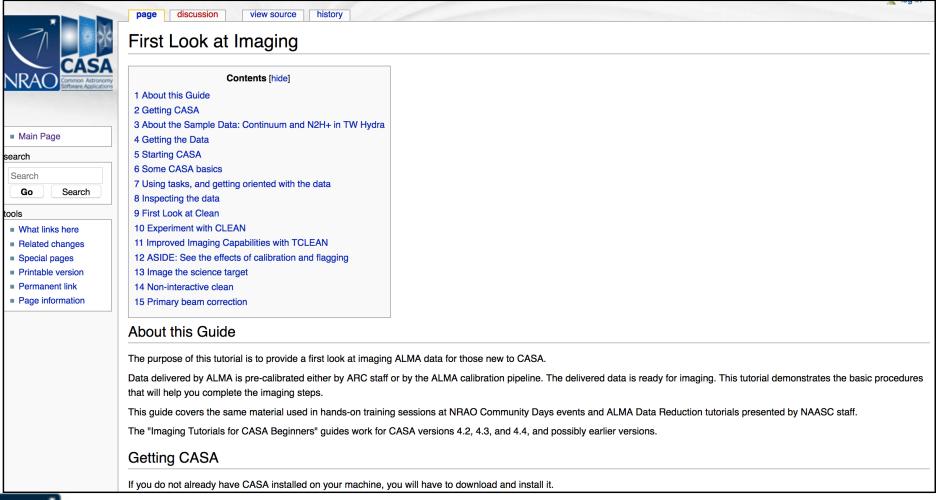
A web-based simulation tool: http://almaost.jb.man.ac.uk/





Overview of Clean:

https://casaguides.nrao.edu/index.php/First_Look_at_Imaging





From Sky Brightness to Visibility

- 1. An interferometer measures the interference pattern observed by pairs of apertures
- 2. The interference pattern is directly related to the source brightness. In particular, for small fields of view the complex visibility, V(u,v), is the 2D Fourier transform of the brightness on the sky, T(x,y)

(van Cittert-Zernike theorem)

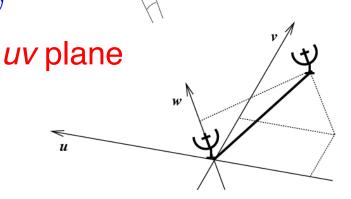
Fourier space/domain

$$V(u,v) = \int \int T(x,y)e^{2\pi i(ux+vy)}dxdy$$

$$T(x,y) = \int \int V(u,v)e^{-2\pi i(ux+vy)}dudv$$

Image space/domain



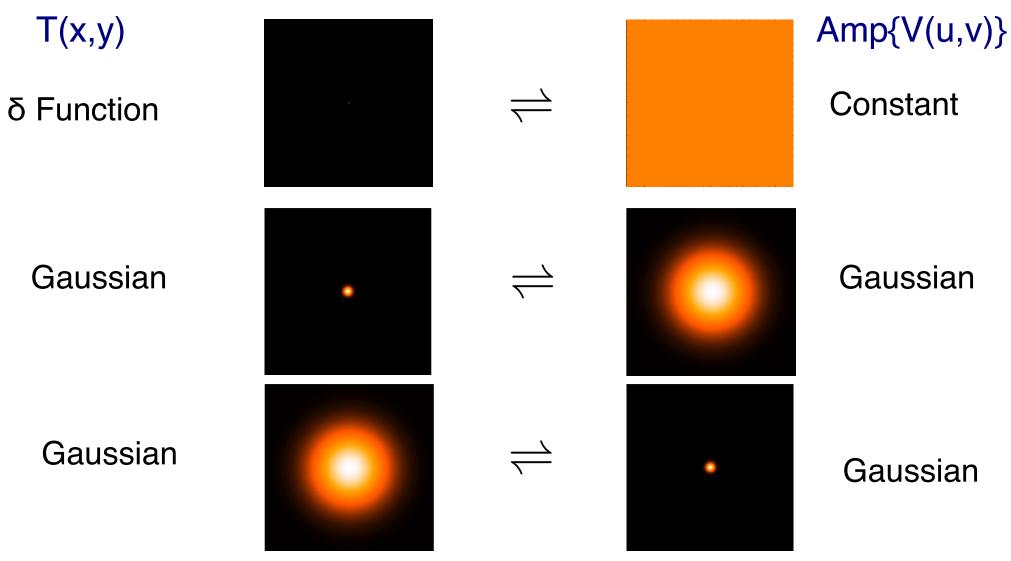


T(x,y)

