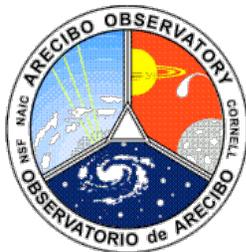


Combining Interferometric and Single Dish Data



NAIC/NRAO Single Dish School on Radio Astronomy 2011

Juergen Ott



The Need for Interferometry

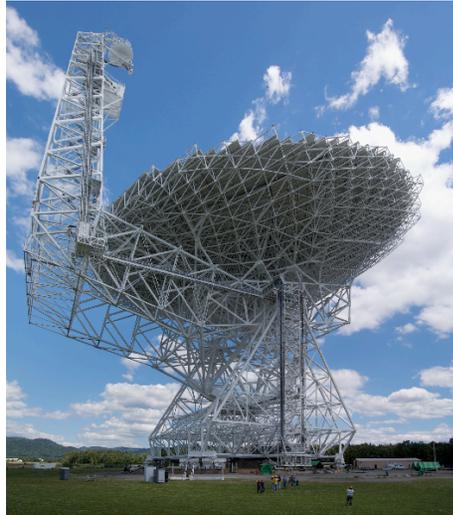
The resolution of a telescope depends on the wavelength and its diameter

$$\theta \sim \lambda/D$$

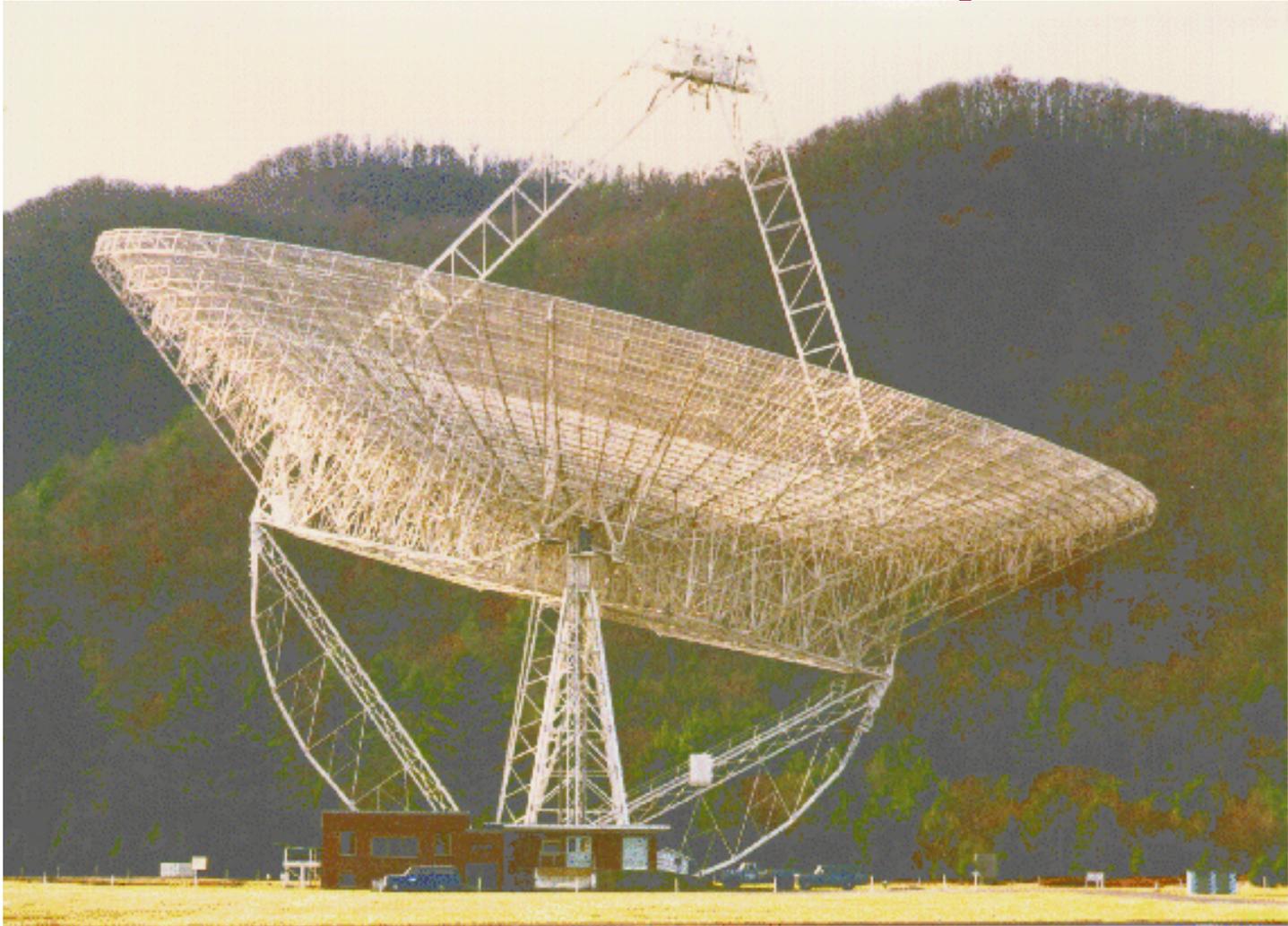
Solution (I) build larger telescopes!



The Need for Interferometry



The Need for Interferometry



The Need for Interferometry



The Need for Interferometry

Prize Time !!!



The Need for Interferometry



The Need for Interferometry

The resolution of a telescope depends on the wavelength and its diameter

$$\Theta \sim \lambda/D$$

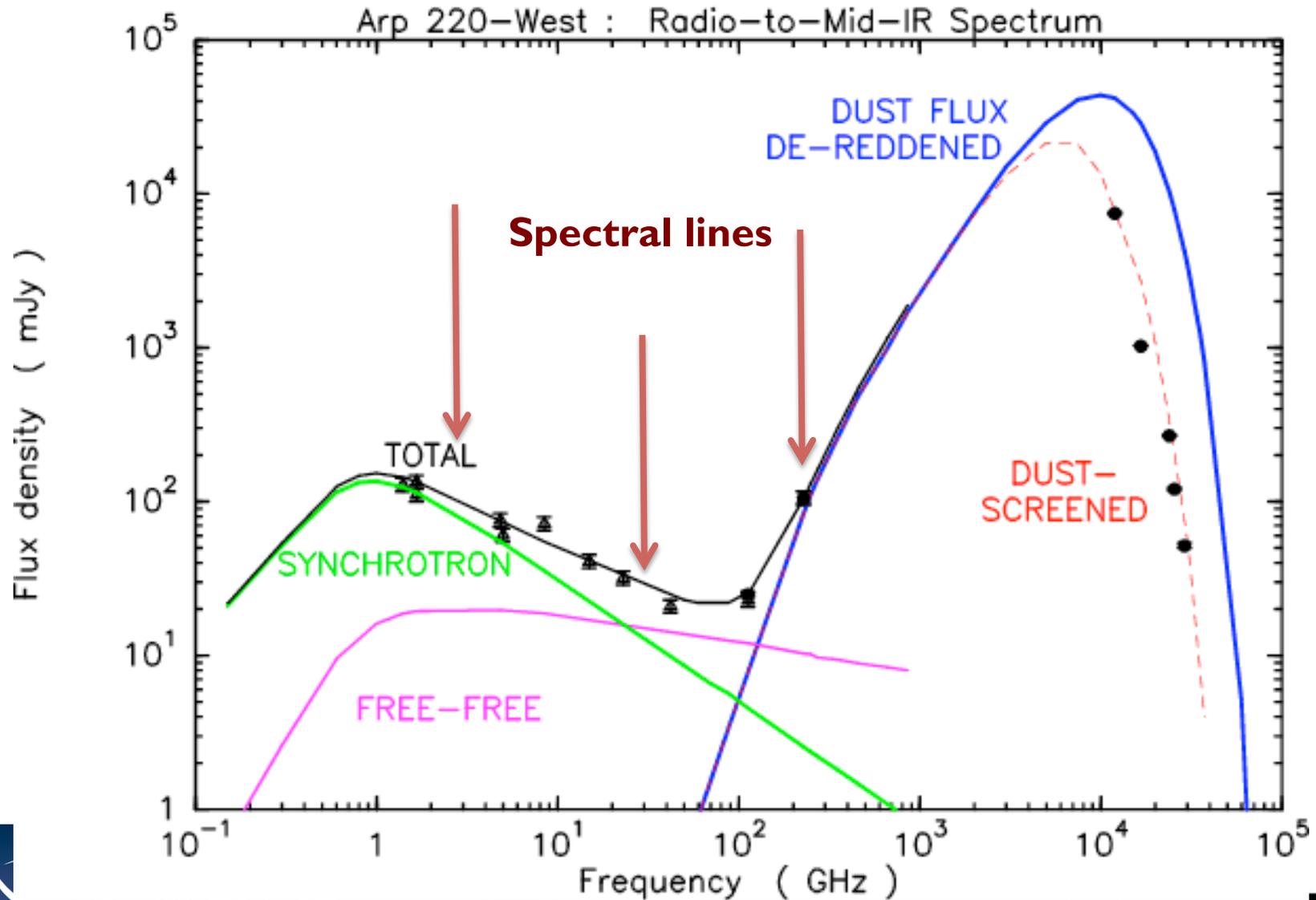
Solution (1) build larger telescopes!

But telescopes are substantial structures and there are engineering, physical and monetary limits

Solution (2) go to smaller wavelengths!



The Need for Interferometry



The Need for Interferometry

The resolution of a telescope depends on the wavelength and its diameter

$$\theta \sim \lambda/D$$

Solution (1) build larger telescopes!

But telescopes are substantial structures and there are engineering, physical and monetary limits

Solution (2) go to smaller wavelengths!

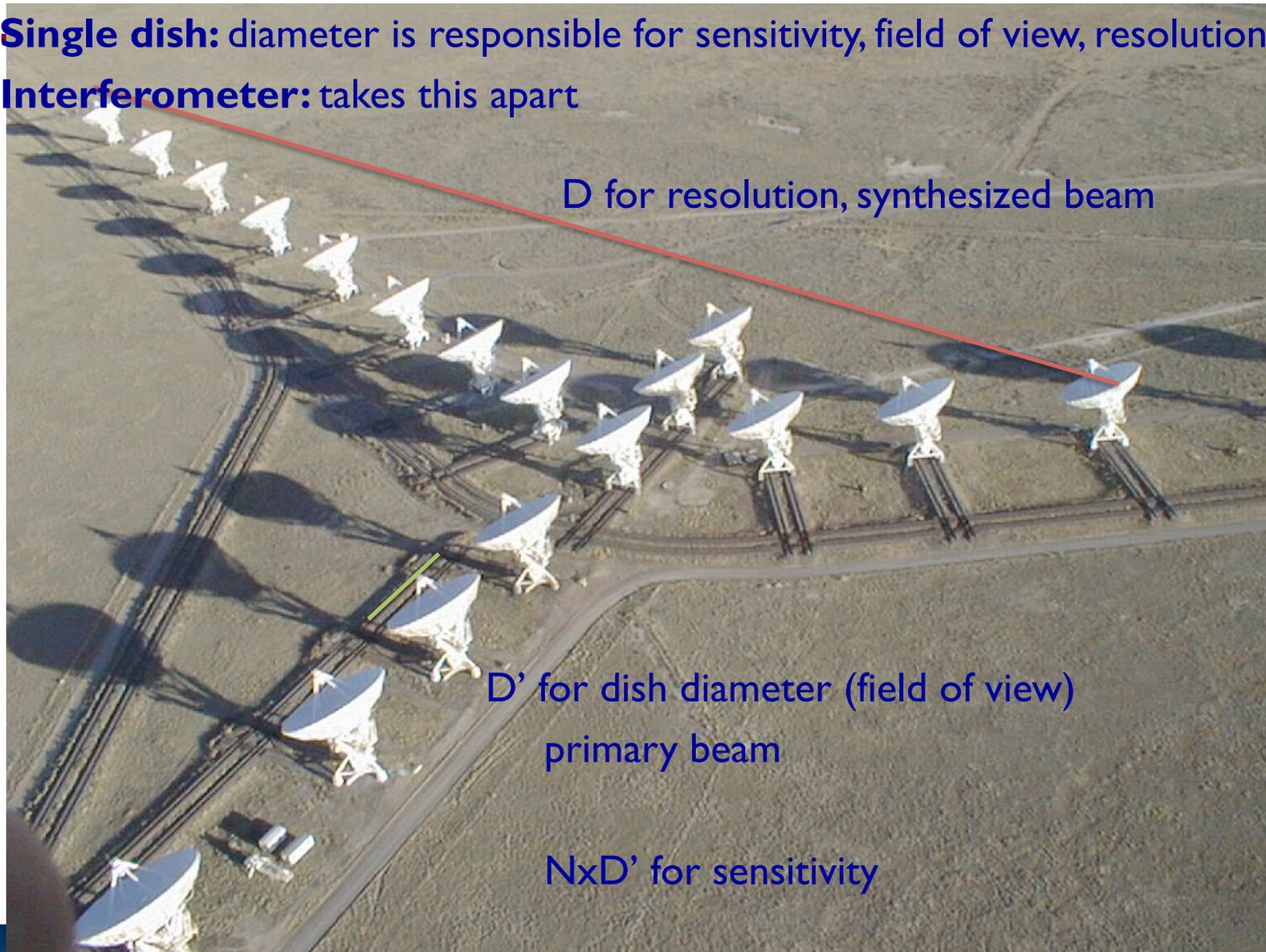
Ok, for some applications but the strength of the continuum changes, as well as the physics of the emission mechanisms. No way to change the frequency when one is after specific spectral lines

Solution (3) interferometry!

Cheat when building a telescope, build many and use Fourier Optics theorems



Single dish: diameter is responsible for sensitivity, field of view, resolution
Interferometer: takes this apart



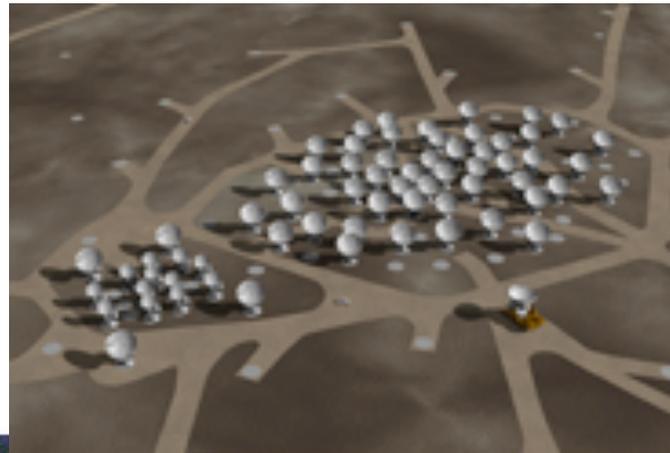
D for resolution, synthesized beam

D' for dish diameter (field of view)
primary beam

$N \times D'$ for sensitivity



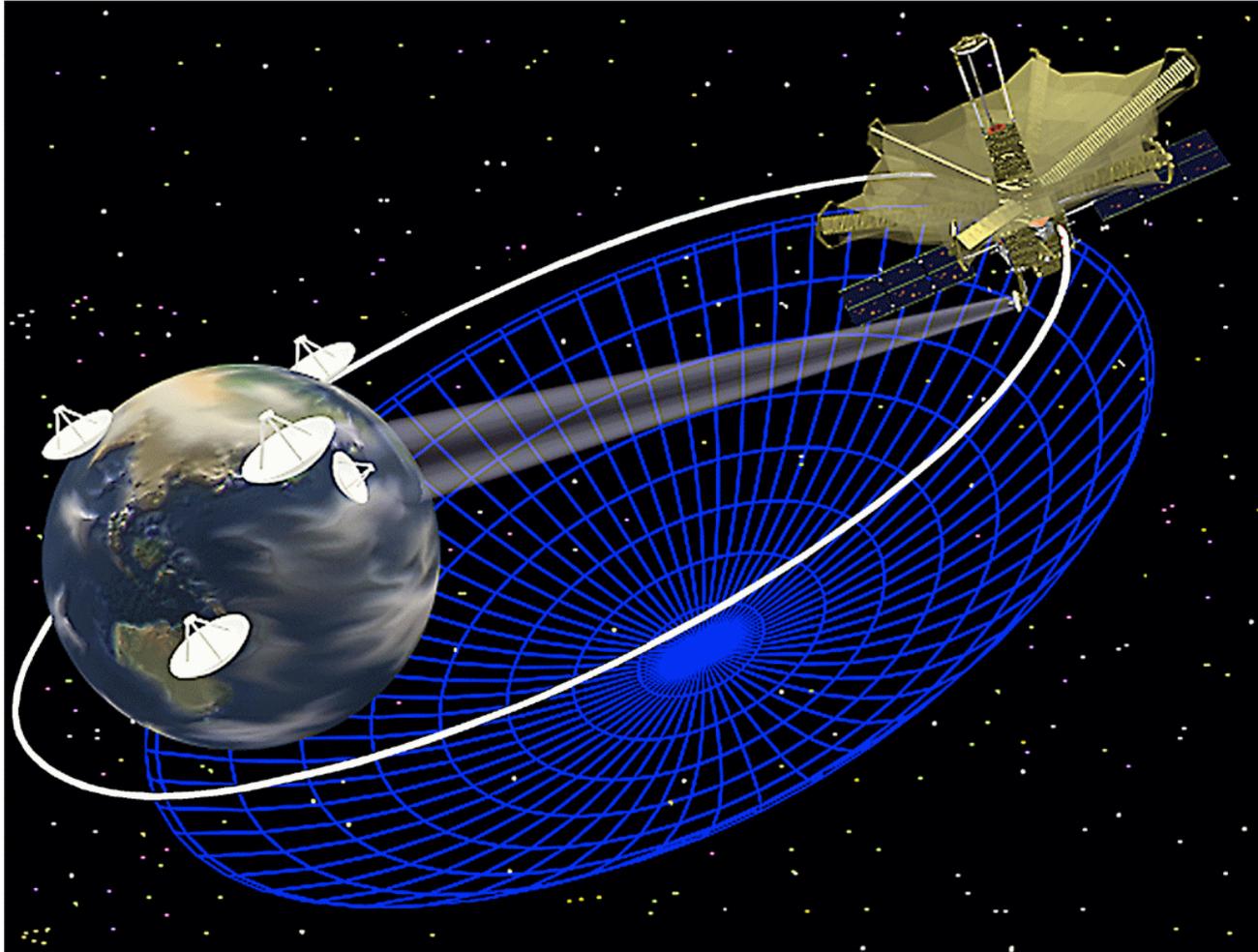
The Need for Interferometry



The Need for Interferometry



The Need for Interferometry

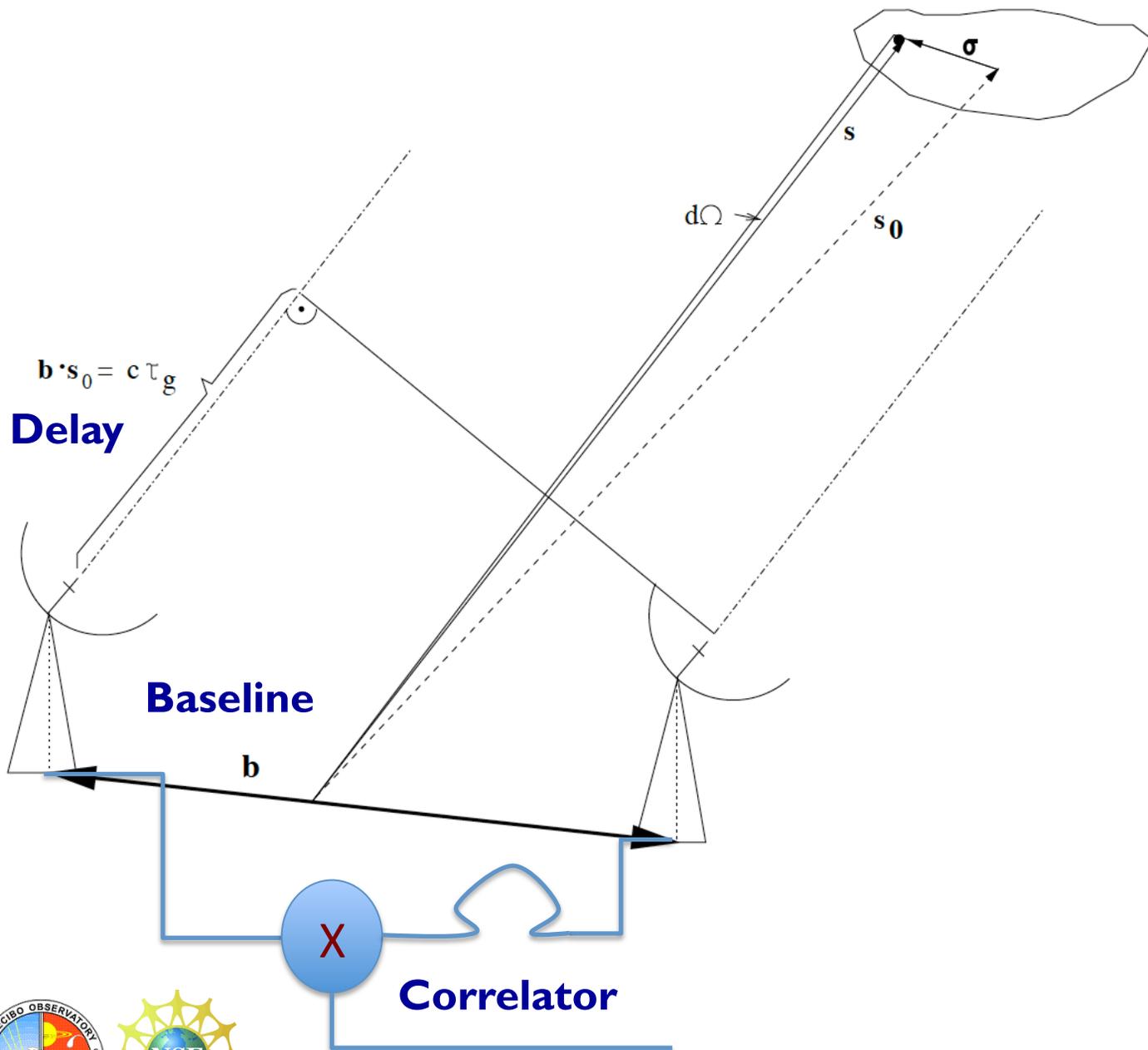


Interferometry

Interferometry decouples the aperture properties of a single dish

- The **sensitivity** is given by the number of antennas times their area
- The **resolution** is given by the largest distance of antennas (synthesized beam)
- The **field of view** is given by the beam of a single antenna (corresponding to the single dish resolution; primary beam)
- The **largest angular scale** that can be imaged is given by the shortest distance of antennas





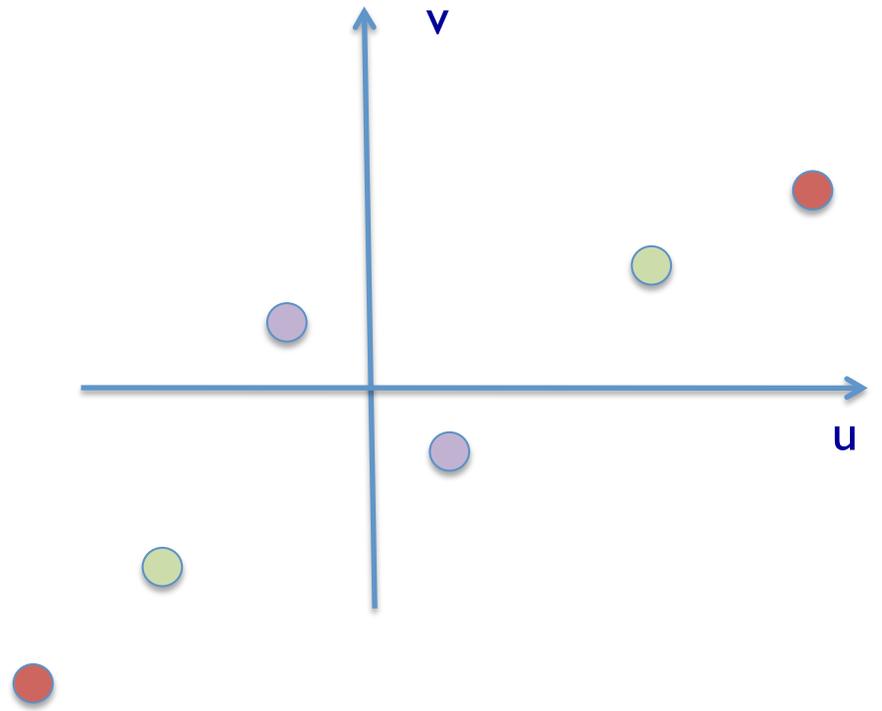
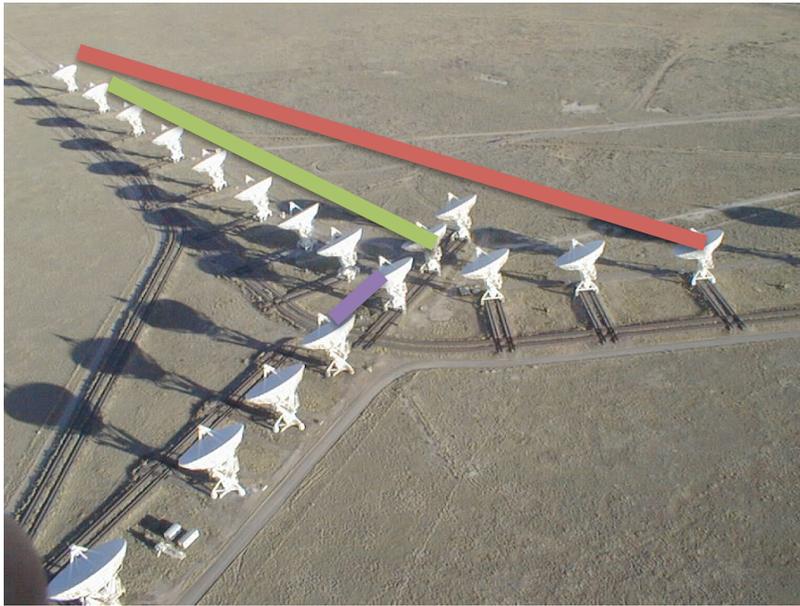
Correlator

Interferometry

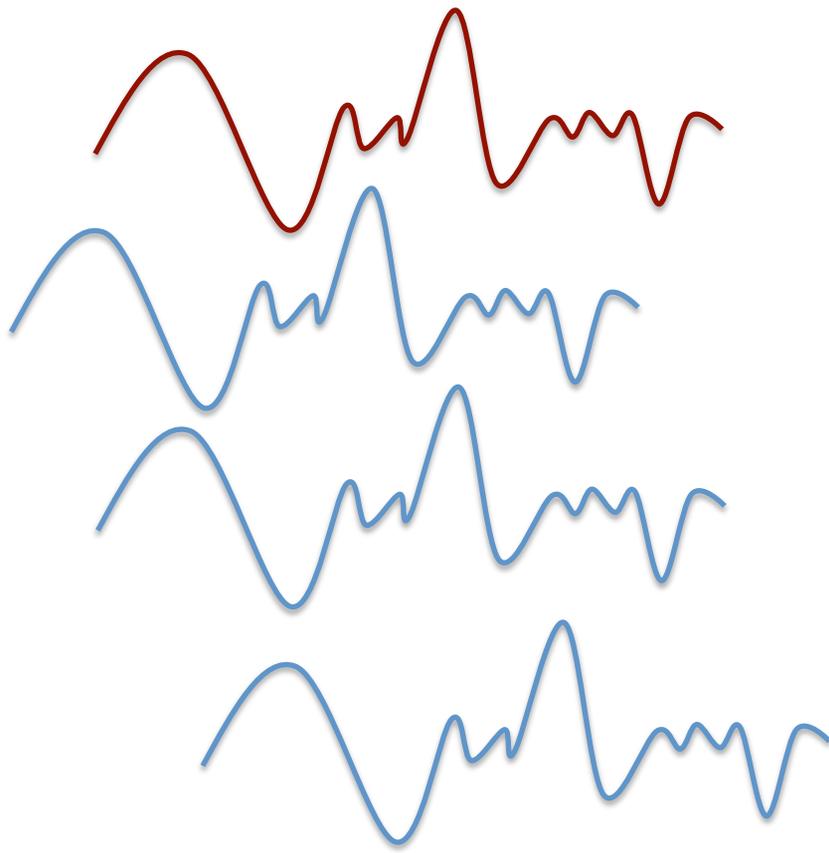
- Every pair of telescopes (every baseline) is sensitive to one spatial frequency, ie a wave pattern on the sky
- The projected distance as seen from the source defines a point in the Fourier domain, the **uv domain**
- For each uv point, a **phase** and **amplitude** is measured
- → the uv points determine what is measured, the phase/amplitude define the strength and displacement of that signal
- The distribution of uv points determine the image quality



Interferometry uv-plane

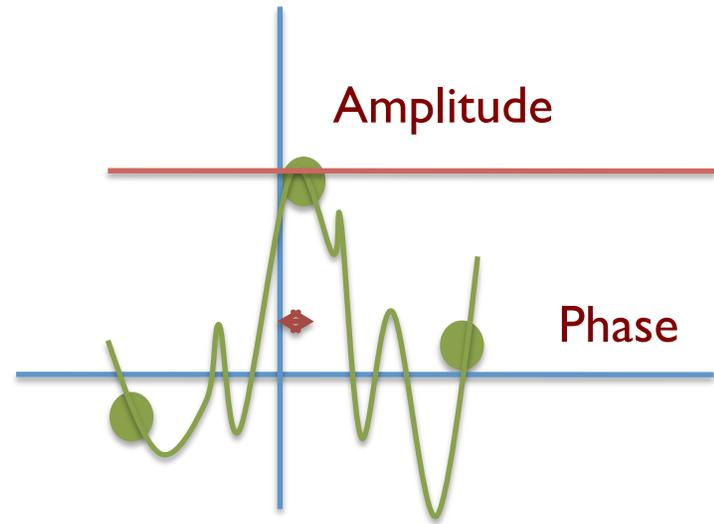


Interferometry – fringe, phase amplitude



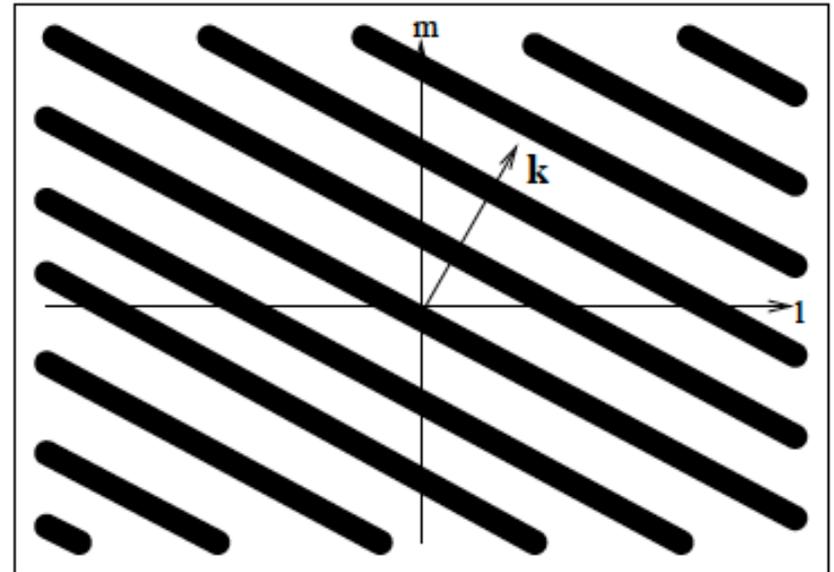
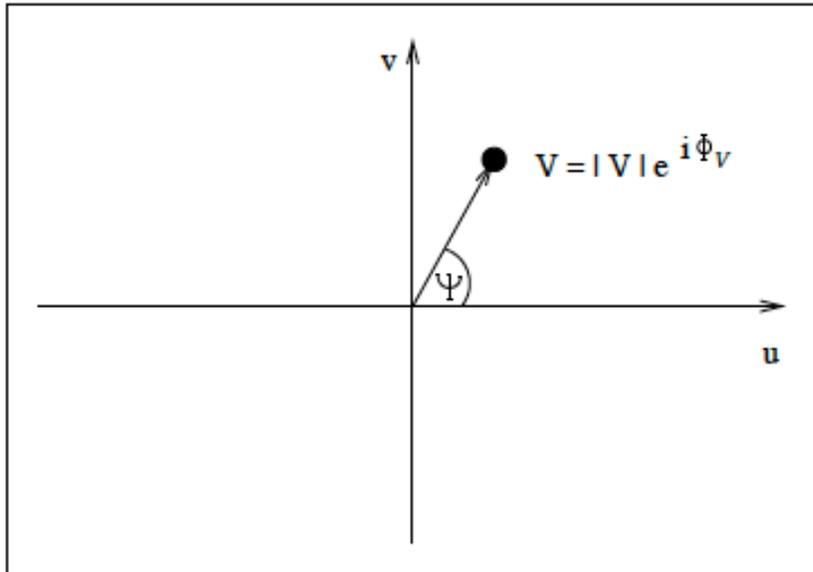
Signal in antenna 1

Signal in antenna 2



Lag spectrum (fringe)



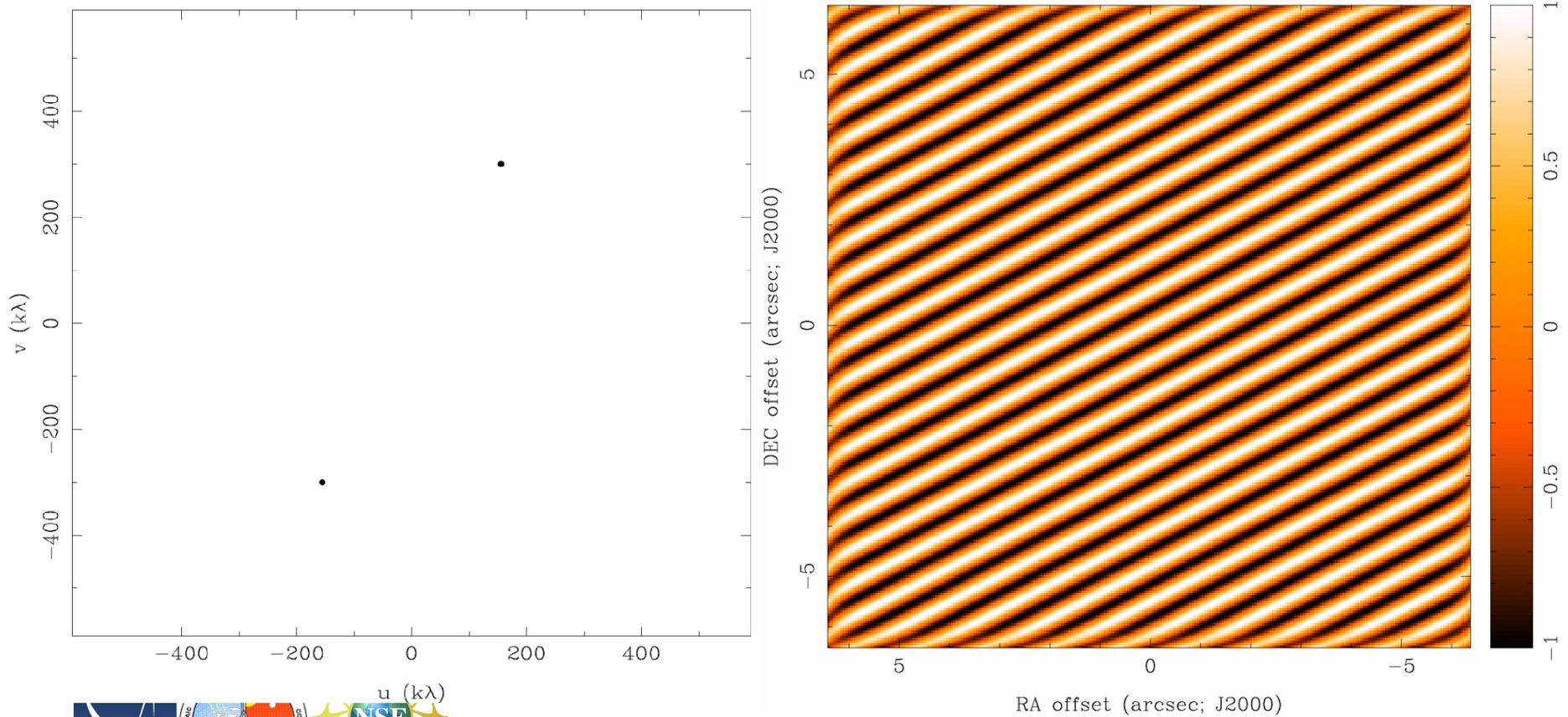


uv domain	Image domain
Visibility	Spatial frequency
Angle ψ toward the uv point	Direction of wave vector k
Length of Vector	Spatial frequency
Phase ϕ of visibility	Offset from the central pixel (phase center)
Amplitude $ V $	Amplitude of spatial frequency