N Pole

image plane

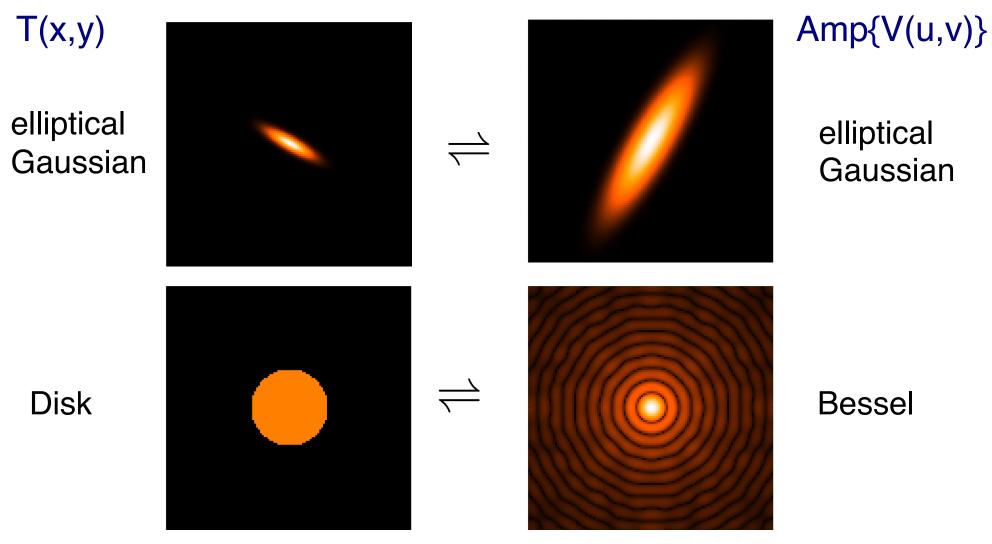
Some 2D Fourier Transform Pairs





narrow features transform to wide features (and vice-versa)

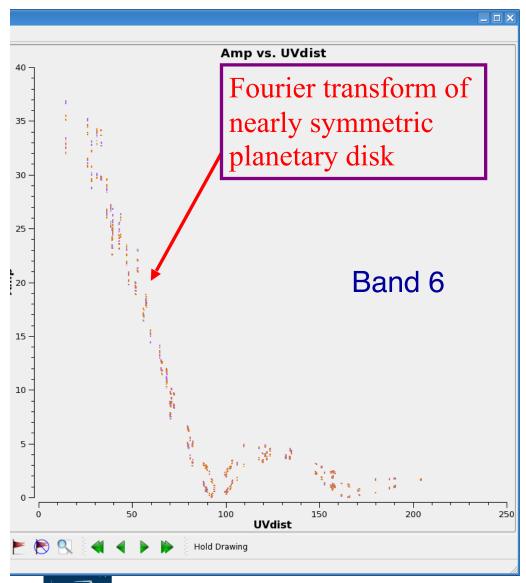
More 2D Fourier Transform Pairs

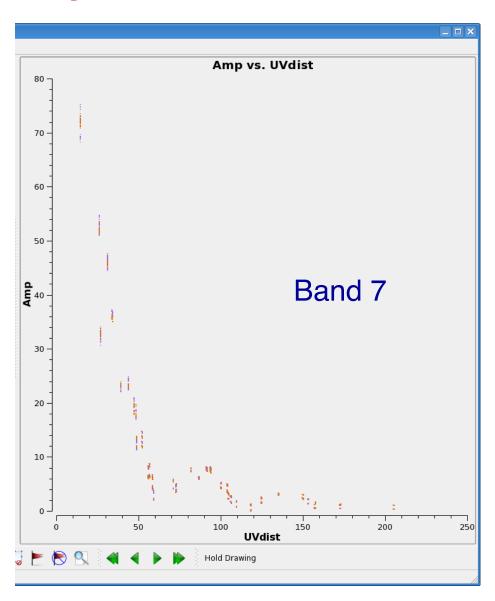




sharp edges result in many high spatial frequencies (sinc function, "ringing", Gibbs phenomenon)