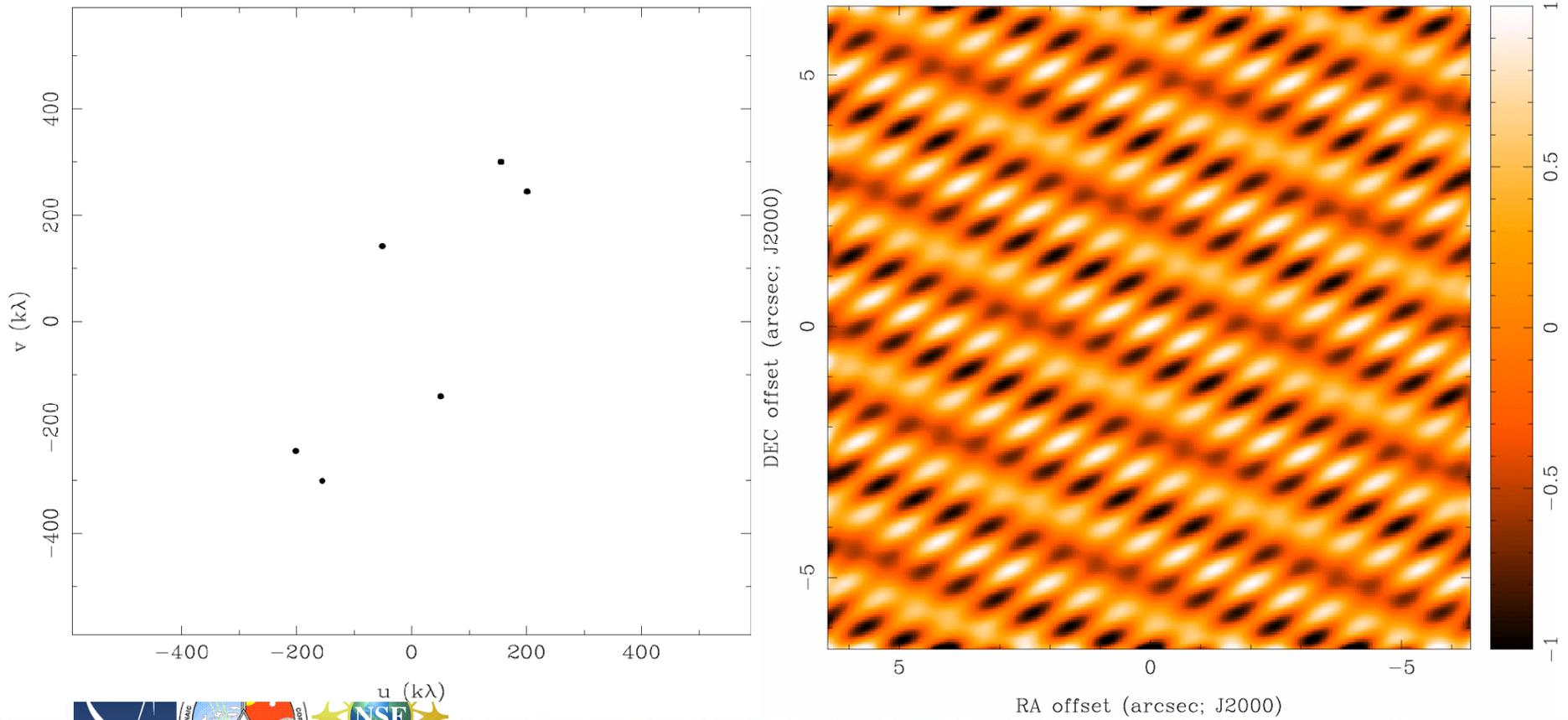
Dirty Beam Shape and N Antennas

2 Antennas



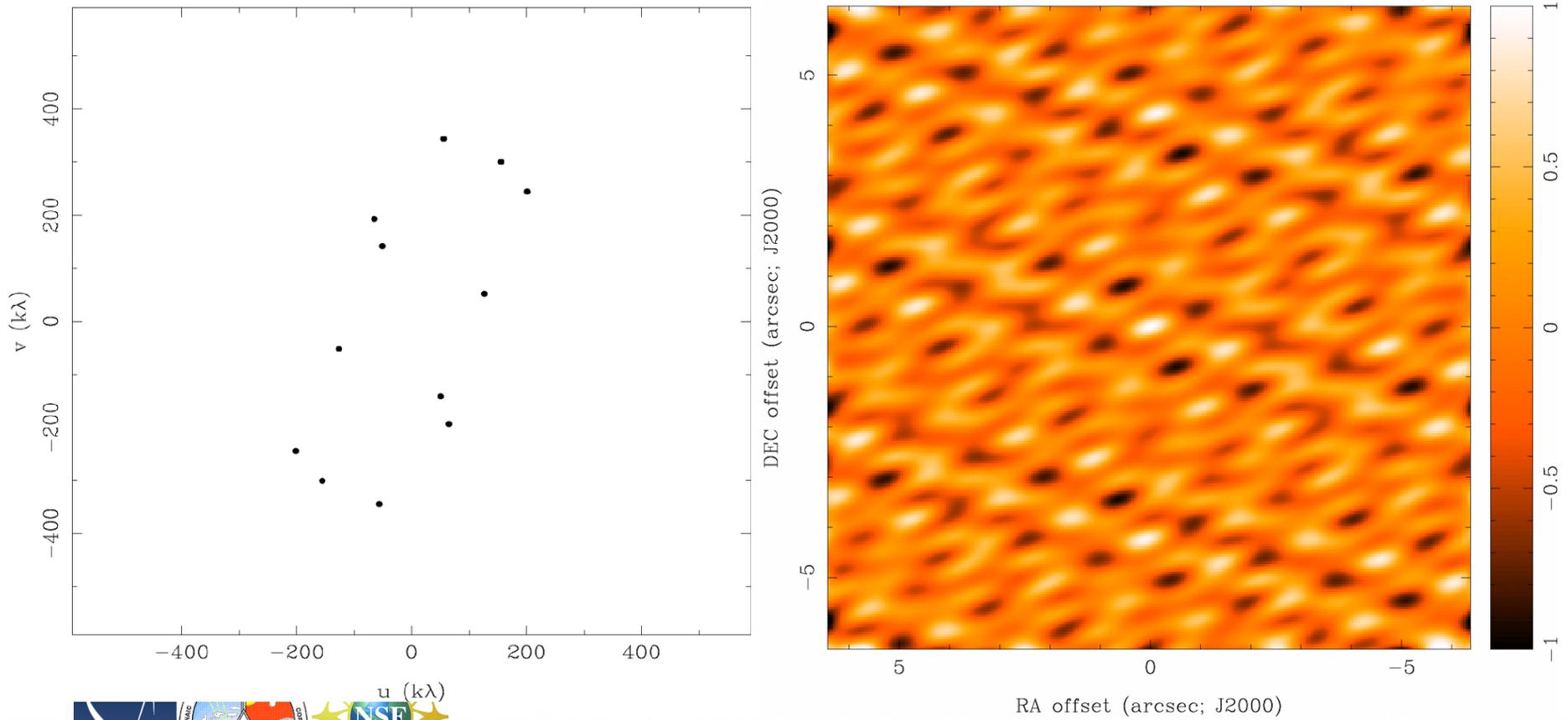
Dirty Beam Shape and N Antennas

3 Antennas



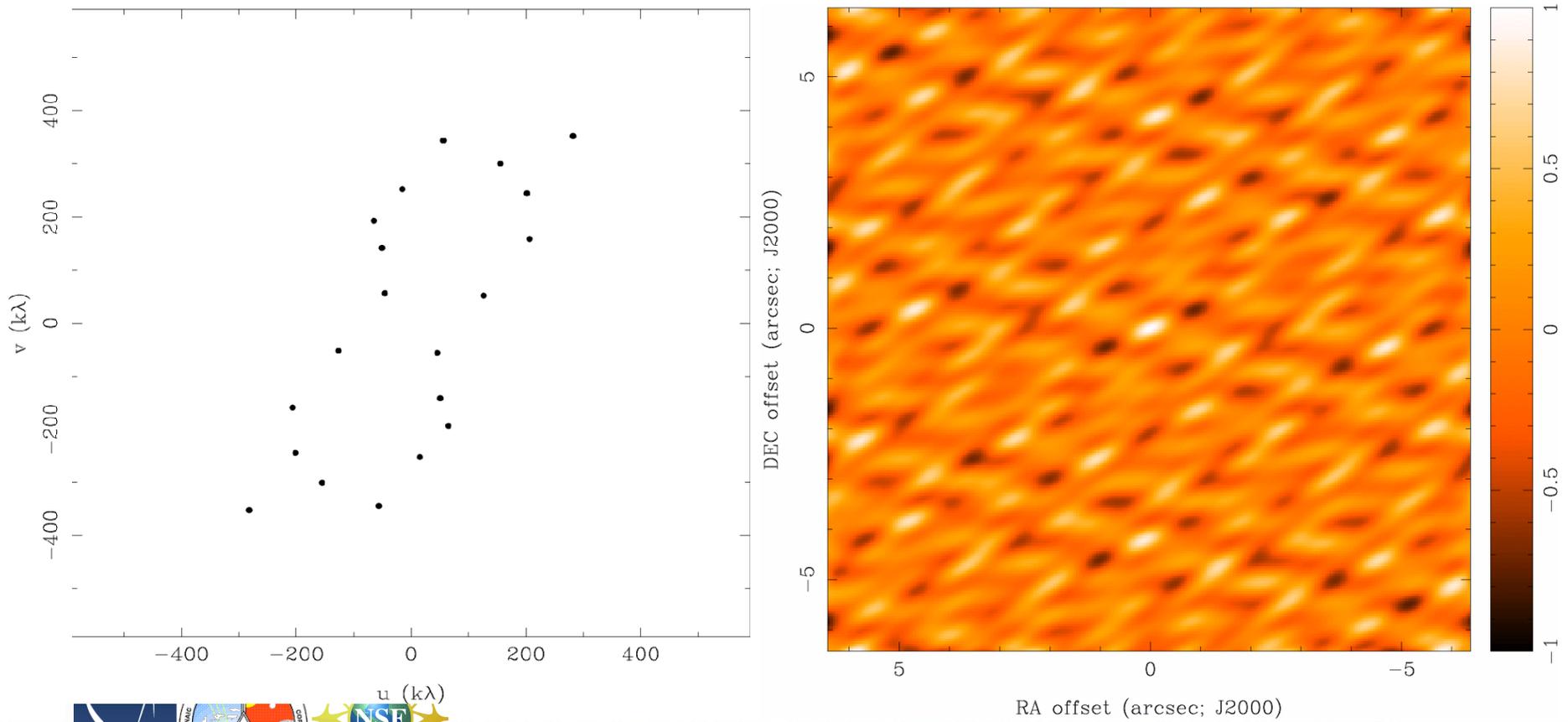
Dirty Beam Shape and N Antennas

4 Antennas



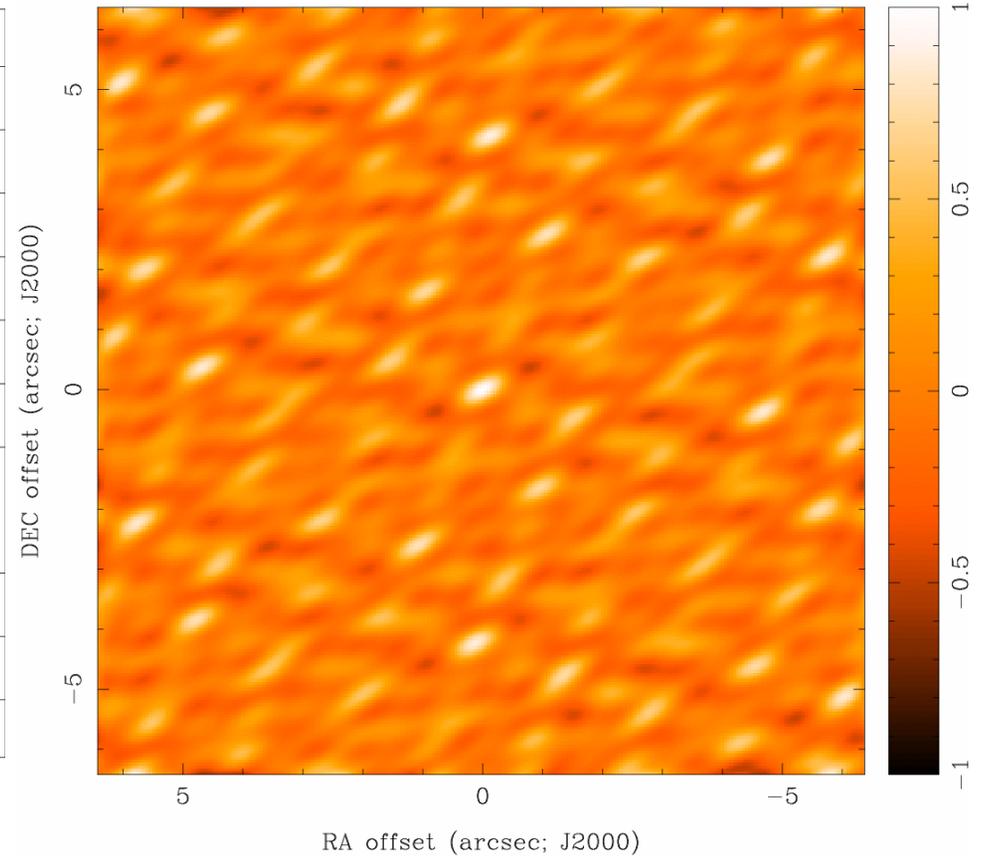
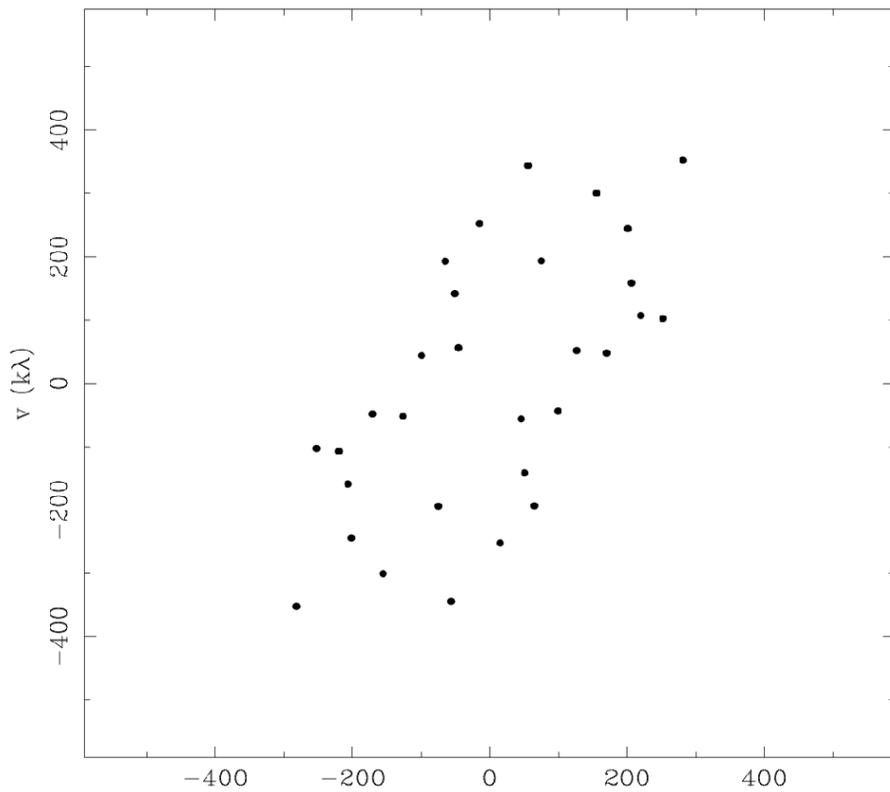
Dirty Beam Shape and N Antennas

5 Antennas



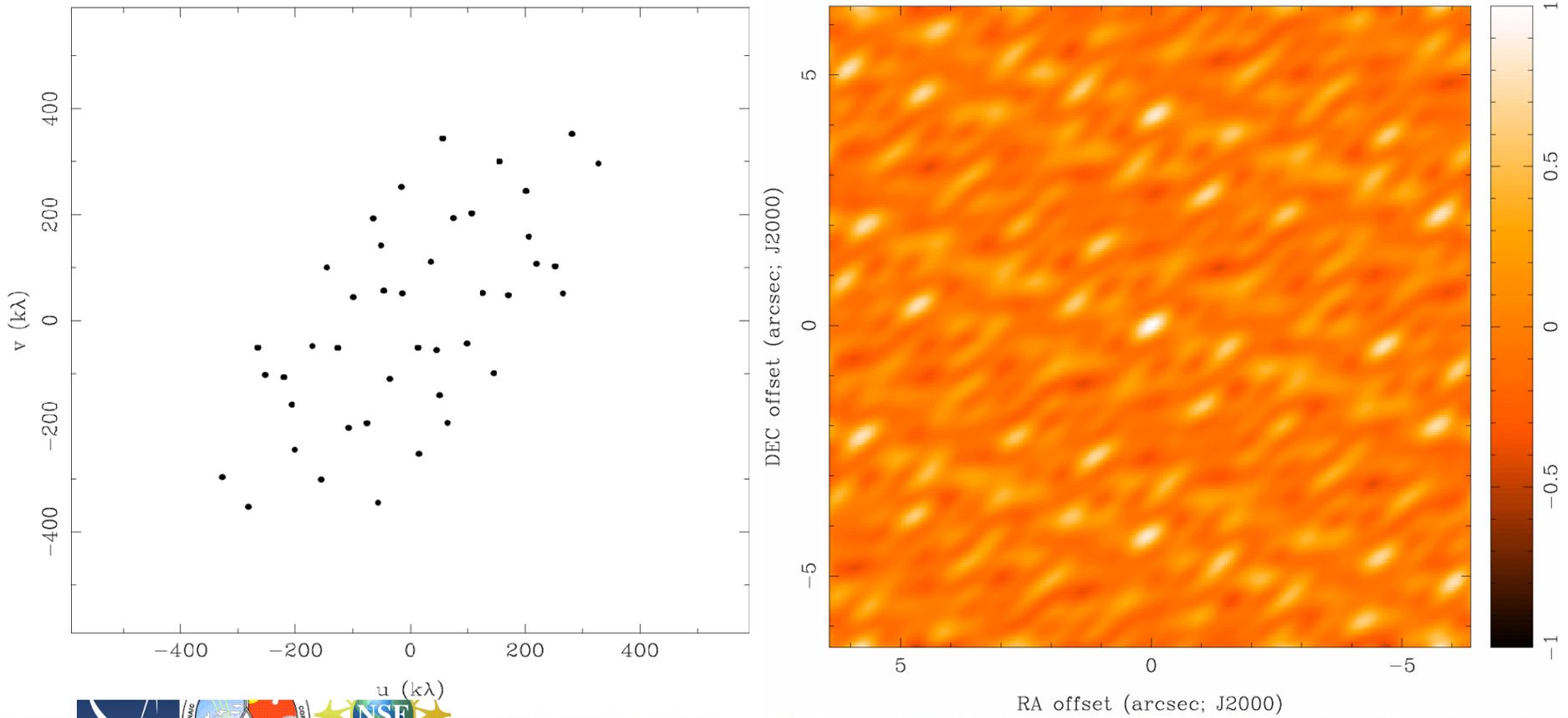
Dirty Beam Shape and N Antennas

6 Antennas



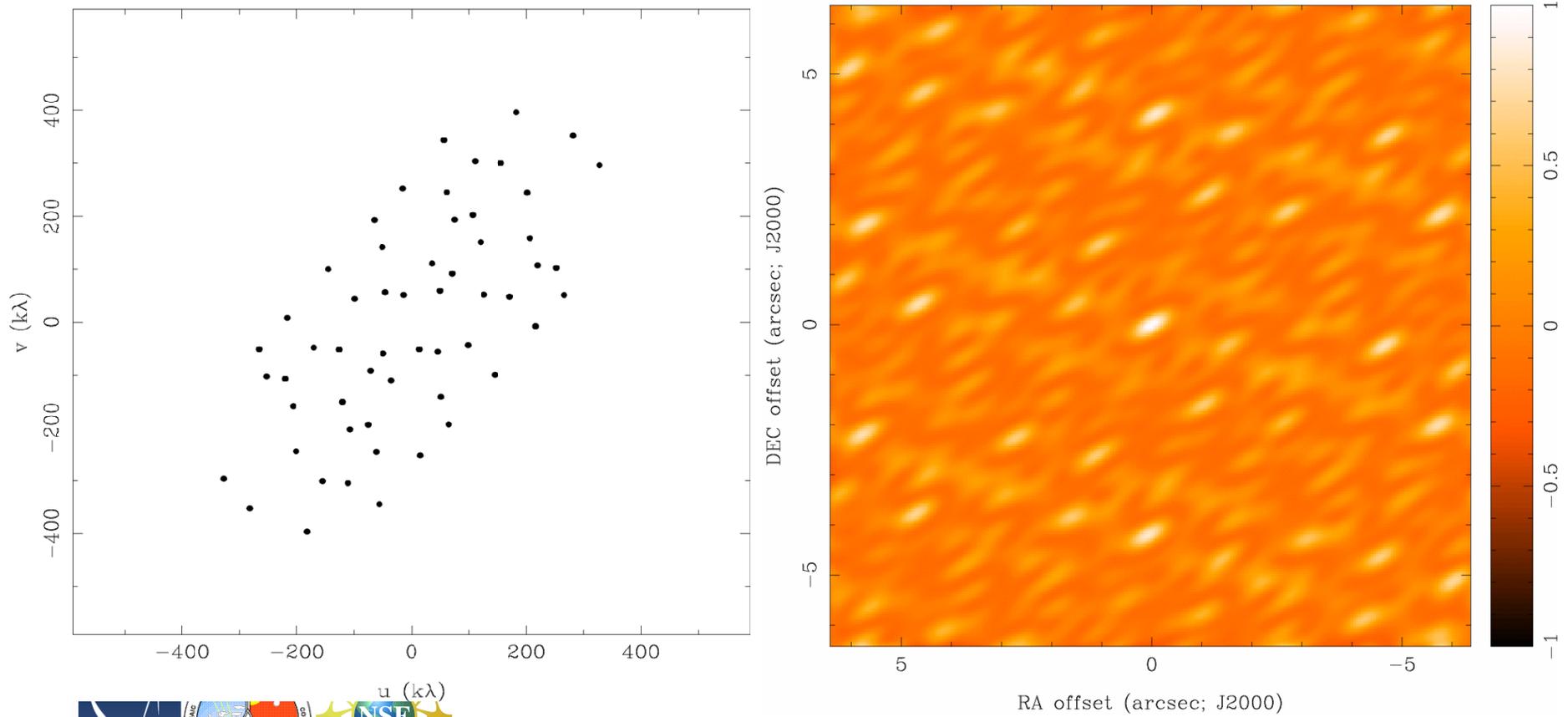
Dirty Beam Shape and N Antennas

7 Antennas



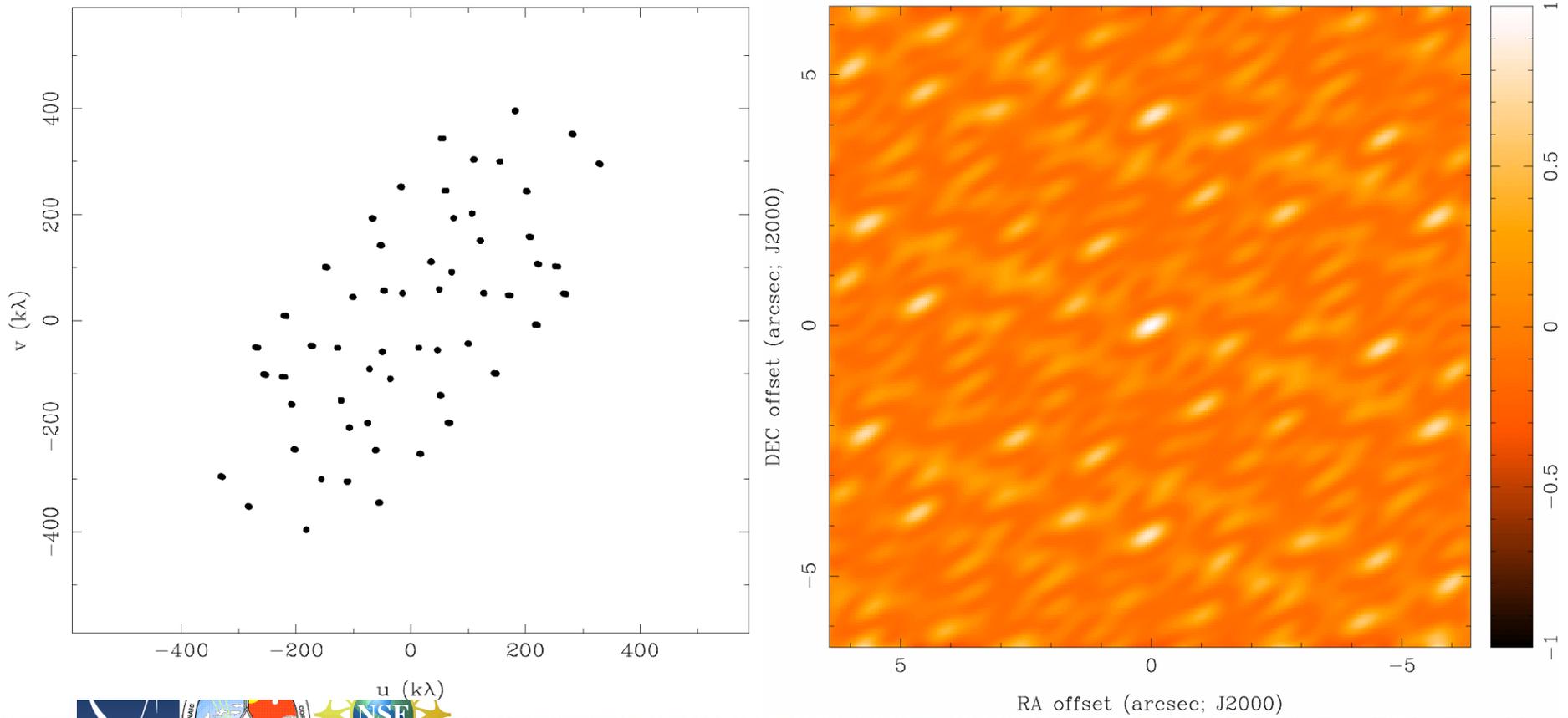
Dirty Beam Shape and N Antennas

8 Antennas



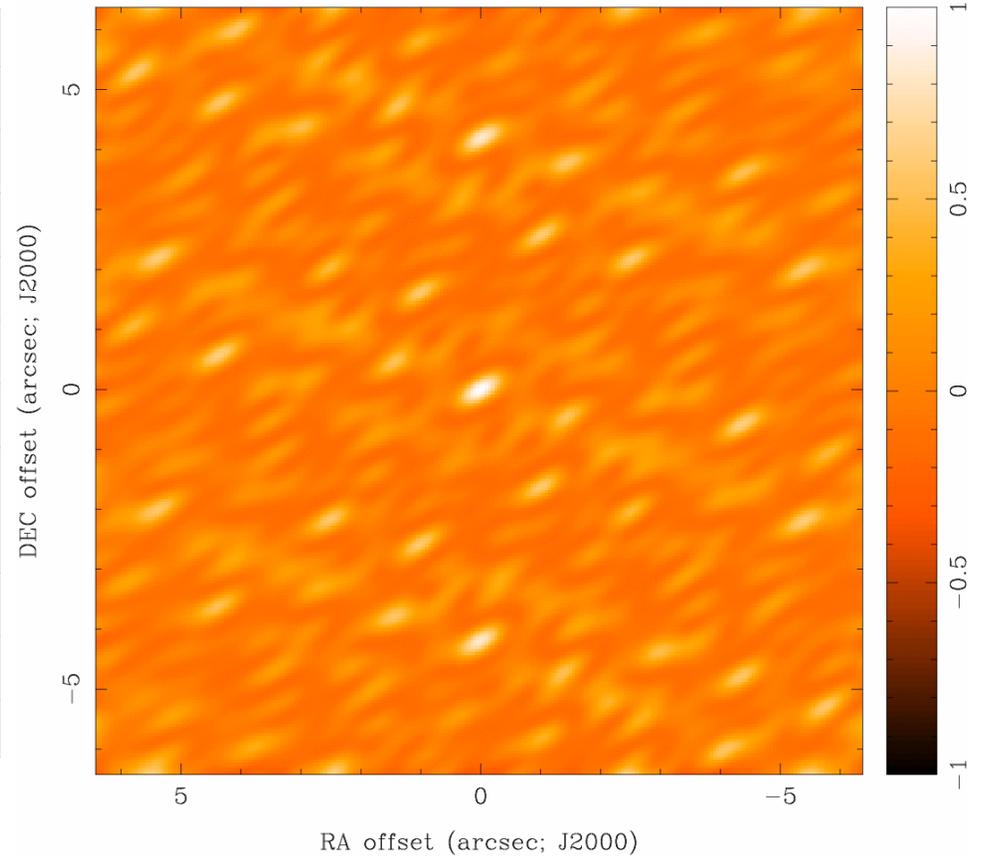
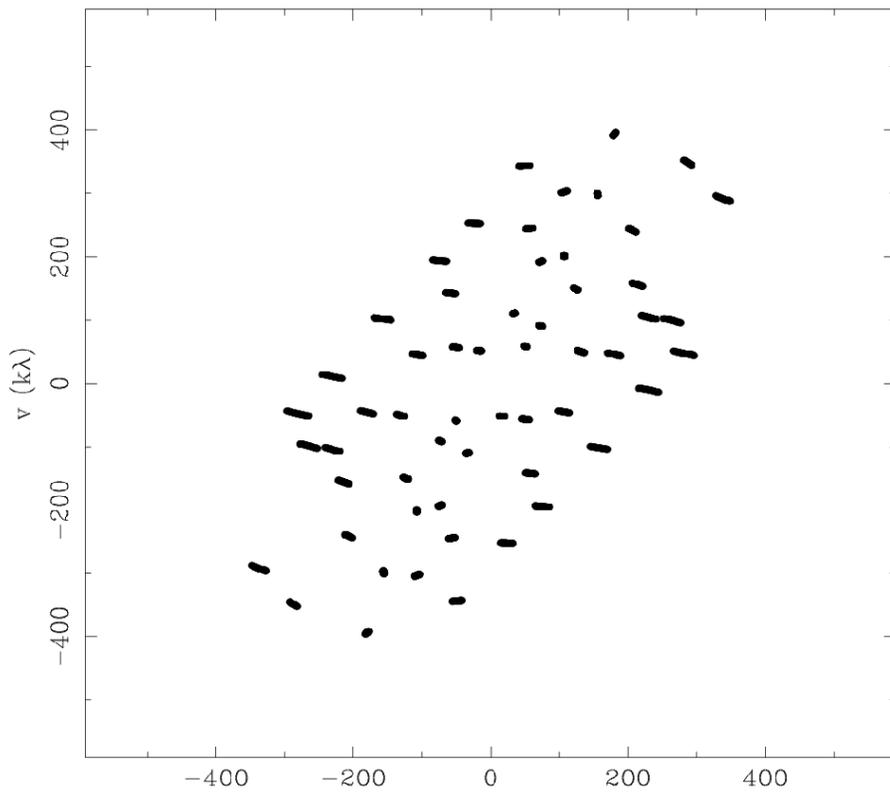
Dirty Beam Shape and N Antennas