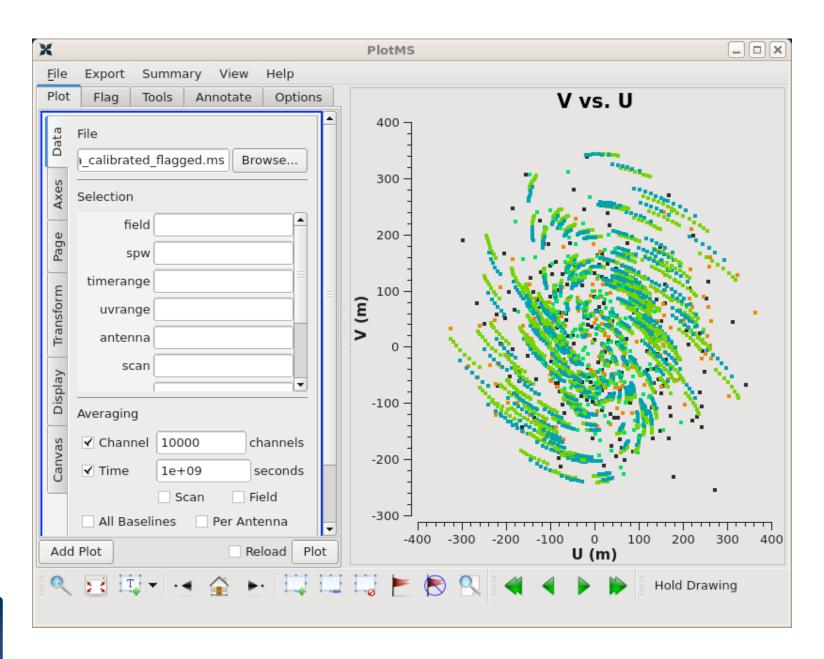
ALMA observes planetary disk







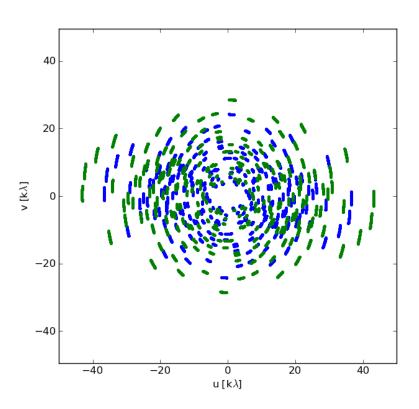
Plotms: Versatile examination of UV data

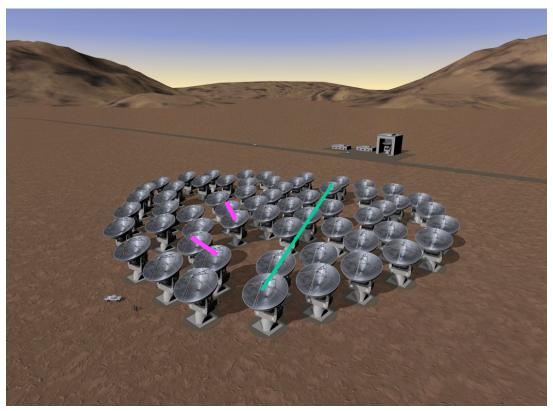




Sampling Function

Interferometers cannot see the entire Fourier/uv domain. But each antenna pair samples one spot: → imperfect image





Small uv-distance: short baselines (measure extended emission) Long uv-distance: long baselines (measure small scale emission) Orientation of baseline also determines orientation in the uv-plane Each visibility has a phase and an amplitude

Dirty Images from a Dirty Beam

We sample the Fourier domain at discrete points

$$B(u,v) = \sum_{k} (u_k, v_k)$$

The inverse Fourier Transform is

$$T^{D}(x,y) = FT^{-1}\{B(u,v) \times V(u,v)\}$$

The convolution theorem tells us

$$T^D(x,y) = b(x,y) \otimes T(x,y)$$

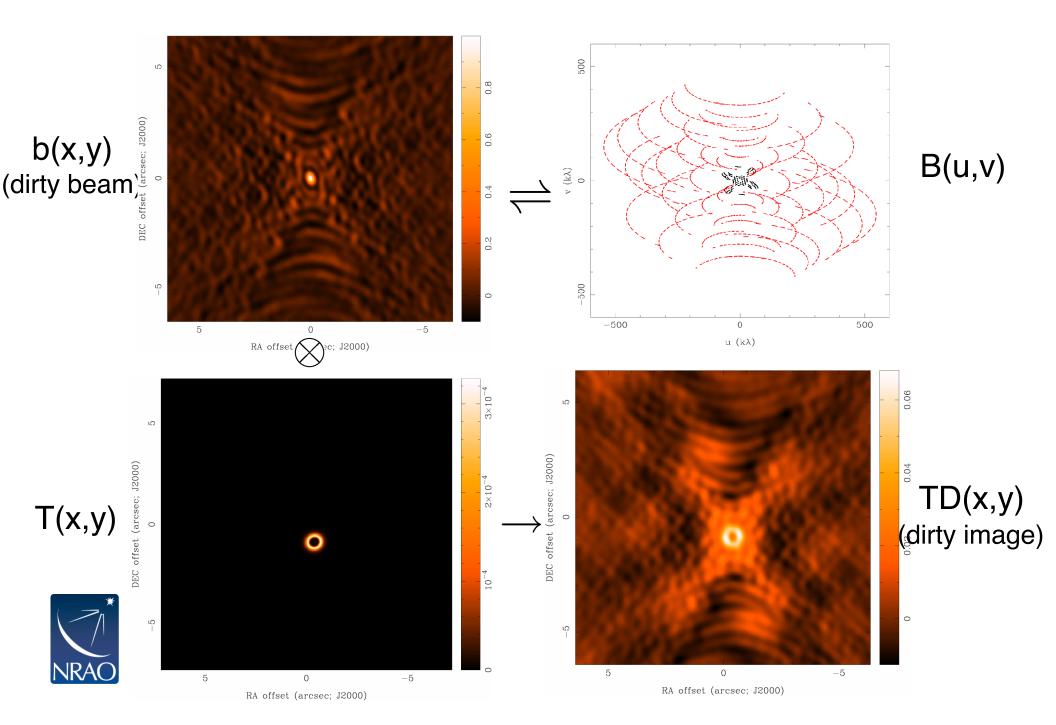
Where the point spread function is

$$b(x,y) = FT^{-1}\{B(u,v)\}\$$

- Fourier transform of sampled visibilities yields the true sky brightness convolved with the point spread function ("dirty beam")
- The "dirty image" is the true image convolved with the "dirty beam"



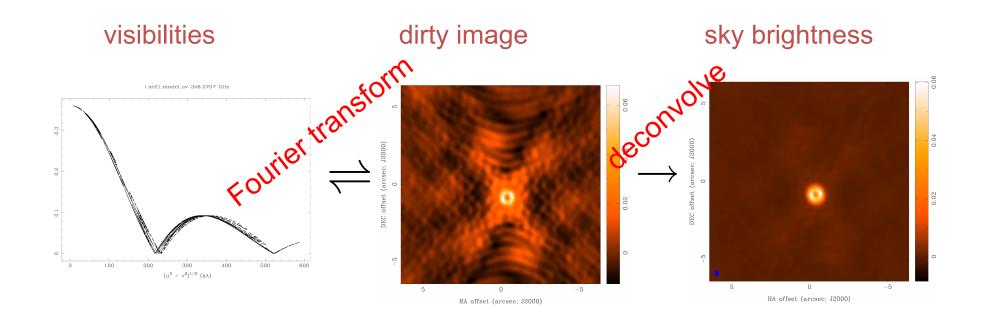
Dirty Beam and Dirty Image



How to analyze (imperfect) interferometer data

Image plane analysis

- dirty image TD(x,y) = Fourier transform { V(u,v) }
- deconvolve b(x,y) from TD(x,y) to determine (model of) T(x,y)