8 Antennas x 6 Samples



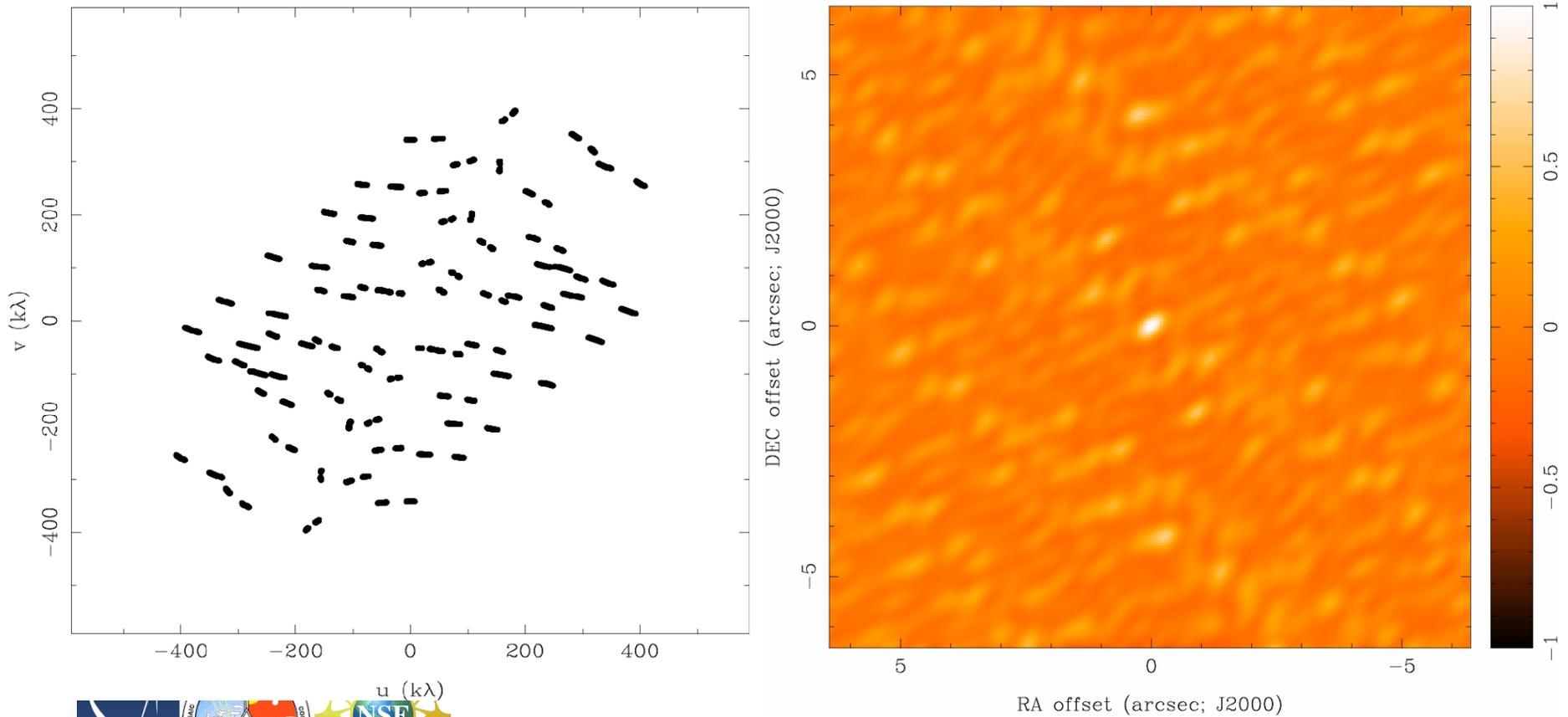
Dirty Beam Shape and N Antennas

8 Antennas x 30 Samples



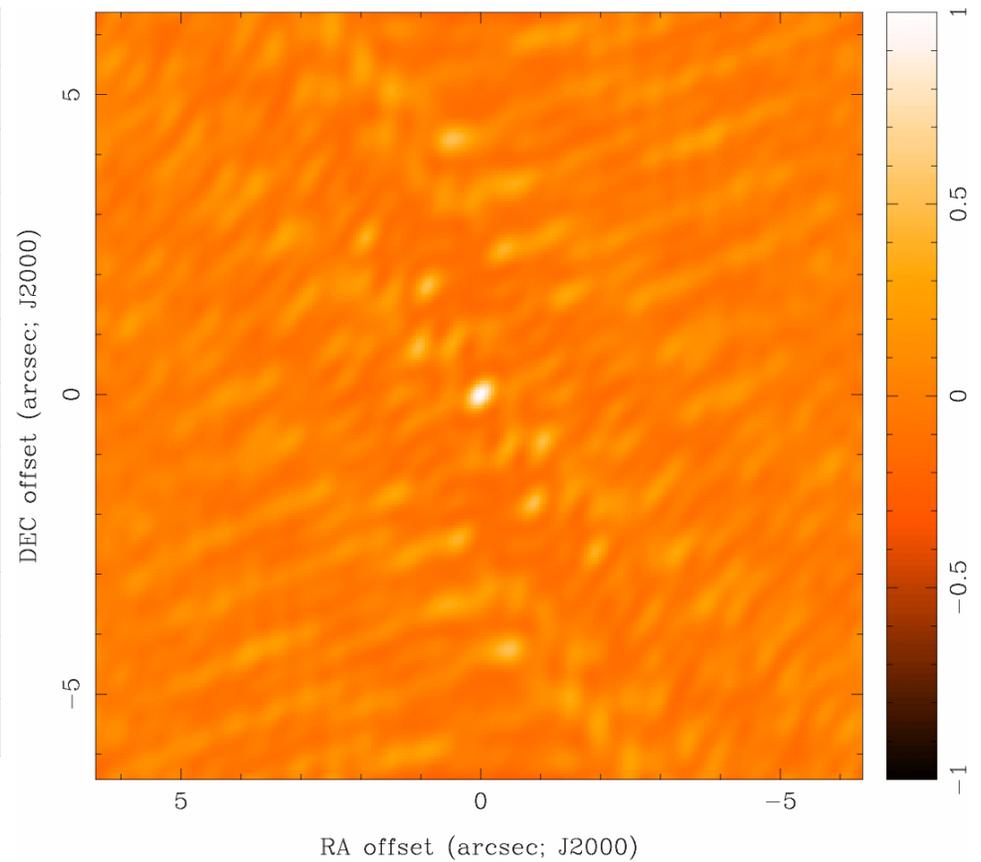
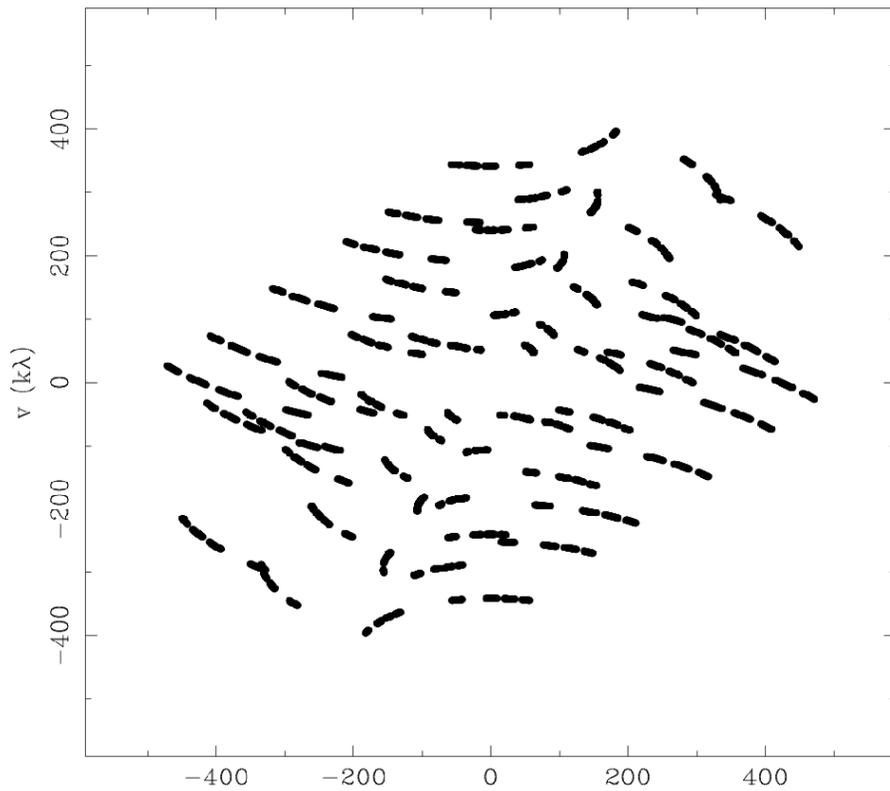
Dirty Beam Shape and N Antennas

8 Antennas x 60 Samples



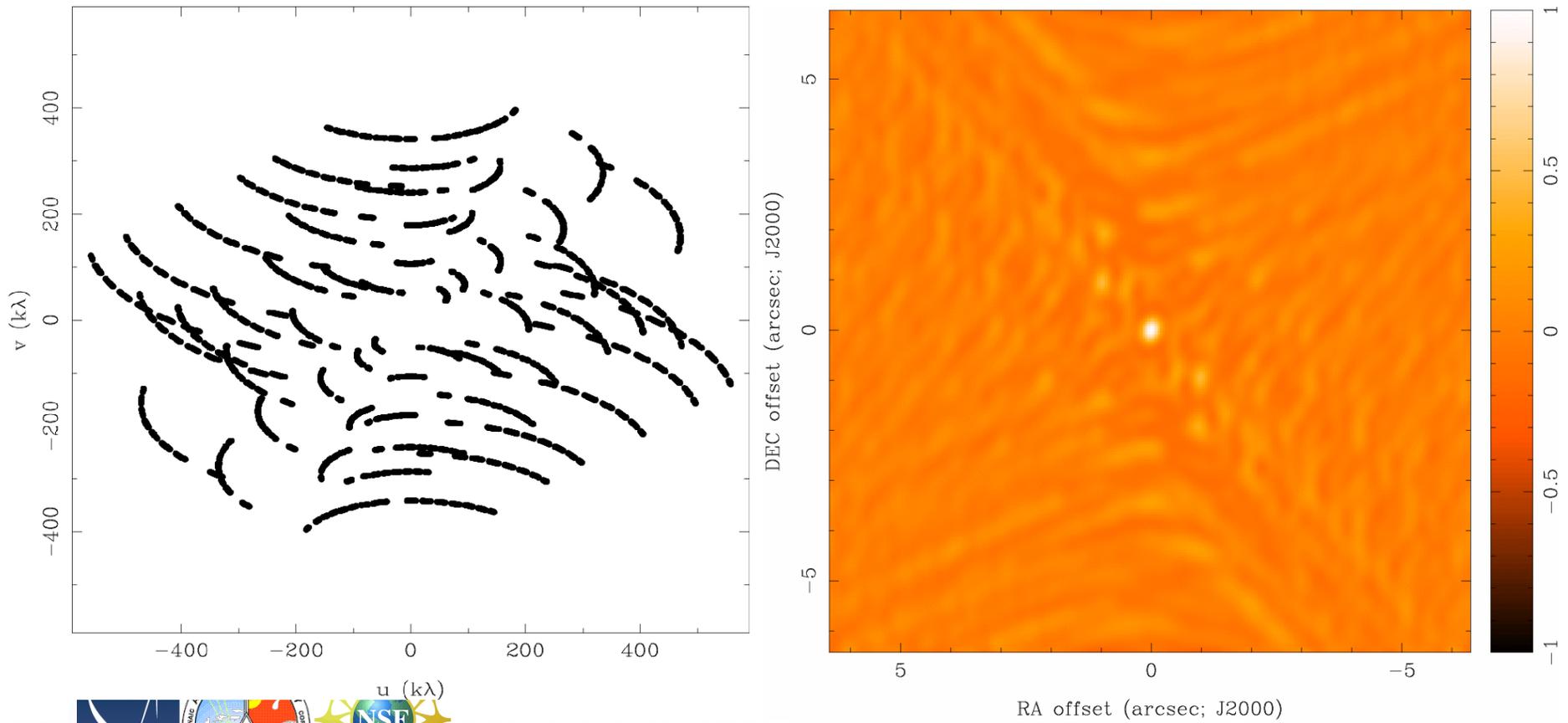
Dirty Beam Shape and N Antennas

8 Antennas x 120 Samples



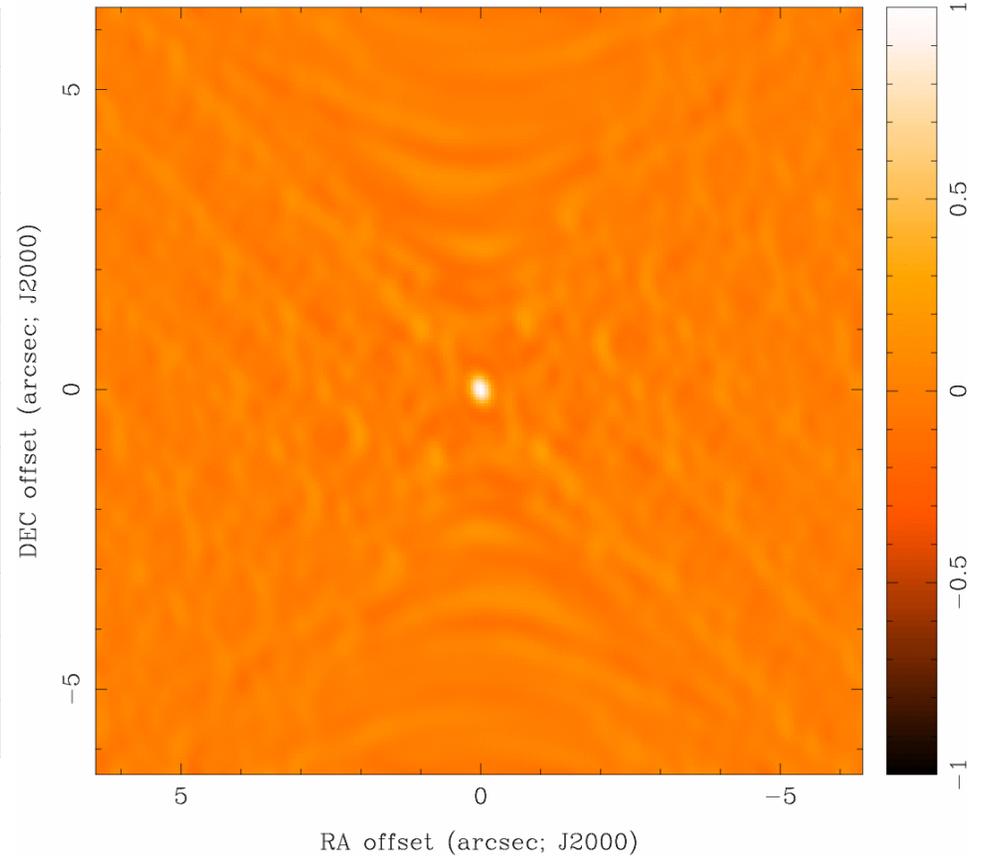
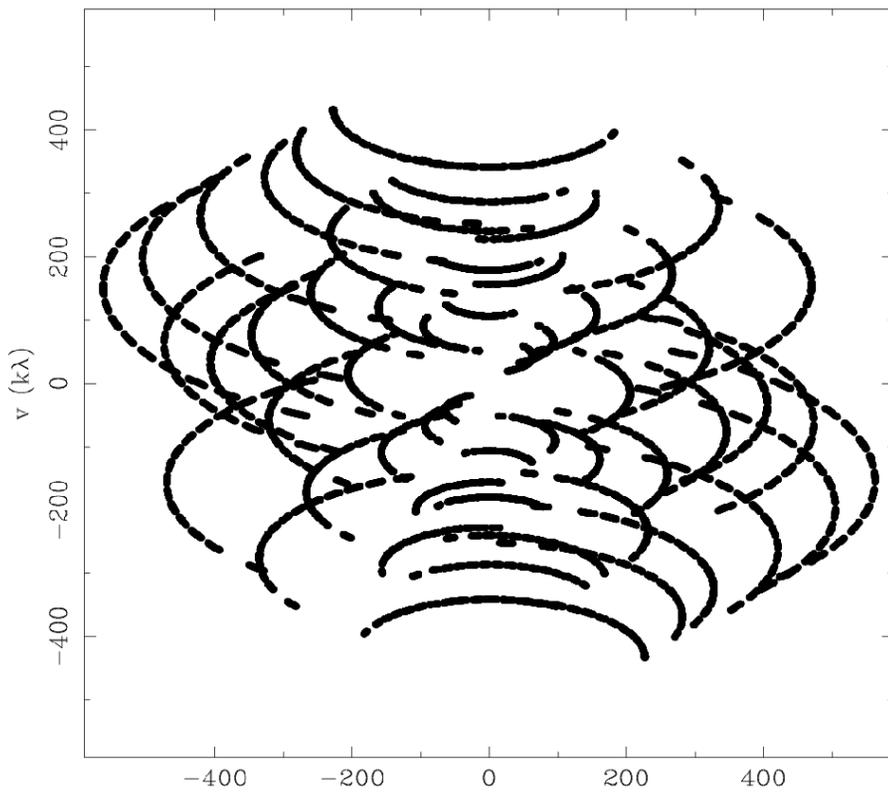
Dirty Beam Shape and N Antennas

8 Antennas x 240 Samples



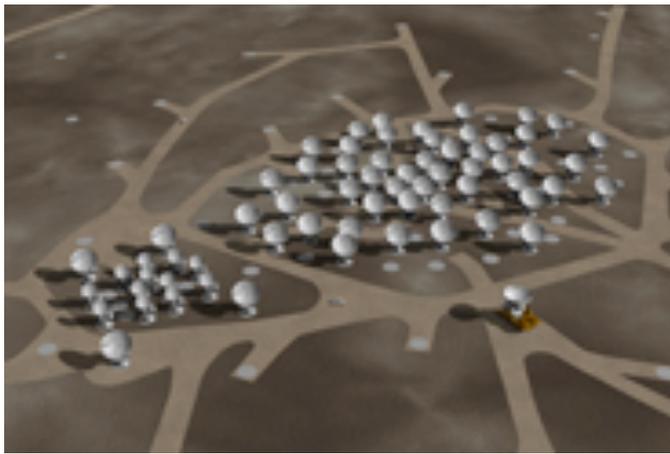
Dirty Beam Shape and N Antennas

8 Antennas x 480 Samples

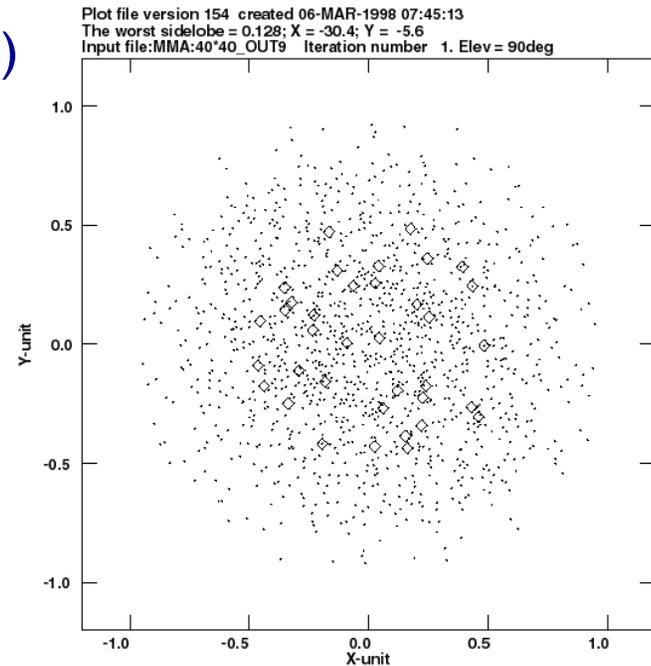


Interferometry

- How to get a lot of visibilities?
- **Solution (1)** build a lot of antenna (pairs)

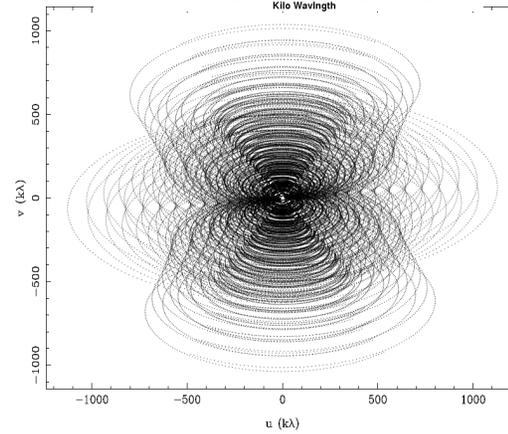
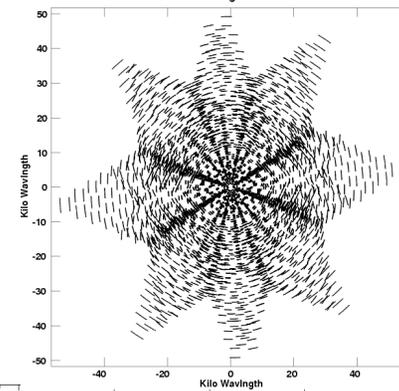
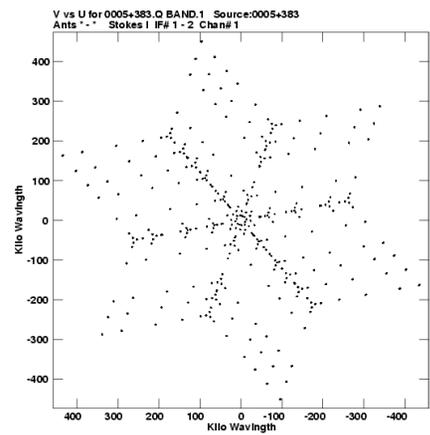


ALMA: 50 antennas = $n(n-1)/2 = 1225$ pairs!



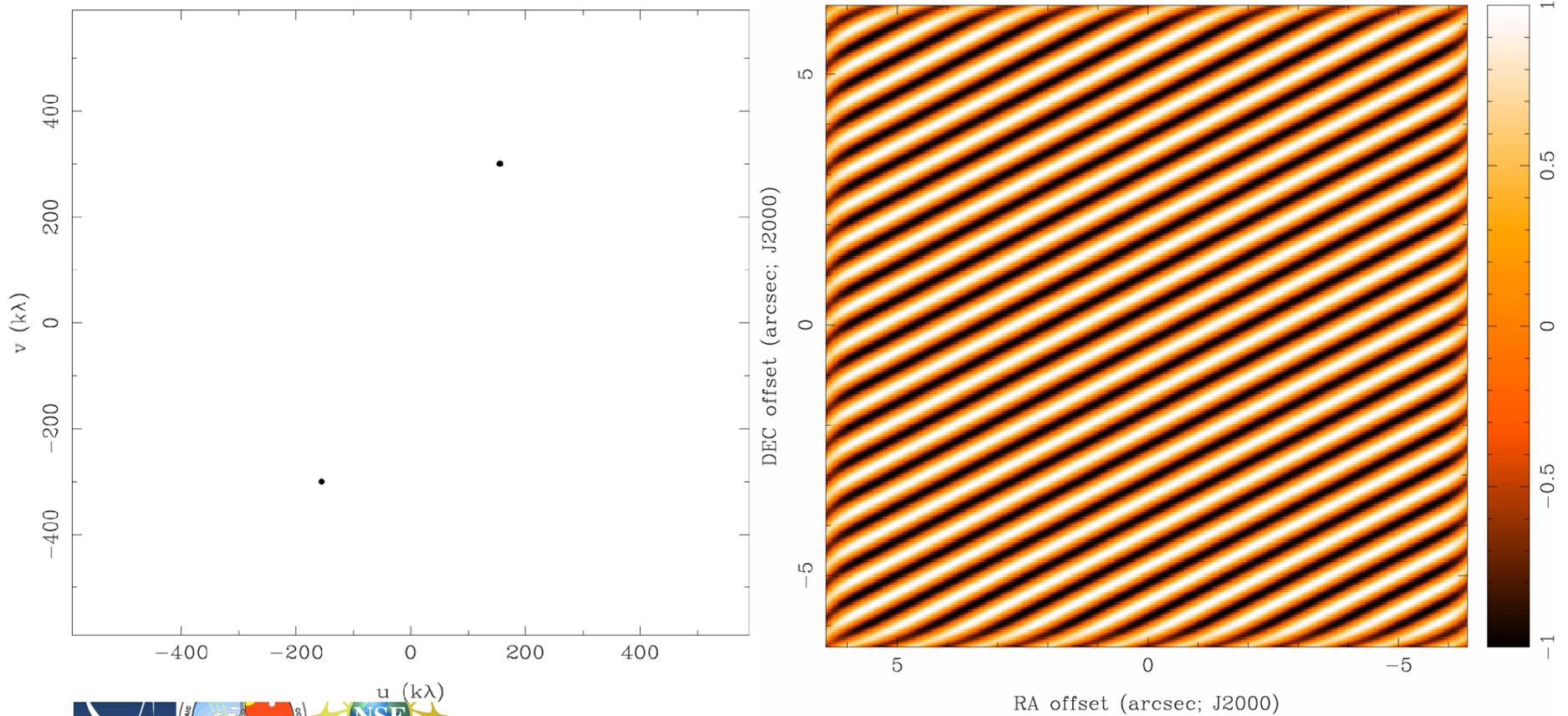
- **Solution (2)** aperture synthesis, let the earth rotation do the trick (Nobel prize in physics 1974, Sir Martin Ryle)