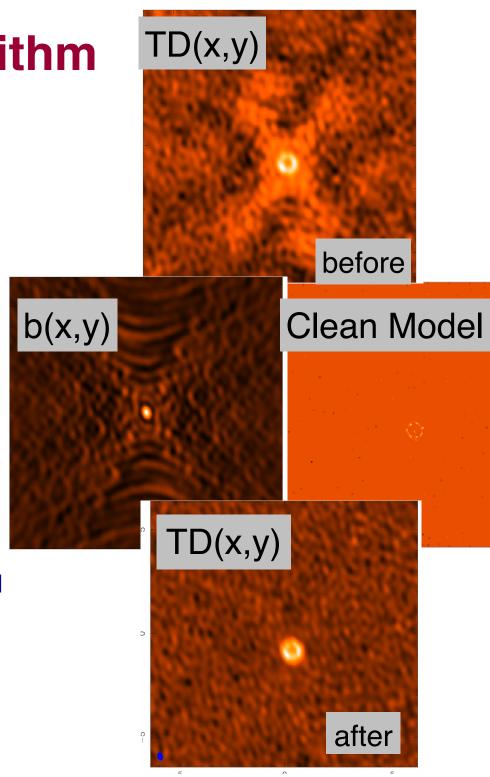




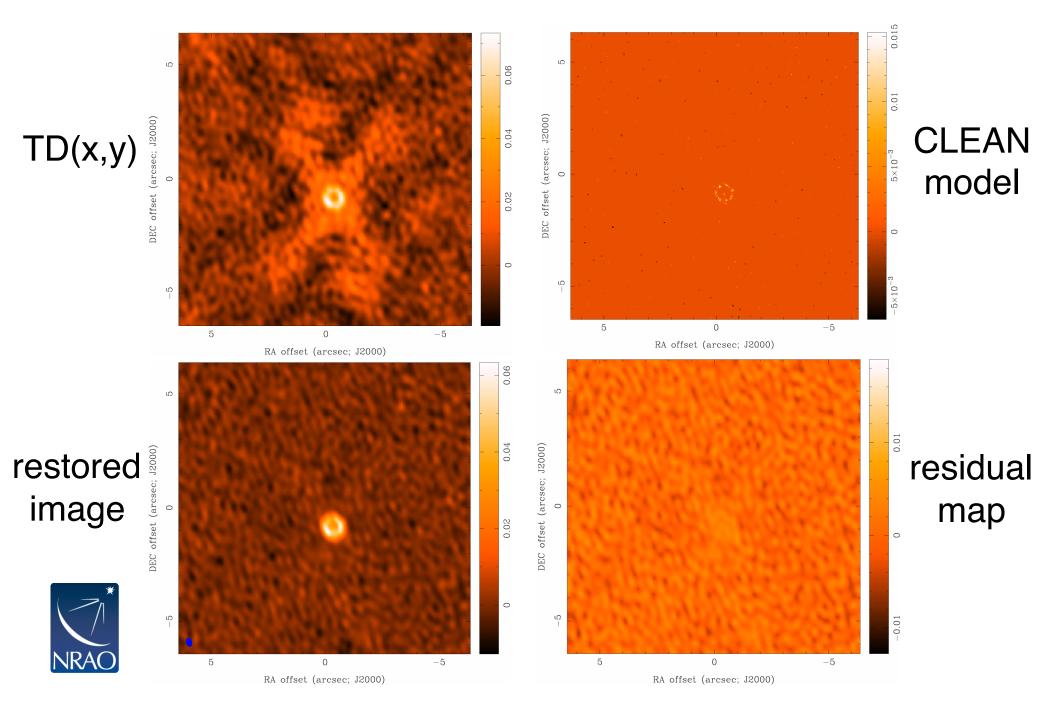
Basic CLEAN Algorithm

- A. Initialize a *residual* map to the dirty map
 - 1. Start loop
 - 2. Identify strongest feature in *residual* map as a point source
 - 3. Add this point source to the clean component list
 - 4. Convolve the point source with b(x,y) and subtract a fraction g (the loop gain) of that from *residual* map
 - 5. If stopping criteria not reached, do next iteration
- B. Convolve Clean component (cc) list by an estimate of the main lobe of the dirty beam (the "Clean beam") and add residual map to make the final "restored" image





CLEAN



CLEAN in CASA:

```
CASA <3>: inp clean
----> inp(clean)
# clean :: Invert and deconvolve images with selected algorithm
                                        # Name of input visibility file
                              . .
imagename
                                           Pre-name of output images
outlierfile
                                           Text file with image names, sizes, centers for
                                           outliers
field
                                          Field Name or id
                              1.1
SDW
                                          Spectral windows e.g. '0~3', '' is all
selectdata
                            True
                                           Other data selection parameters
    timerange
                                           Range of time to select from data
                                        # Select data within uvrange
    uvrange
                                        # Select data based on antenna/baseline
    antenna
                                        # Scan number range
    scan
    observation
                                          Observation ID range
                                          Scan Intent(s)
    intent
mode
                           'mfs'
                                           Spectral gridding type (mfs, channel, velocity,
                                            frequency)
gridmode
                                           Gridding kernel for FFT-based transforms,
                                            default='' None
niter
                             500
                                           Maximum number of iterations
                             0.1
gain
                                           Loop gain for cleaning
threshold
                        '0.0mJy'
                                           Flux level to stop cleaning, must include
                                            units: '1.0mJy'
psfmode
                         'clark'
                                           Method of PSF calculation to use during minor
                                            cycles
imagermode
                       'csclean'
                                           Options: 'csclean' or 'mosaic', '', uses
                                            psfmode
    cyclefactor
                                           Controls how often major cycles are done. (e.g.
                             1.5
                                            5 for frequently)
                              - 1
                                           Cycle threshold doubles in this number of
    cyclespeedup
                                            iterations
multiscale
                              []
                                           Deconvolution scales (pixels); [] = standard
interactive
                           False
                                           Use interactive clean (with GUI viewer)
mask
                                           Cleanbox(es), mask image(s), region(s), or a
                              [1
                                            level
imsize
                    = [256, 256]
                                           x and y image size in pixels. Single value:
                                            same for both
cell
                    = ['1.0arcsec']
                                           x and y cell size(s). Default unit arcsec.
phasecenter
                                           Image center: direction or field index
restfreq
                                           Rest frequency to assign to image (see help)
                                           Stokes params to image (eg I,IV,IQ,IQUV)
stokes
weighting
                       'natural'
                                           Weighting of uv (natural, uniform, briggs, ...)
                                           Apply additional uv tapering of visibilities
uvtaper
                           False
modelimage
                                           Name of model image(s) to initialize cleaning
                            ['']
restoringbeam
                                           Output Gaussian restoring beam for CLEAN image
                           False
                                           Output primary beam-corrected image
pbcor
minpb
                             0.2
                                        # Minimum PB level to use
usescratch
                           False
                                        # True if to save model visibilities in
                                            MODEL DATA column
                           False
                                        # Divide large image cubes into channel chunks
allowchunk
                                          for deconvolution
```

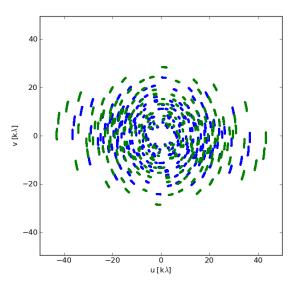


Dirty Beam Shape and Weighting

- · Each visibility point is given a weight in the imaging step
- First piece: weight given by Tsys, integration time, etc.