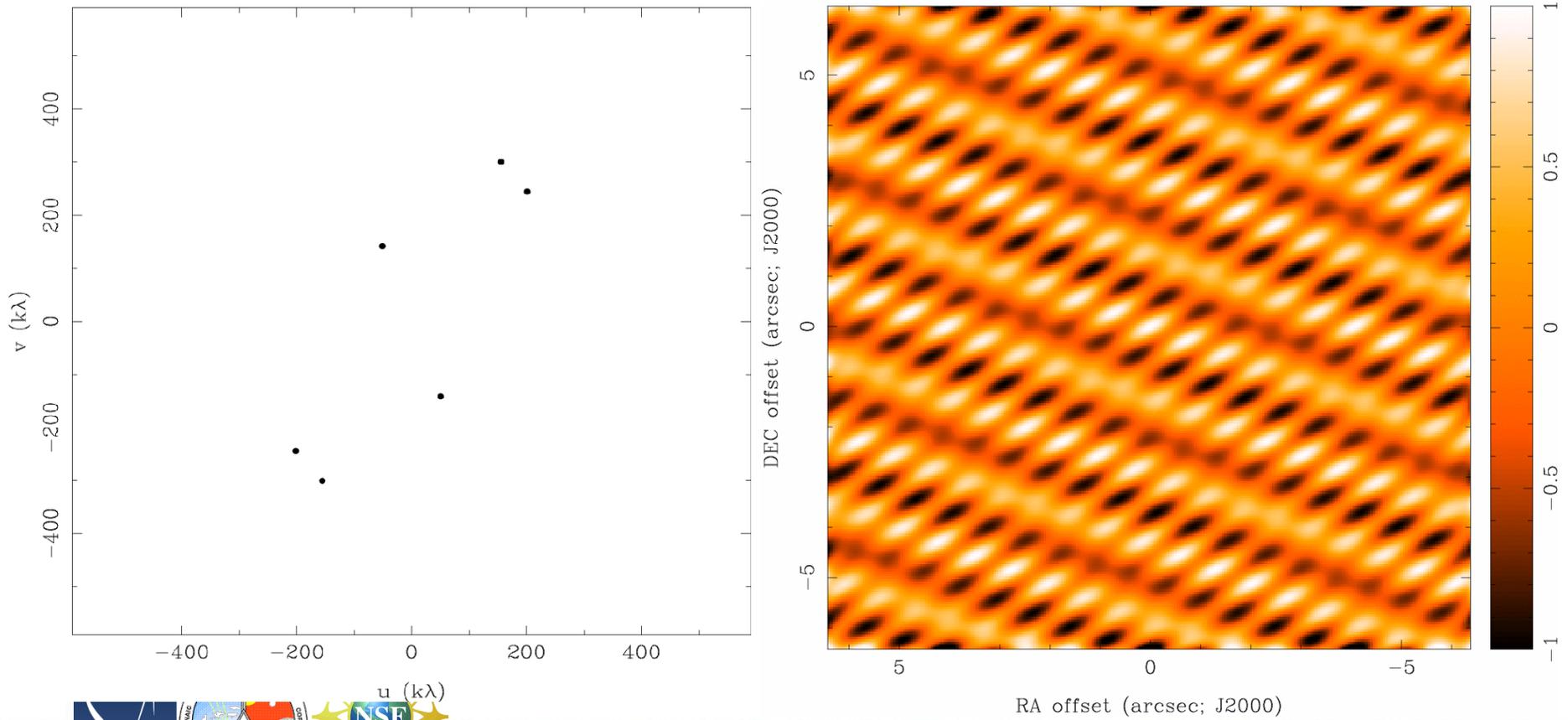
Dirty Beam Shape and N Antennas

2 Antennas



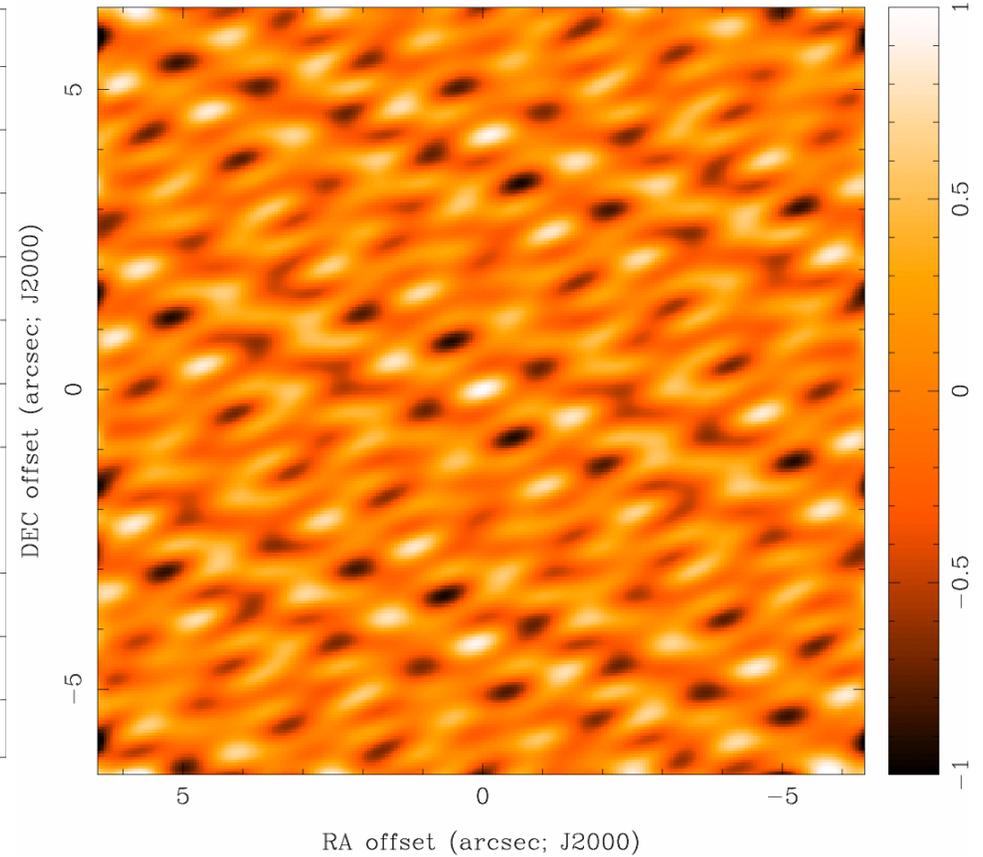
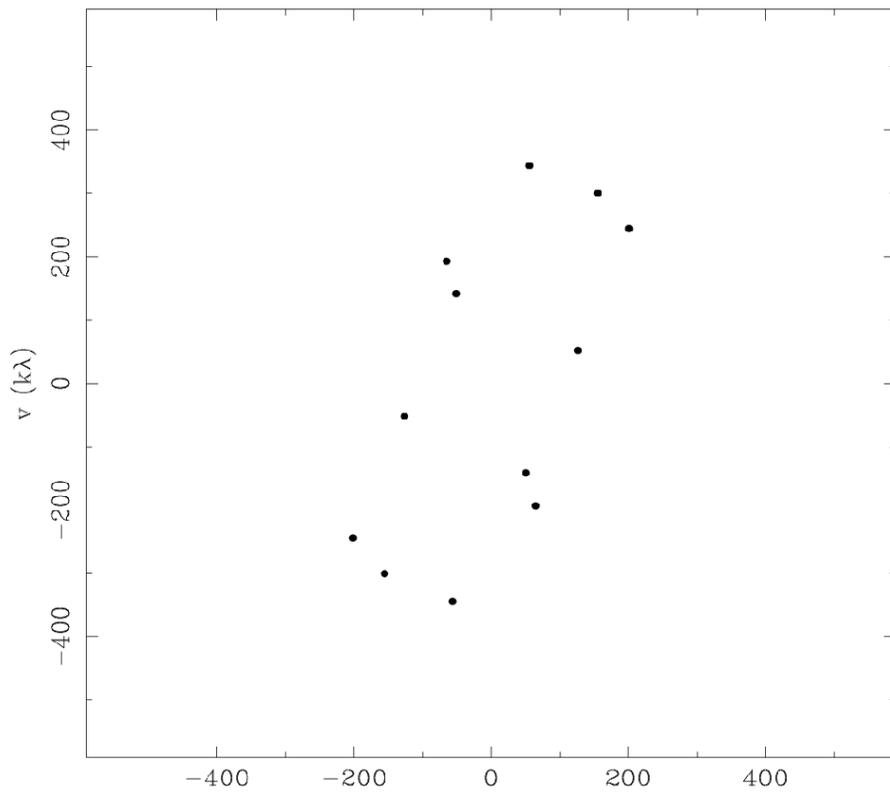
Dirty Beam Shape and N Antennas

3 Antennas



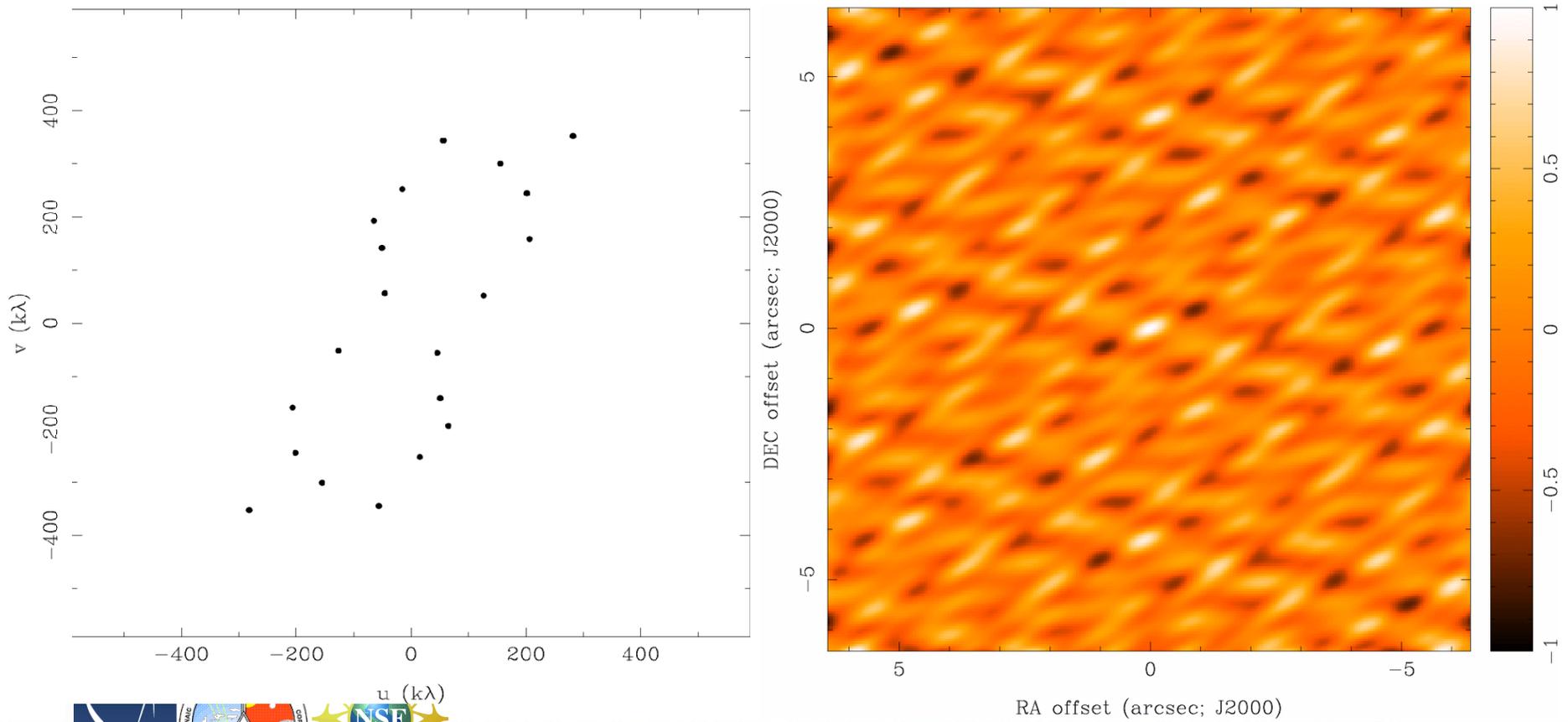
Dirty Beam Shape and N Antennas

4 Antennas



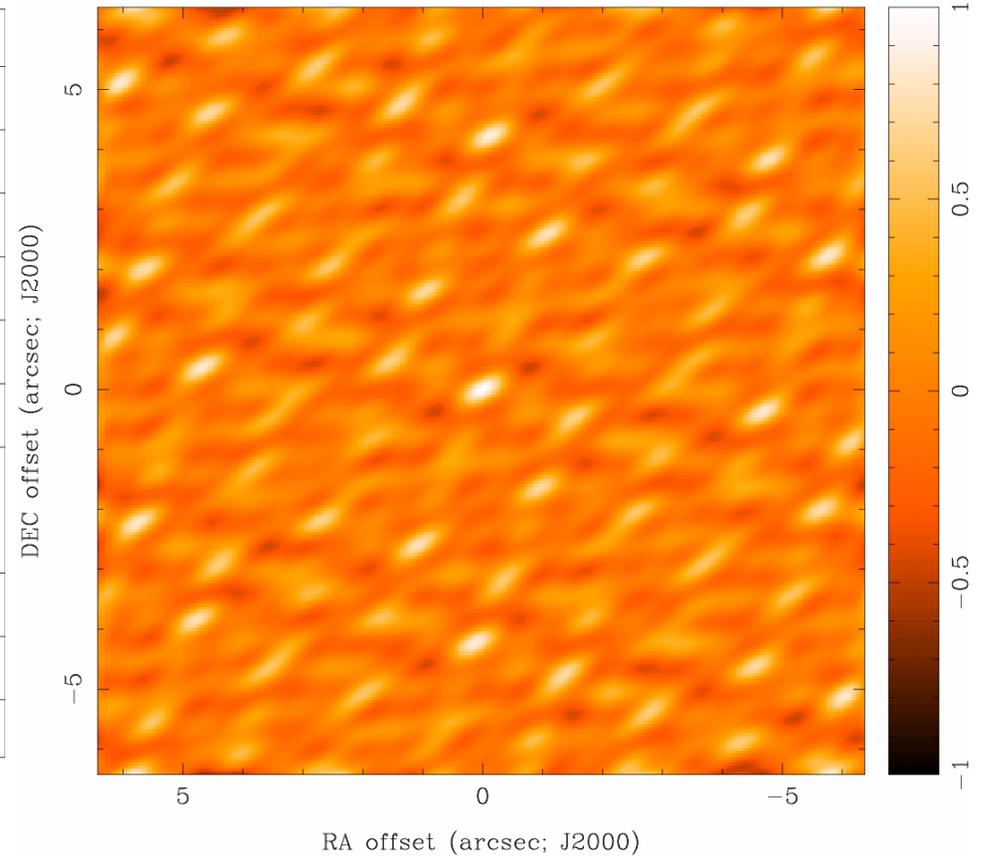
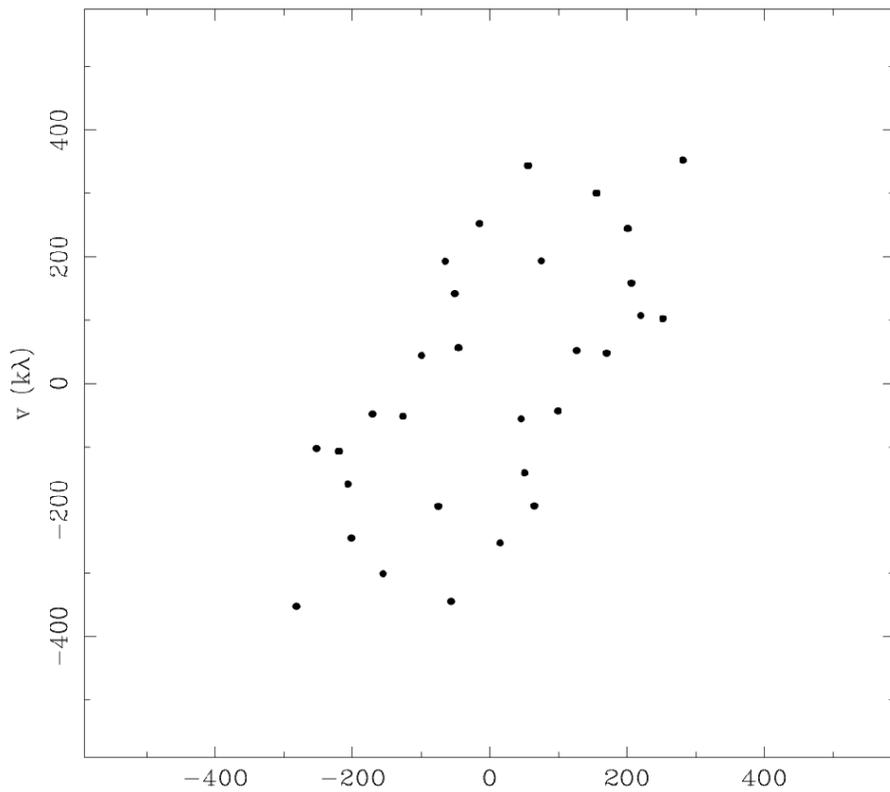
Dirty Beam Shape and N Antennas

5 Antennas



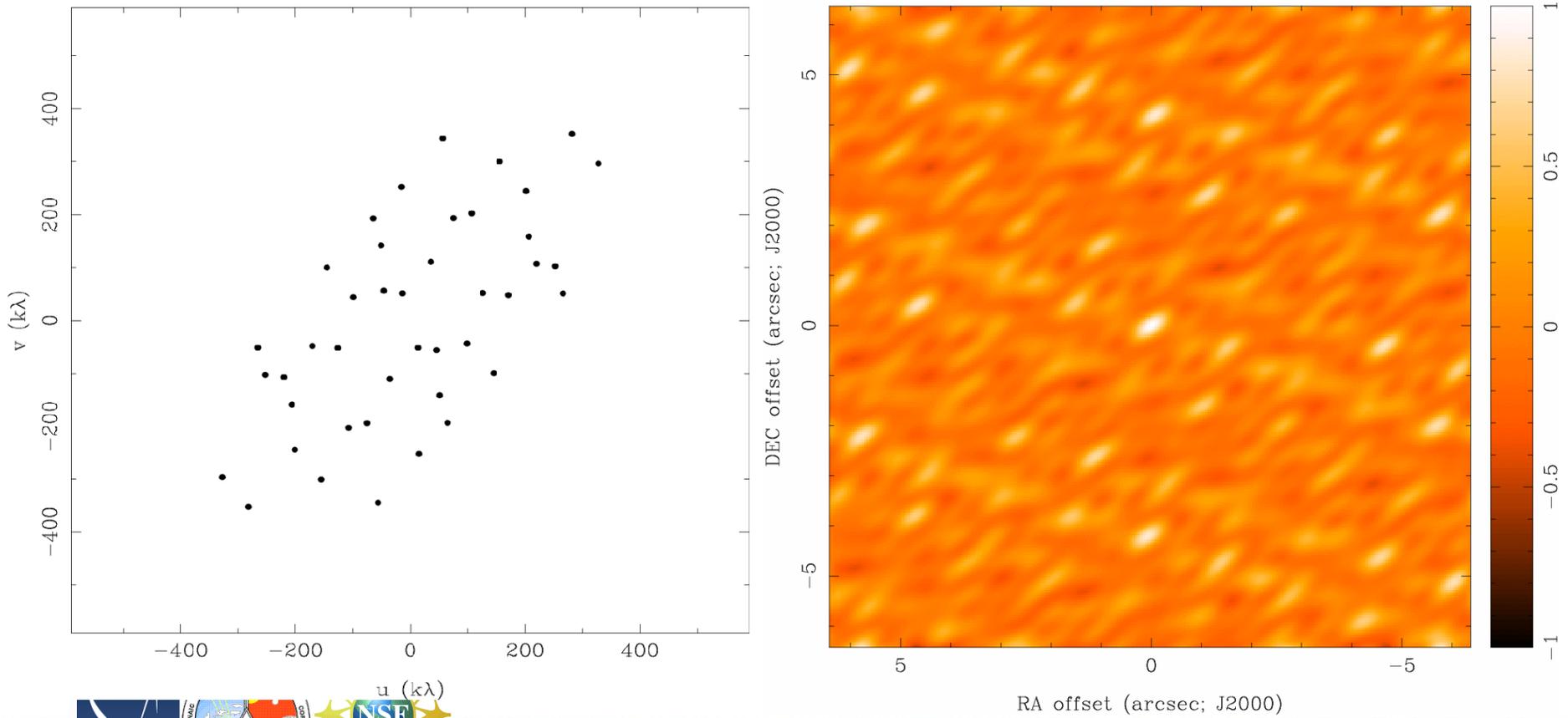
Dirty Beam Shape and N Antennas

6 Antennas



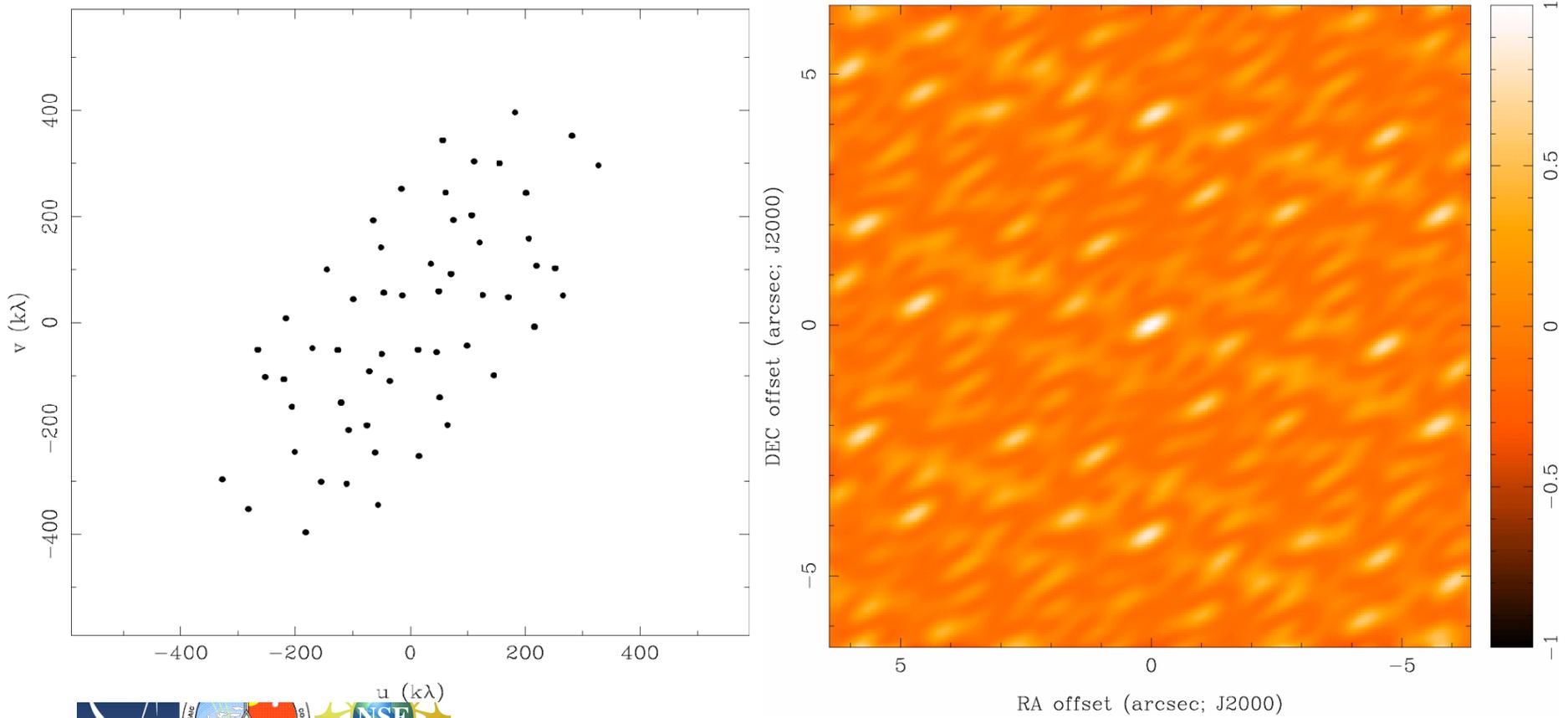
Dirty Beam Shape and N Antennas

7 Antennas



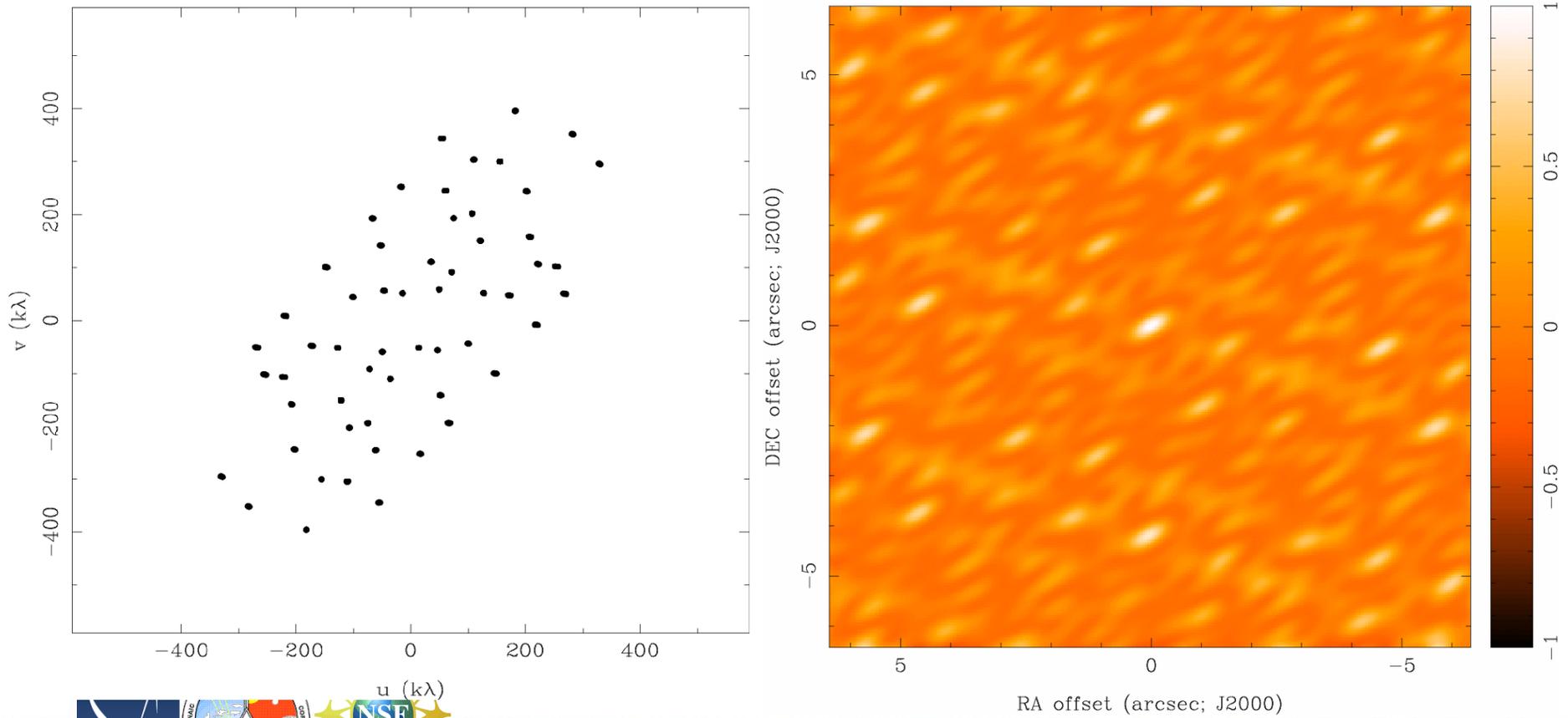
Dirty Beam Shape and N Antennas

8 Antennas



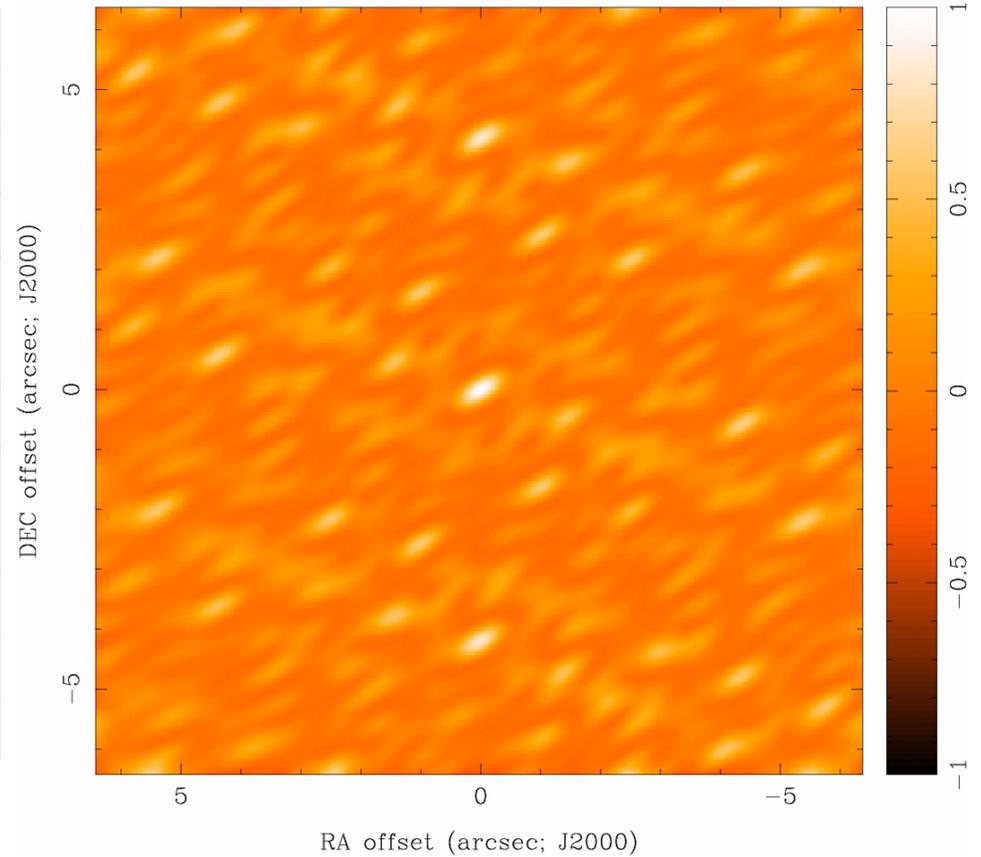
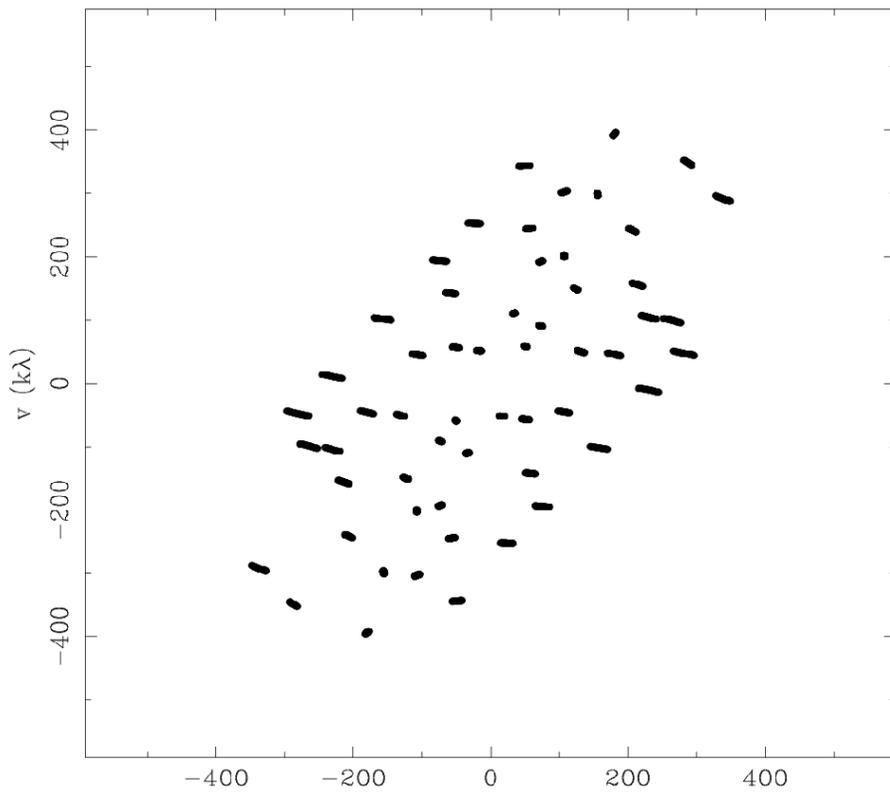
Dirty Beam Shape and N Antennas

8 Antennas x 6 Samples



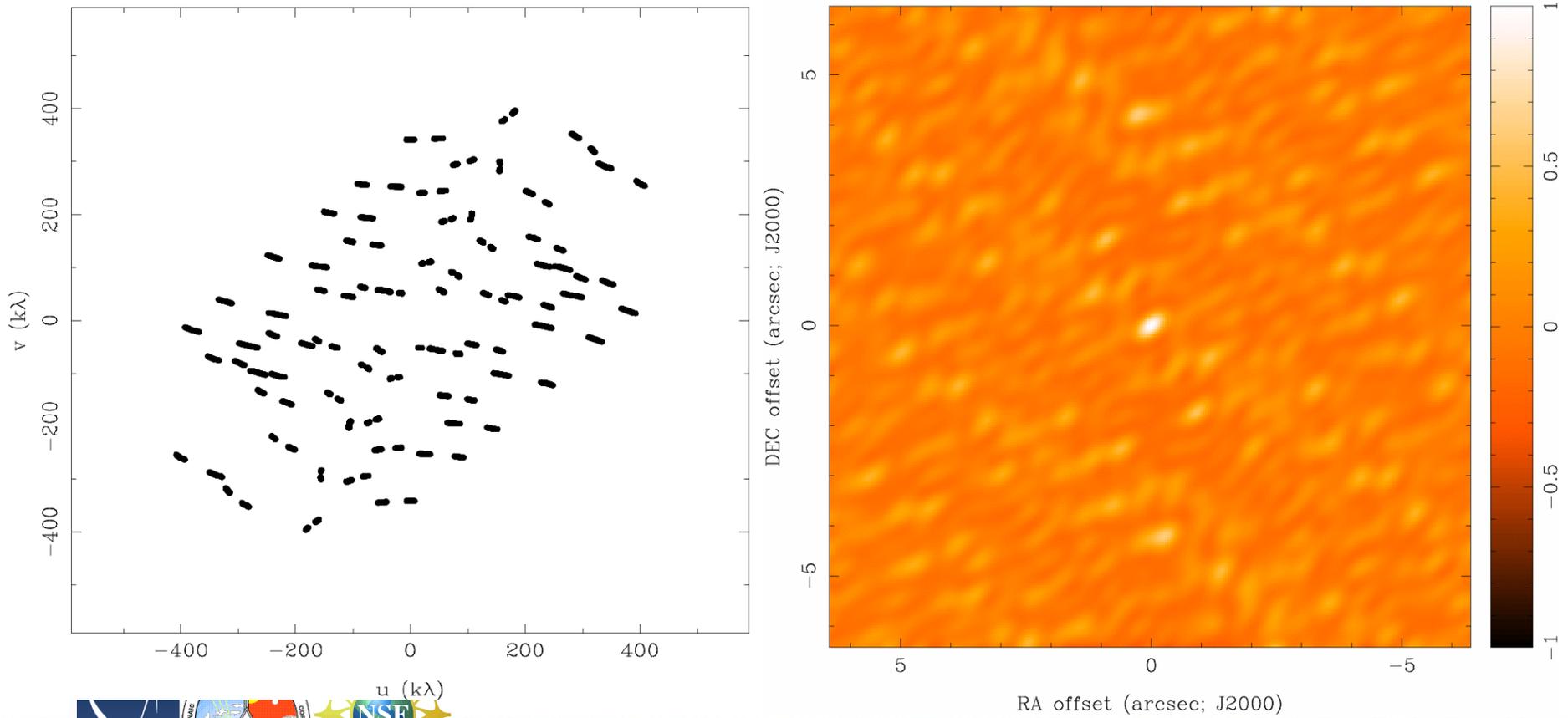
Dirty Beam Shape and N Antennas

8 Antennas x 30 Samples



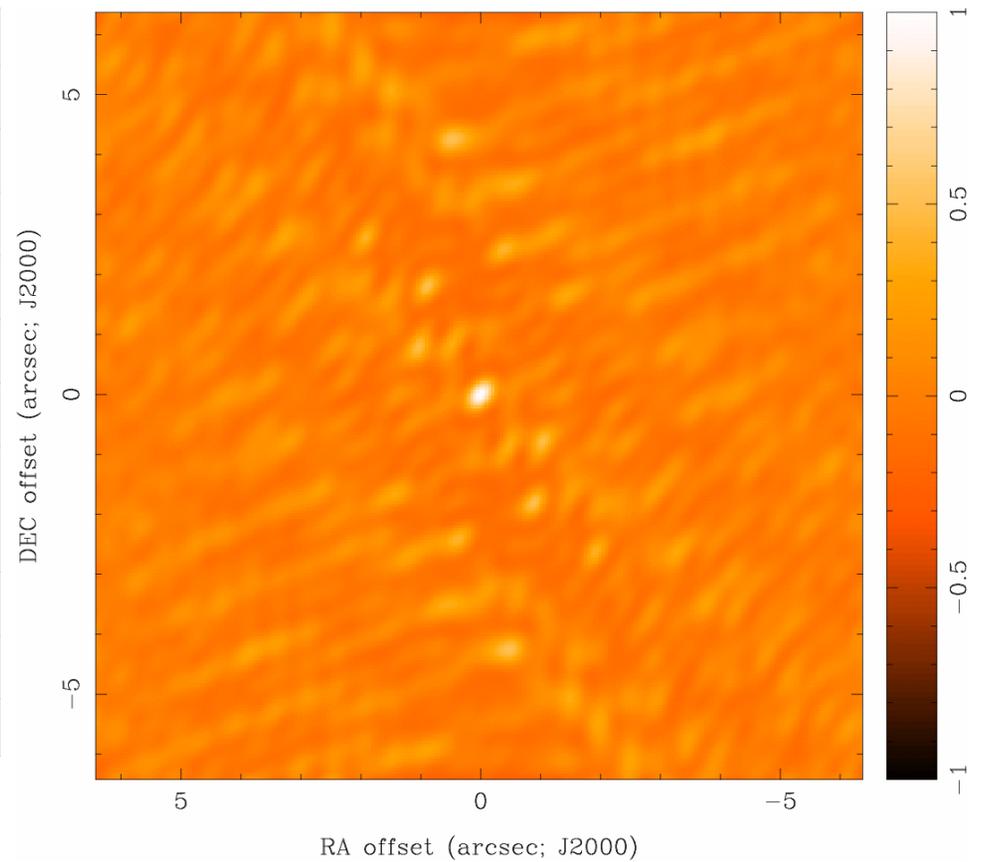
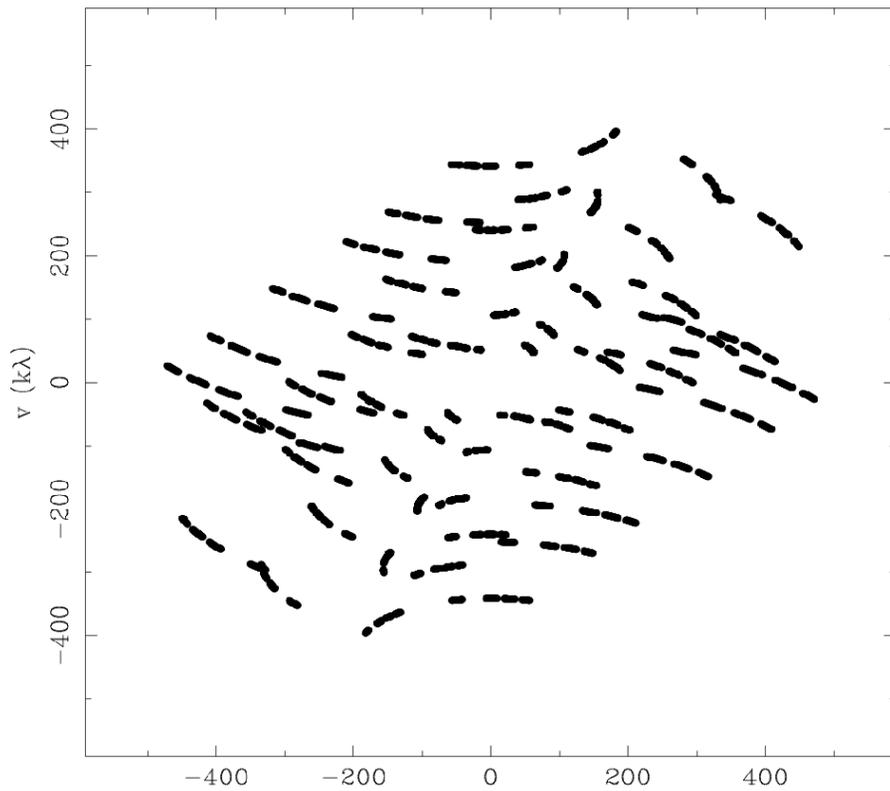
Dirty Beam Shape and N Antennas

8 Antennas x 60 Samples



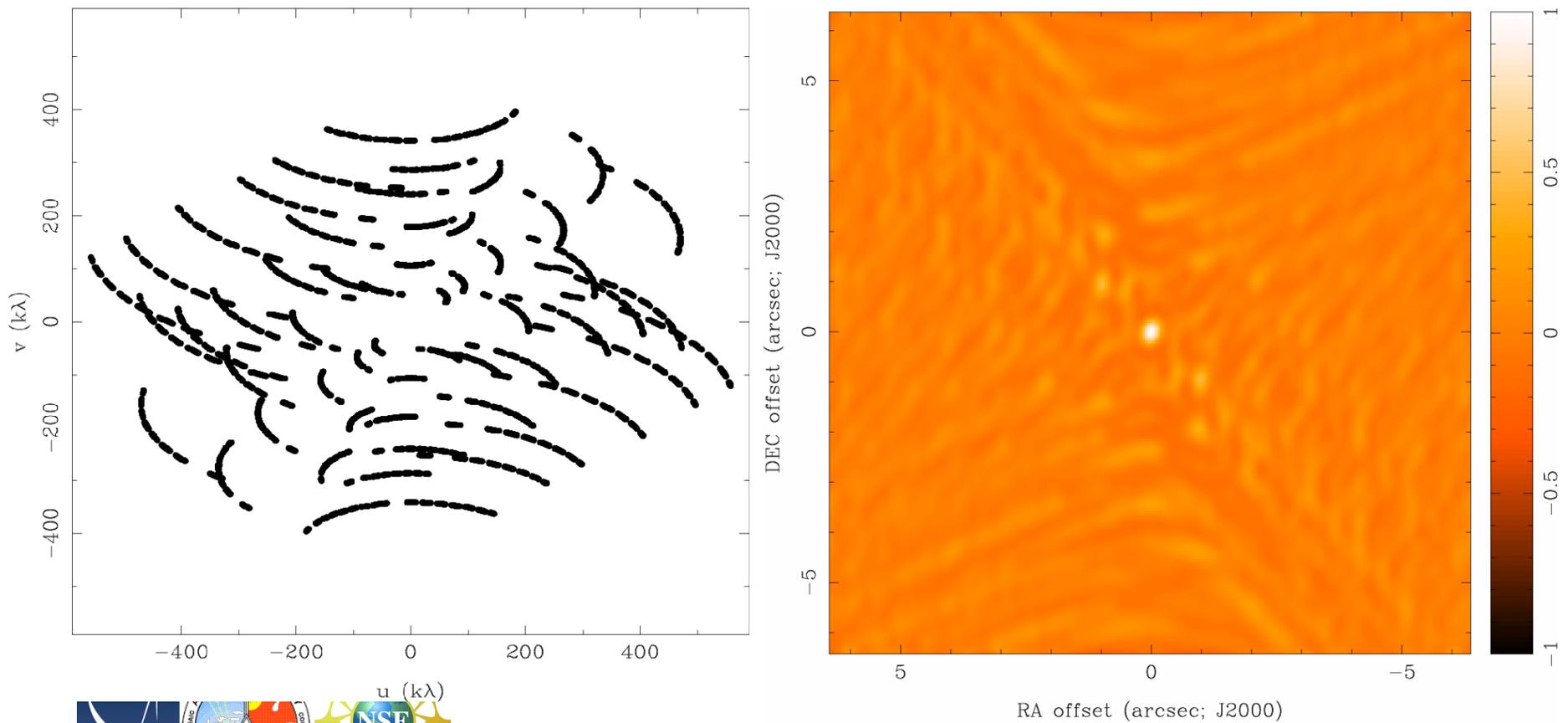
Dirty Beam Shape and N Antennas

8 Antennas x 120 Samples



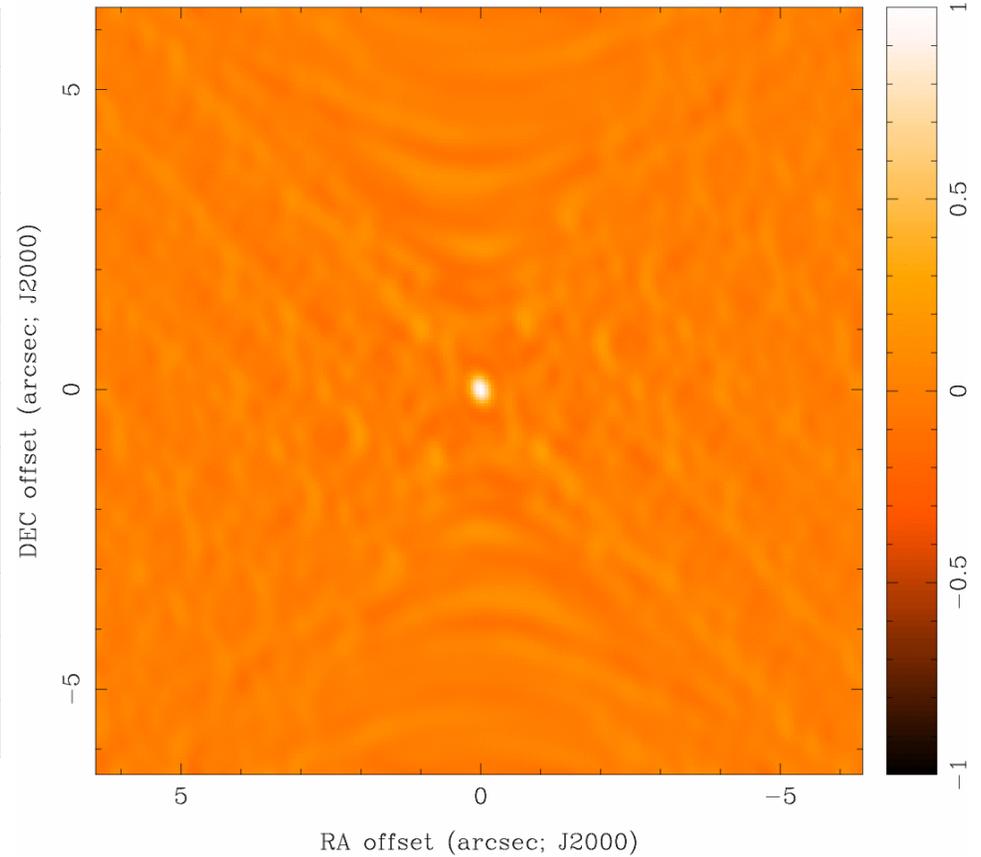
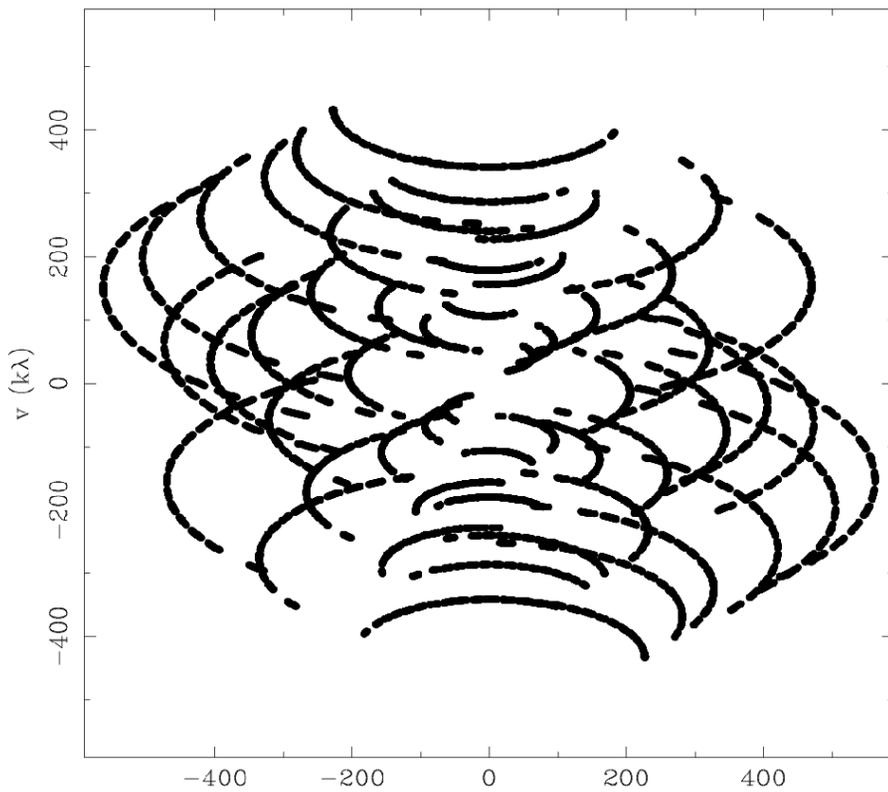
Dirty Beam Shape and N Antennas