Natural

- Each sample is given the same weight
- There are many samples at short baselines, so natural weighting will give the largest beam and the best surface brightness sensitivity (and sometimes pronounced wings in the dirty beam)

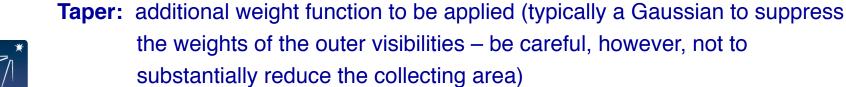


Uniform

- each visibility is given a weight inversely proportional to the sample density
- Weighs down short baselines, long baselines are more pronounced. Best resolution; poorer noise characteristics

Briggs (Robust)

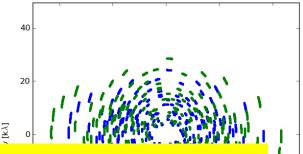
- A graduated scheme using the parameter robust; compromise of noise and resolution
- In CASA, set robust from -2 (~ uniform) to +2 (~ natural)
- robust = 0 often a good choice





Dirty Beam Shape and Weighting

- · Each visibility point is given a weight in the imaging step
- First piece: weight given by Tsys, integration time, etc.
- Natural
 - Each sample is given the same weight



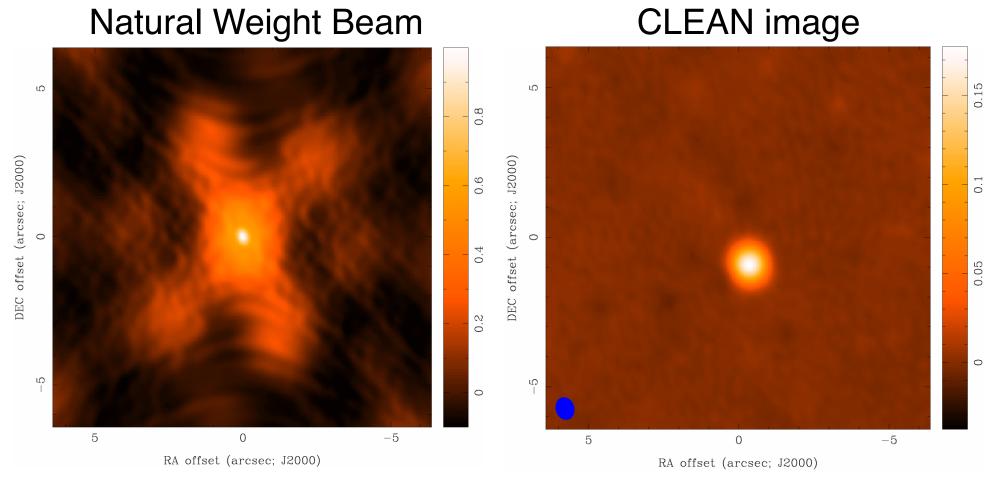
It is possible to create different images based on the *same* visibility datasets.

- . Adjust the weighting to match your science goal:
 - * Detection experiment/weak extended source: natural (maybe even with a taper)
 - * Finer detail of strong sources: robust or even uniform



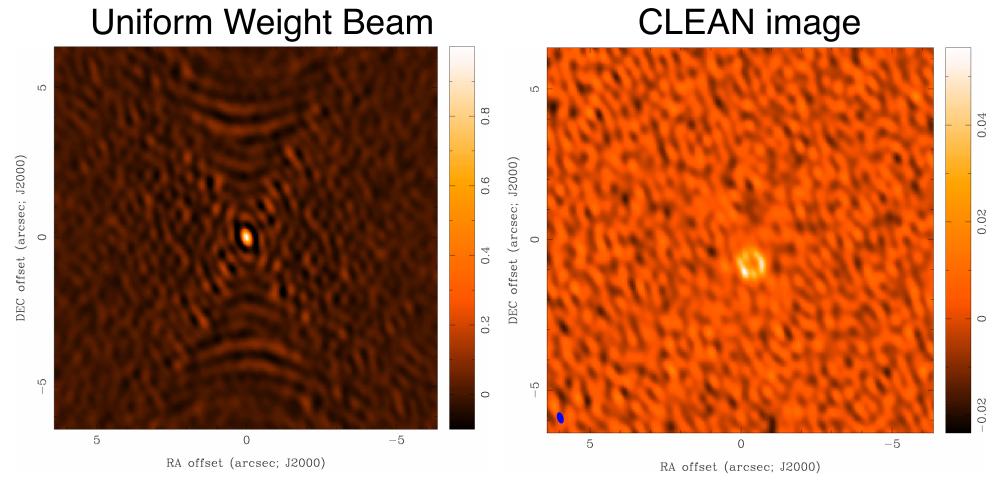
Taper: additional weight function to be applied (typically a Gaussian to suppress the weights of the outer visibilities – be careful, however, not to substantially reduce the collecting area)