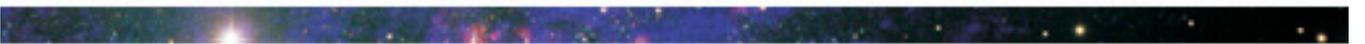
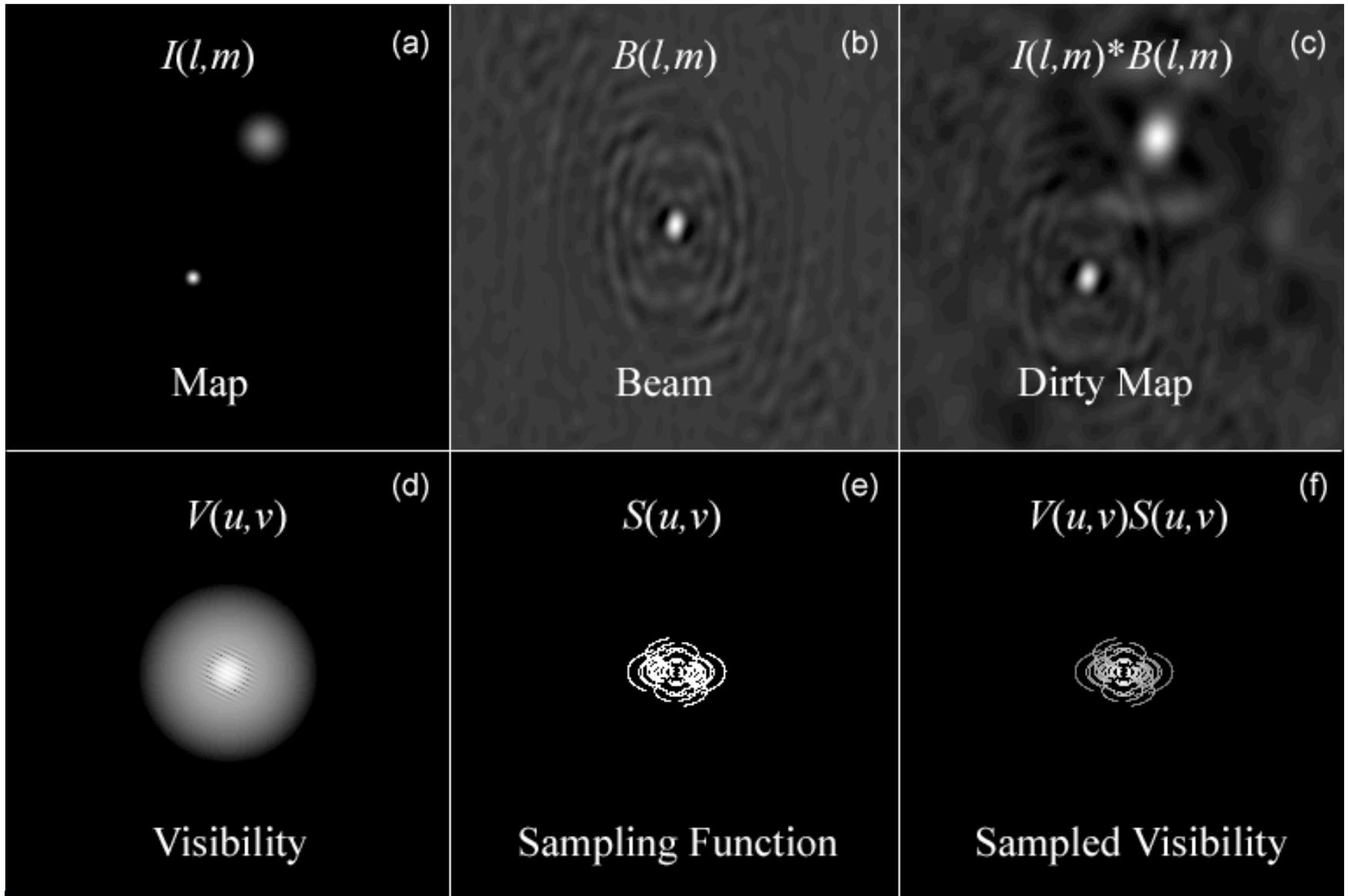
8 Antennas x 240 Samples



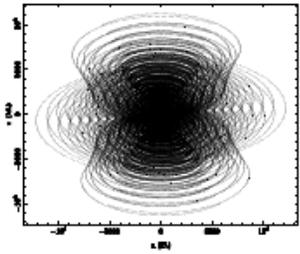
Dirty Beam Shape and N Antennas

8 Antennas x 480 Samples

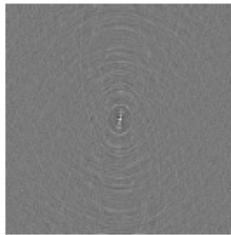




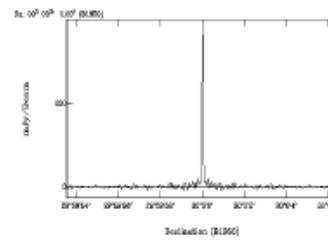
HD - coverage
VLA Konfiguration A



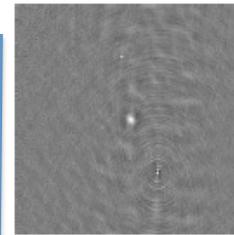
Dirty Beam



Dirty Beam Profil (vertikaler Schnitt)

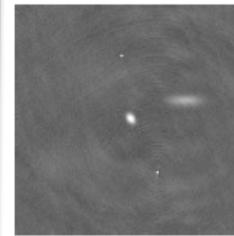
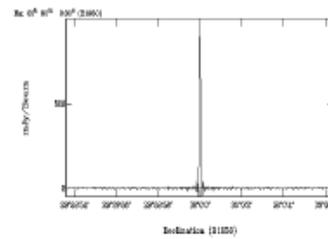
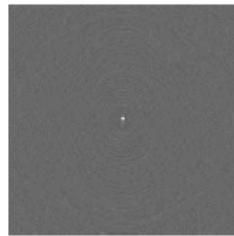
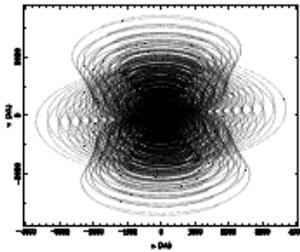


Dirty Image



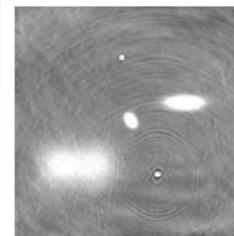
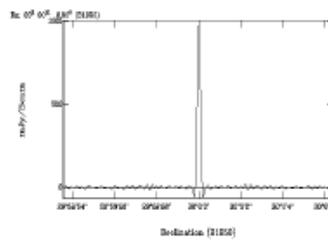
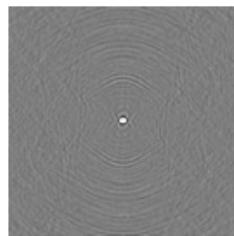
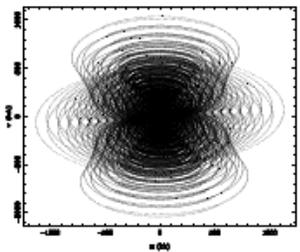
A-config 0.7-36km

VLA Konfiguration B



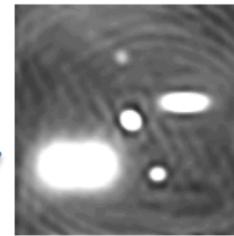
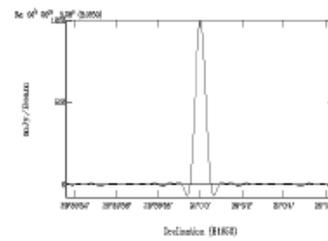
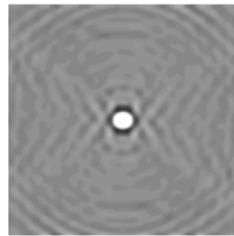
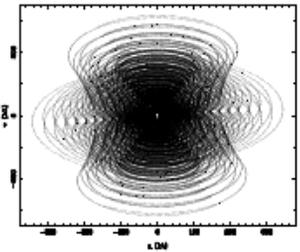
B-config 0.2-11km

VLA Konfiguration C



C-config 0.04-4km

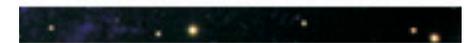
VLA Konfiguration D

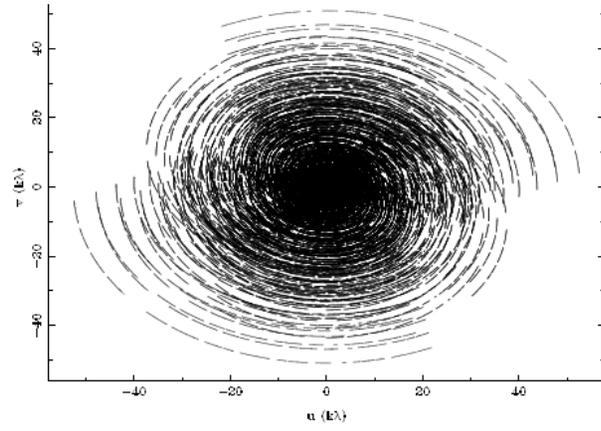


D-config 0.04-1km

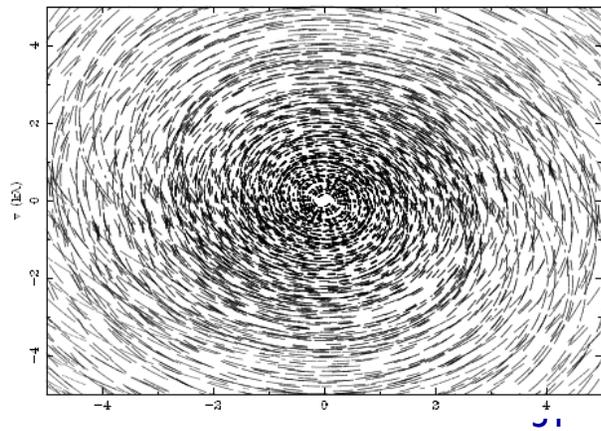
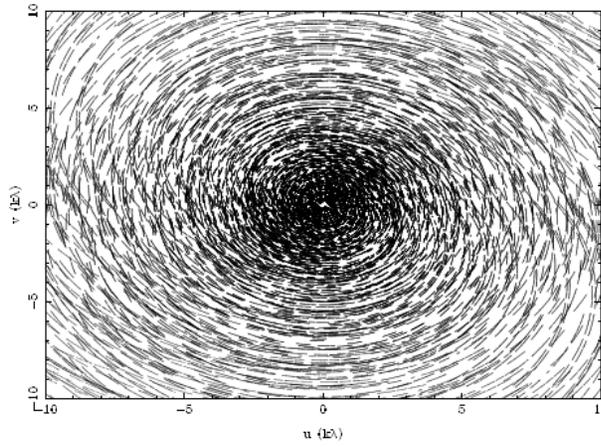
↑ resolution

↓ Surface brightness sensitivity



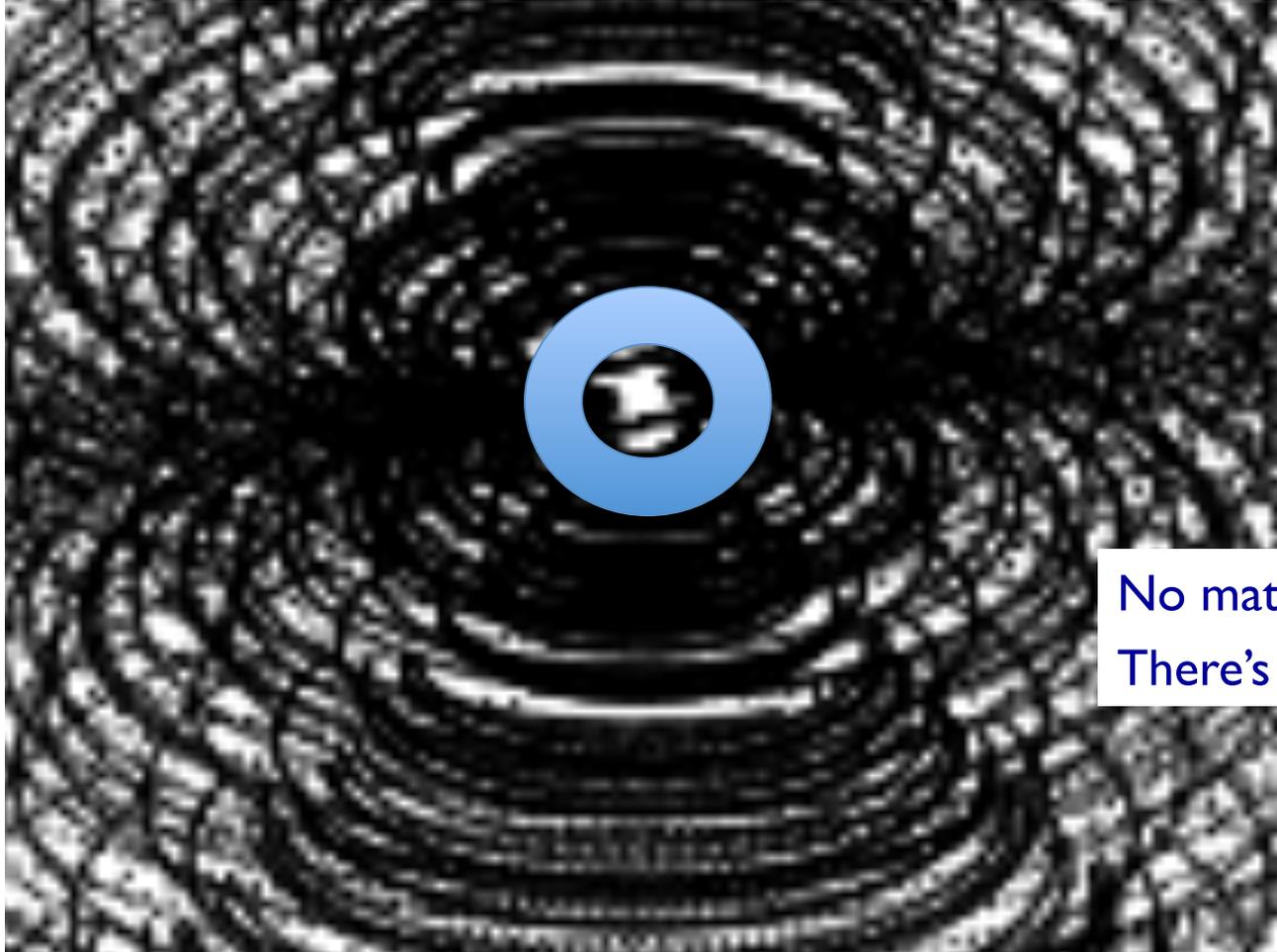


Let's zoom in!

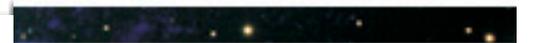
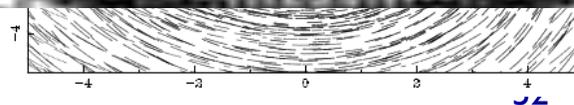




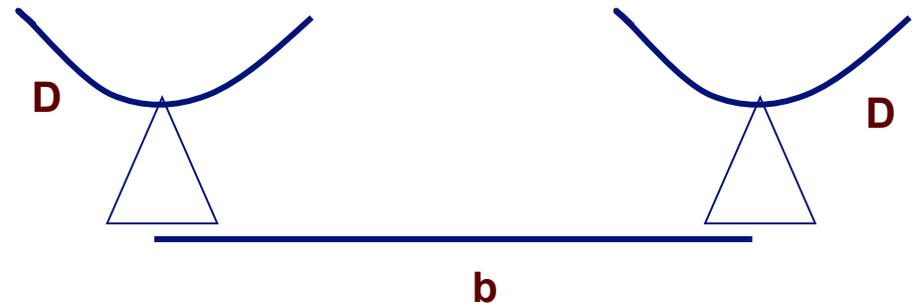
Let's zoom in!



No matter what you do,
There's always a central hole



uv-coverage

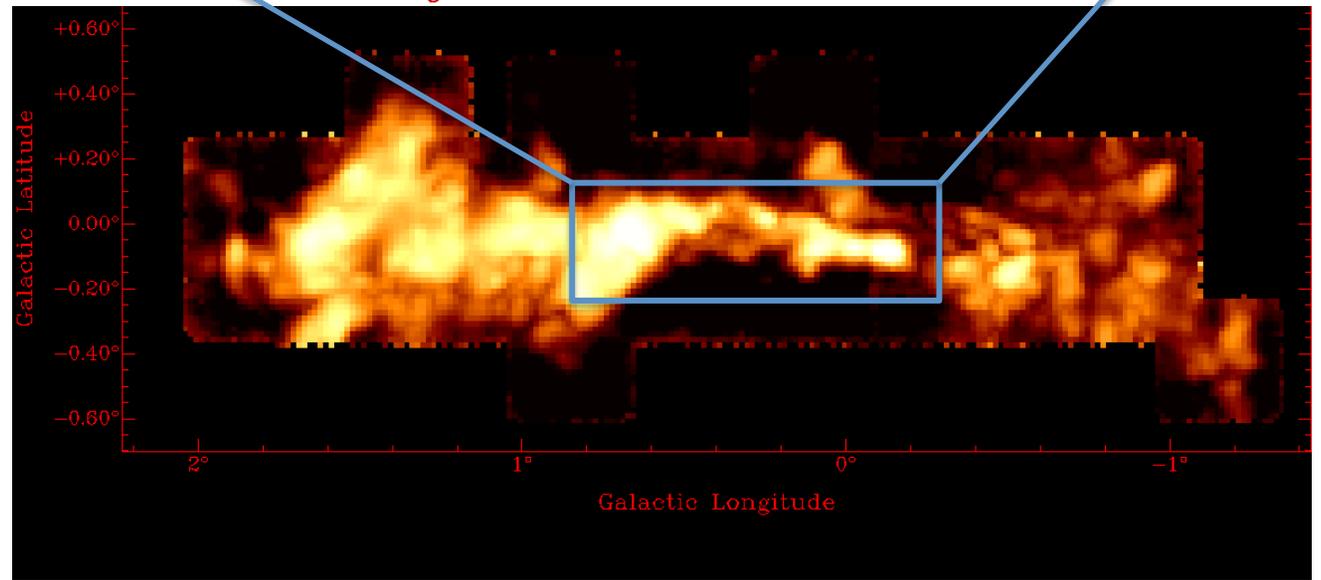
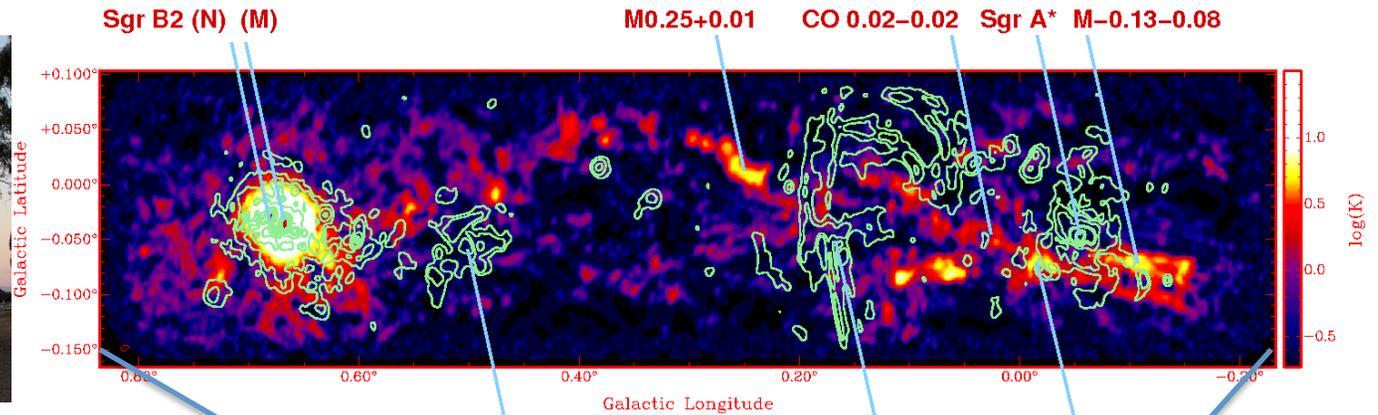


- What's the problem with the hole?
- It's the **short baselines**
- They define the largest spatial frequencies, or the largest angular scales that an interferometer is sensitive to
- The field of view is given by the beam of a single antenna
- The largest angular scale is given by the shortest distance between 2 antennas $\theta < 2\lambda/d_{\min}$
- Single antenna diameter $<$ shortest distance
- Field of view $>$ largest sensitive scale
- Extreme: full flux in field of view is given by the central pixel in the uv-coverage