Imaging Results



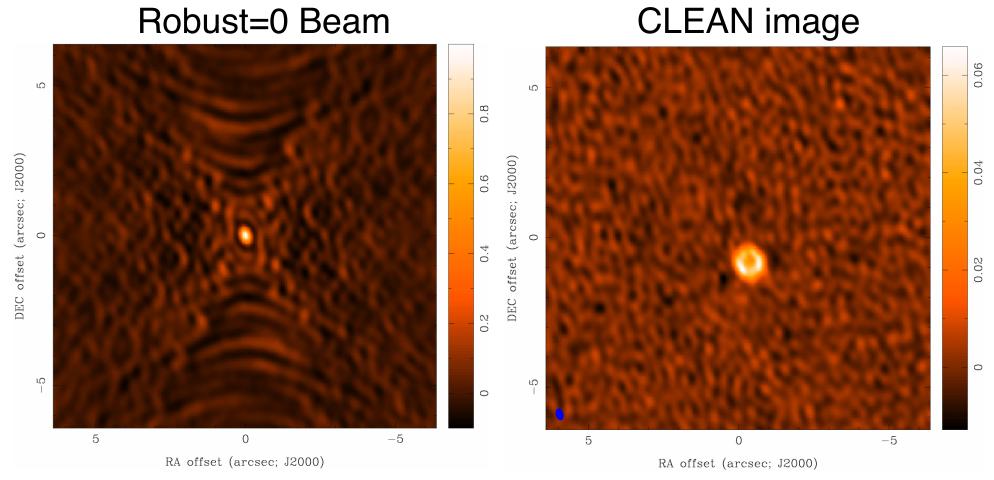


Imaging Results





Imaging Results





Output of CLEAN

Minimally:

my_image.flux
 Relative sky sensitivity

my_image.image Cleaned and restored image (Jy/clean beam)

my_image.maskClean "boxes"

my_image.model Clean components (Jy/pixel)

my_image.psfDirty beam

my_image.residual Residual (Jy/dirty beam)

If CLEAN is started again with same image name, it will try to continue deconvolution from where it left off. Make sure this is what you want. If not, give a new name or remove existing files with rmtables('my_image.*')

Also: try NOT to do CTRL+C as it could corrupt your MS when it touches the visibilities in a major cycle.



Coming in Cycle 5: TCLEAN will replace CLEAN

Why replace clean? Clean has become difficult to maintain, trace down issues, and most importantly to extend to new capabilities, like combining different algorithms together and parallelizing the code efficiently.

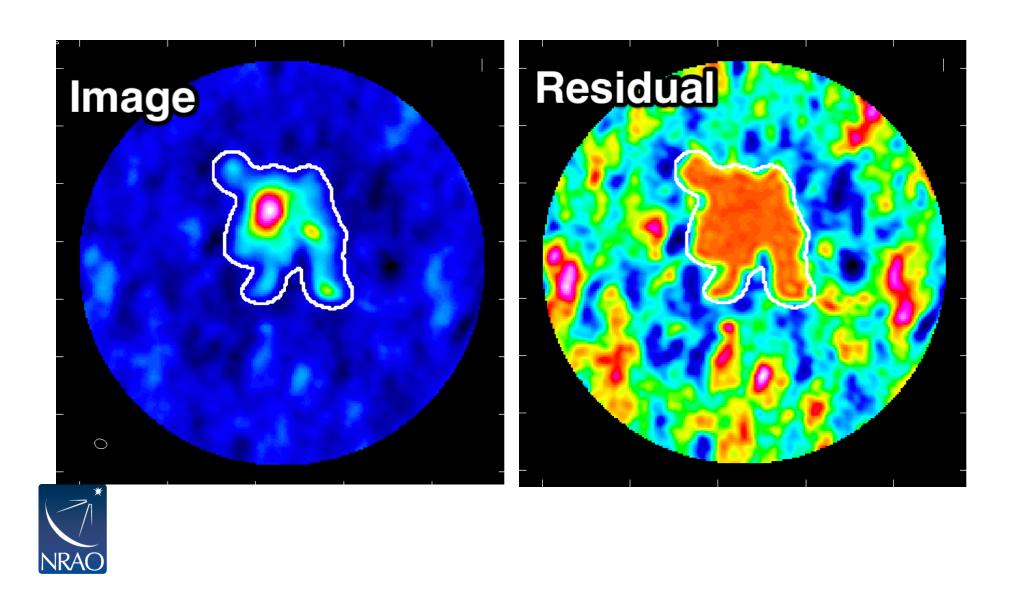
Benefits of TCLEAN:

- A more straightforward interface that is more logical, usable and reliable to the users including significant improvements to the logging output and has been made much more homogeneous across algorithms.
- more combinations of imaging algorithms most important of these for ALMA is the ability to account for spatial spectral index variations (nterms >1) for mosaics.
- Includes algorithms for autoboxing refactored code has simplified development of a fully integrated autoboxing capability (available for the first time in CASA 5.0, and for deployment in the pipeline for CASA 5.1, Cycle 5)
- Add significant improvements in divergence checks for safeguarding against divergence in the cleaning process



Coming in Cycle 5: TCLEAN

Also included in TCLEAN: Robust Autoboxing algorithms!



Coming in Cycle 5: TCLEAN

Should I use CLEAN or TCLEAN?

As we transition from clean to tclean, we will be updating all the relevant documentation including the CASA Guides, Scripts and Tutorials... Etc.

The ALMA Imaging Pipeline uses tclean and calls to tclean are in all the pipeline "hif_" routines.

So we strongly advise people that tclean should start to be used especially as we are getting closer to Cycle 5. There will be no further development or bug fixes in clean!



Coming in Cycle 5: TCLEAN

TCLEAN also offers a more straightforward user interface inside CASA and clearer logging output

Example Syntax Changes:

clean	tclean		
mode	specmode		
resmooth=True	restoringbeam='common'		
minpb	pblimit		
gridmode, imagermode	gridder		
psfmode	deconvolver		
modelimage	startmodel		
.flux (output)	.pb (output)		

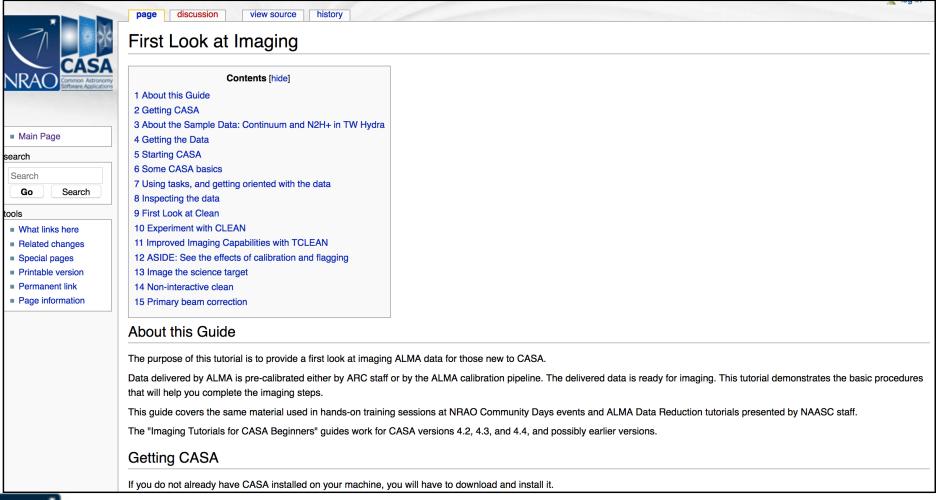
Major syntax and usage changes from clean → tclean are summarized here: https://casaguides.nrao.edu/index.php/TCLEAN_and_ALMA





Overview of Clean:

https://casaguides.nrao.edu/index.php/First_Look_at_Imaging







Small group work:

Suggested timeline:

(5 mins) Share your working goals with your teammates. (until ~4:20 pm) work individually, discuss with teammates. (10 mins) Wrap up, share your achievements with teammates.

Group 2: Group 1: Group 3: Group 4: Brendan Andrew Kristy Caprice Laurence **Jackie** Nathan Peter **Patrick** Meghana Rachael Richard Rebecca Intae Sam Yao-Lun **Taylor** Sydney





ALMA simulation tutorial:

https://casaguides.nrao.edu/index.php/ Simulating_Observations_in_CASA_4.3

ALMA imaging tutorial:

https://casaguides.nrao.edu/index.php/First_Look_at_Imaging

TCLEAN syntax:

https://casaguides.nrao.edu/index.php/TCLEAN_and_ALMA







For more info:

http://www.almaobservatory.org

The Atacama Large Millimeter/submillimeter Array (ALMA), an international astronomy facility, is a partnership of the European Organisation for Astronomical Research in the Southern Hemisphere (ESO), the U.S. National Science Foundation (NSF) and the National Institutes of Natural Sciences (NINS) of Japan in cooperation with the Republic of Chile. ALMA is funded by ESO on behalf of its Member States, by NSF in cooperation with the National Research Council of Canada (NRC) and the National Science Council of Taiwan (NSC) and by NINS in cooperation with the Academia Sinica (AS) in Taiwan and the Korea Astronomy and Space Science Institute (KASI). ALMA construction and operations are led by ESO on behalf of its Member States; by the National Radio Astronomy Observatory (NRAO), managed by Associated Universities, Inc. (AUI), on behalf of North America; and by the National Astronomical Observatory of Japan (NAOJ) on behalf of East Asia. The Joint ALMA Observatory (JAO) provides the unified leadership and management of the construction, commissioning and operation of ALMA.