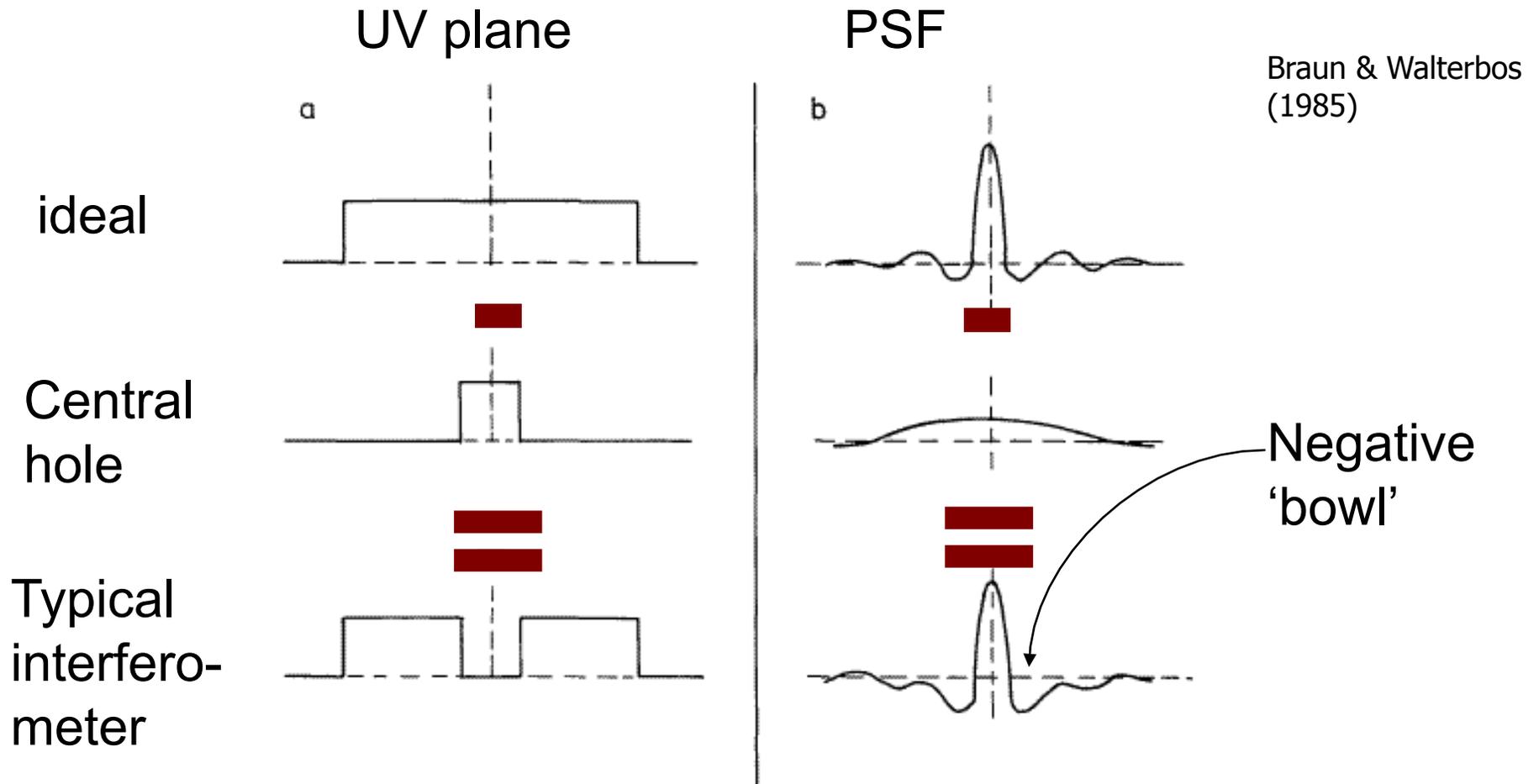
Short spacings & zero spacings problem



Short Spacing Problem



The short-spacing problem

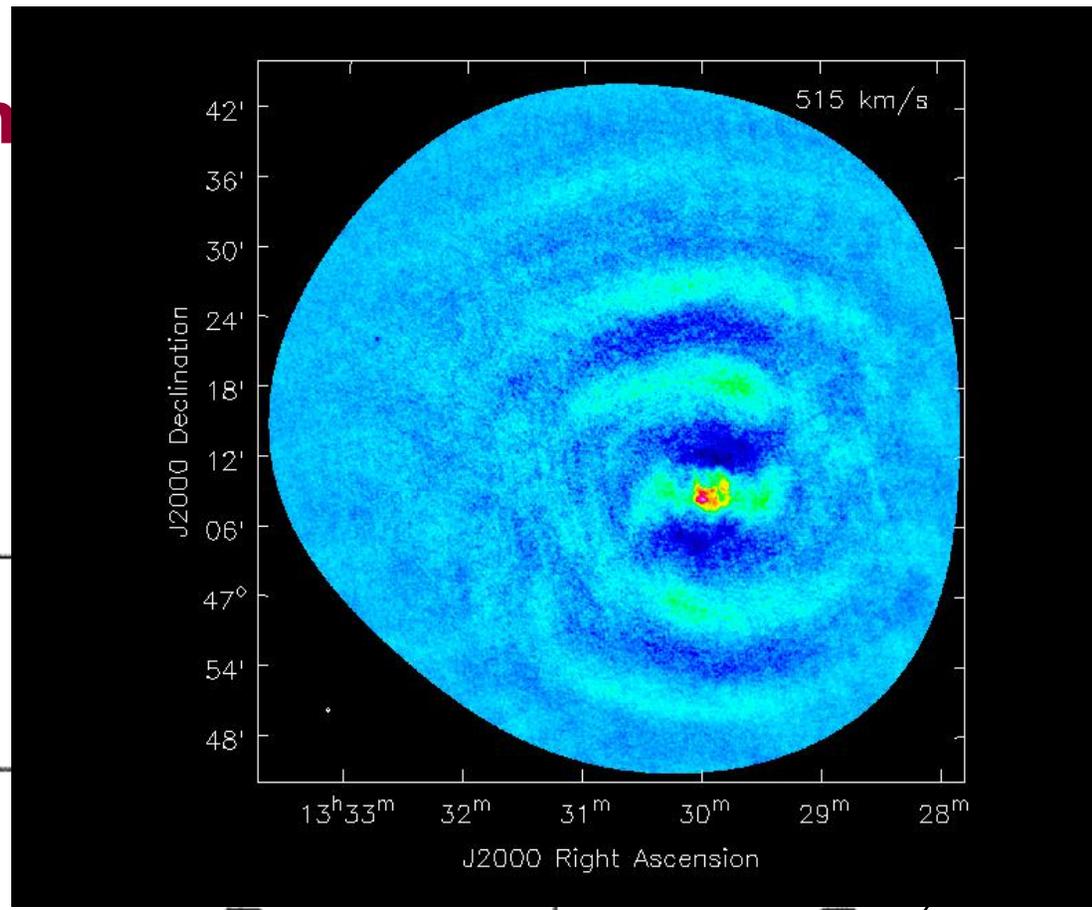


The shell

ideal

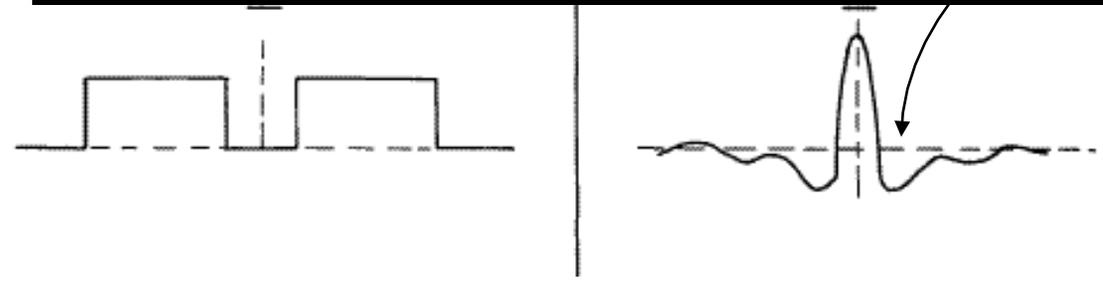
Central hole

Typical interferometer

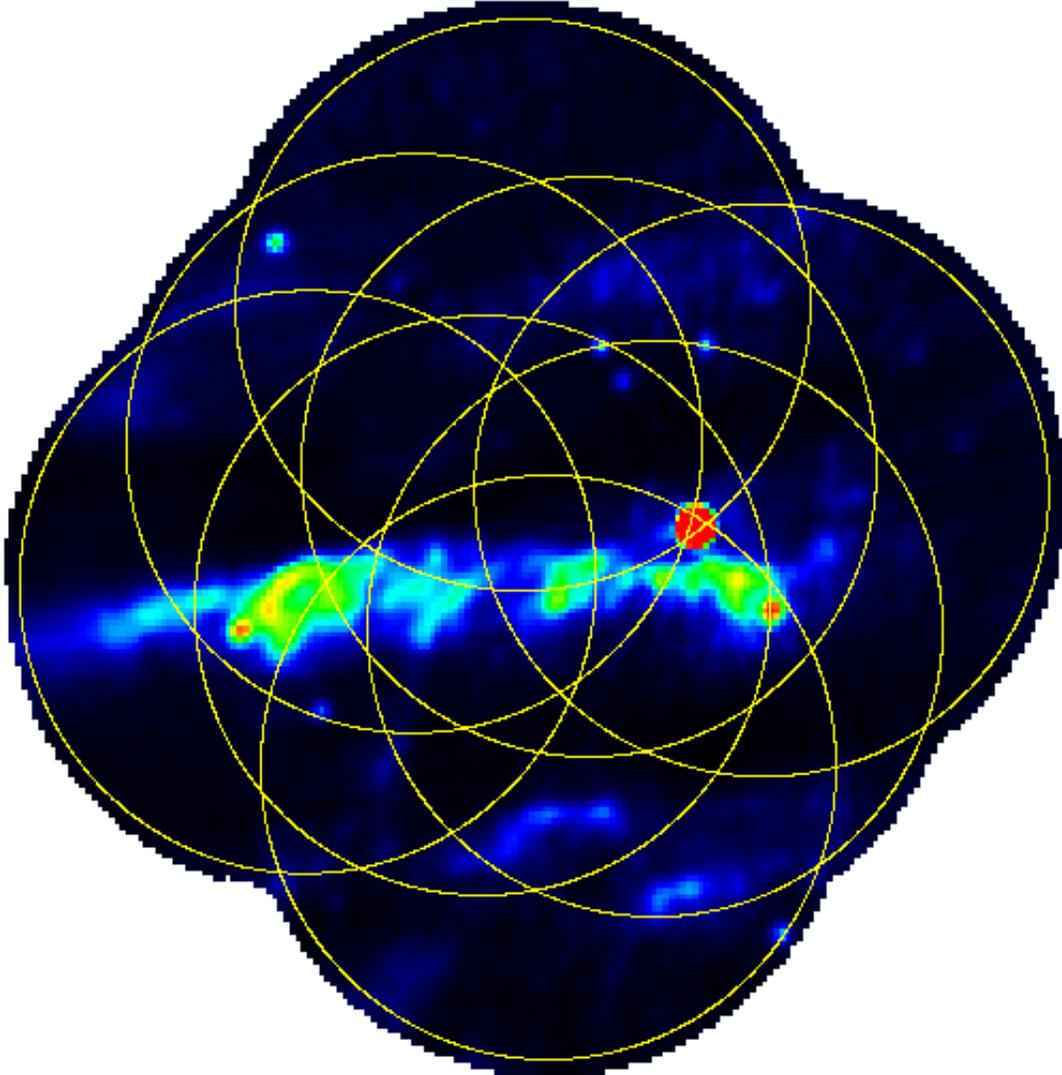


Braun & Walterbos (1985)

Negative 'bowl'

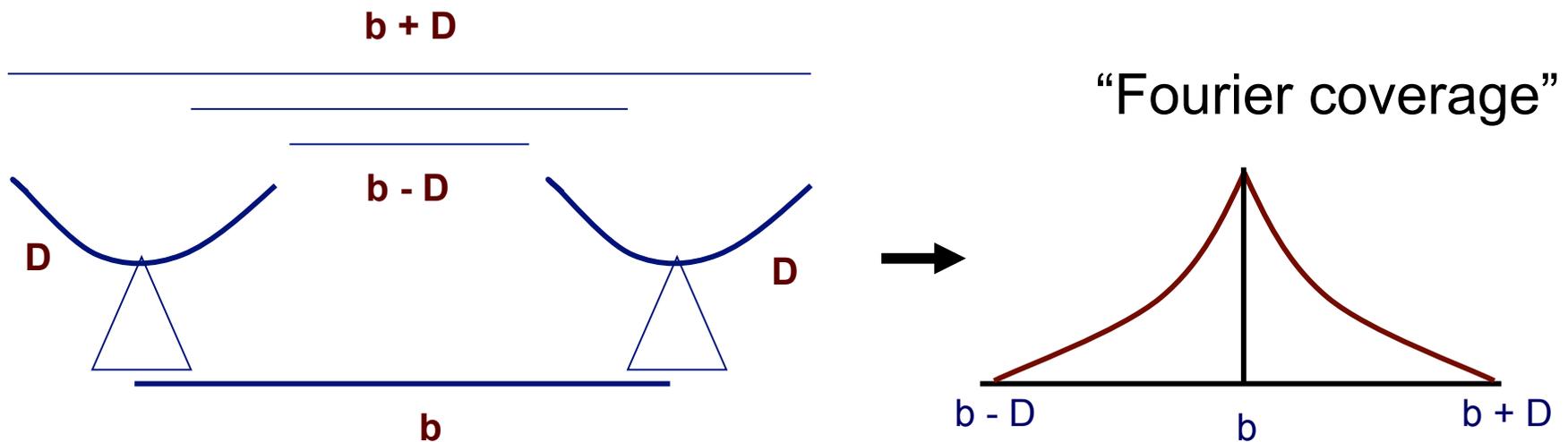


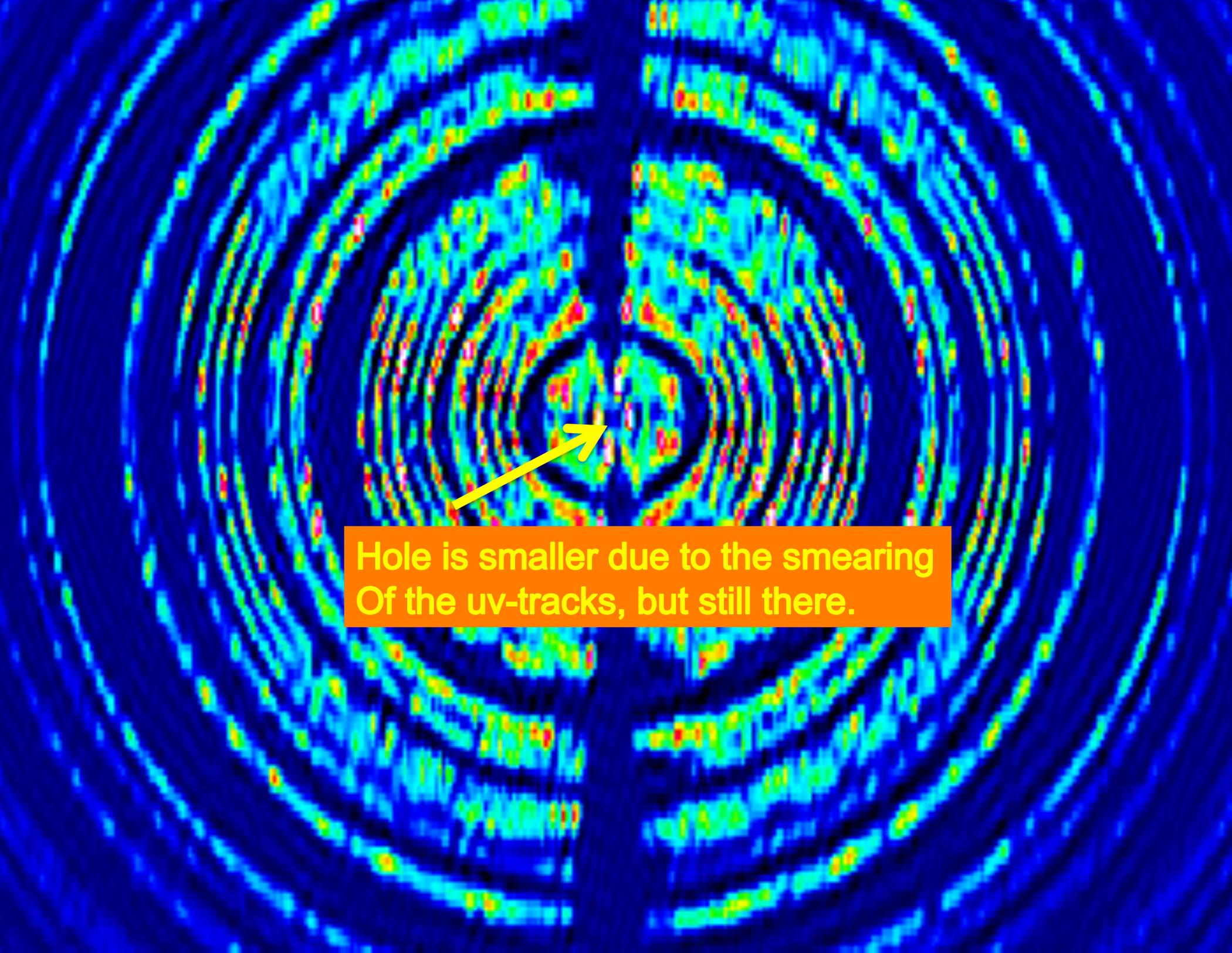
Mosaicing helps!



Ekers & Rots Theorem

- Extended this formalism to interferometers to show that an interferometer doesn't just measure angular scales $\theta = \lambda / b$ it actually measures $\lambda / (b - D) < \theta < \lambda / (b + D)$

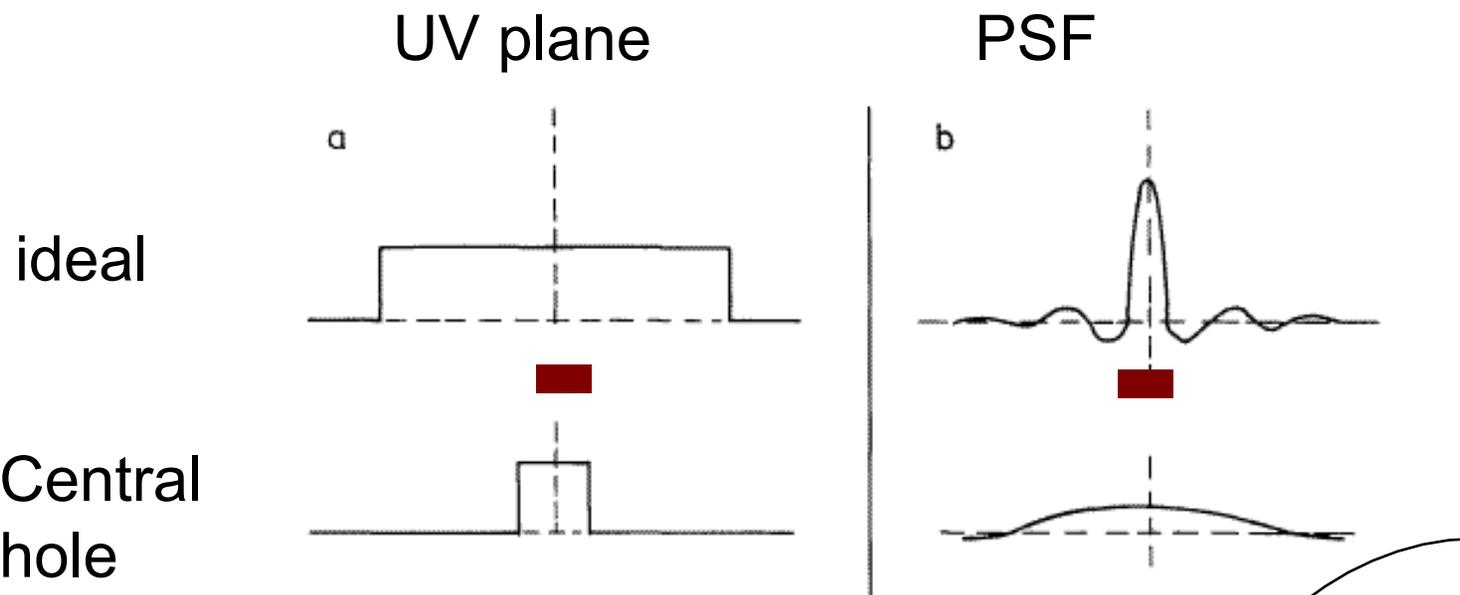




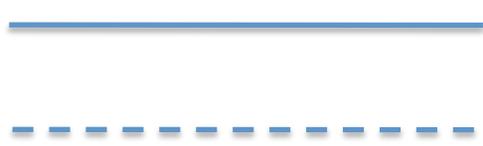
Hole is smaller due to the smearing
Of the uv-tracks, but still there.

The zero-spacing problem

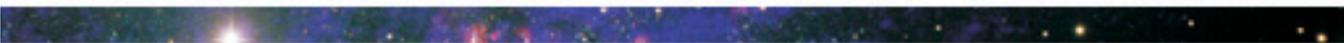
Braun & Walterbos
(1985)



The dirty map extended to infinity contains exactly a flux of zero!



Total Flux!

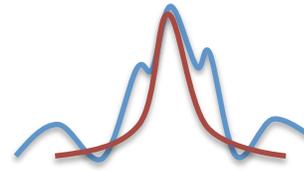


uv-coverage

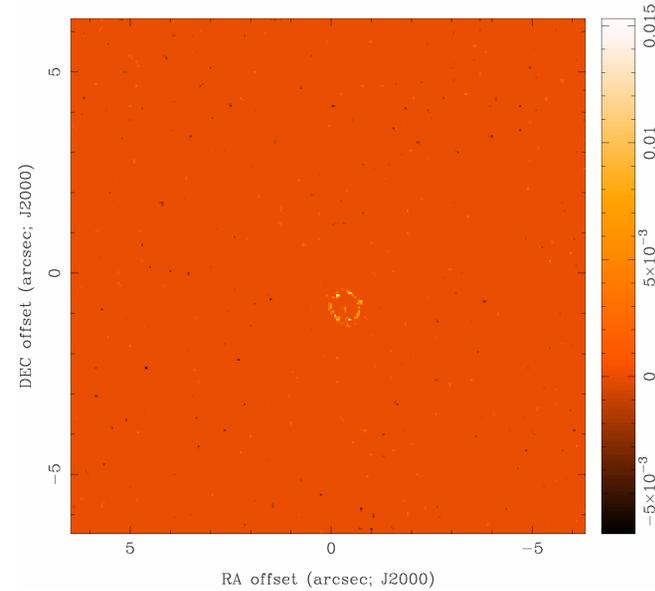
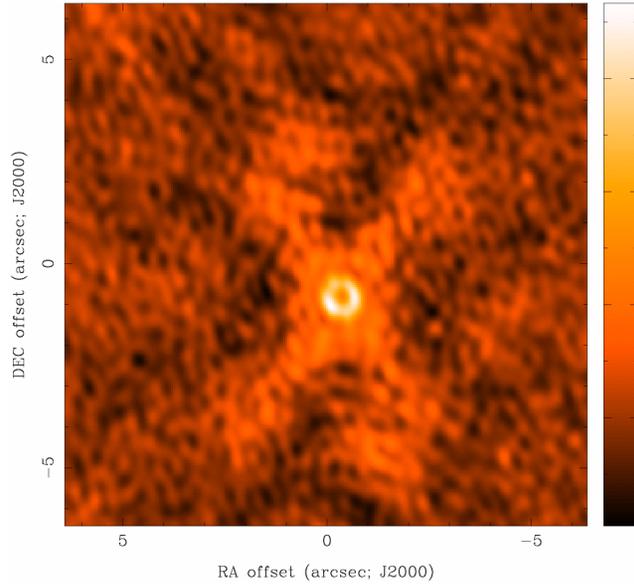
- **Solution (I)** deconvolution
- Take dirty map → find strongest source → remove dirty beam → write in table
- Fit dirty beam with Gaussian → clean beam
- Convolve table of positions and strengths with clean beam



CLEAN

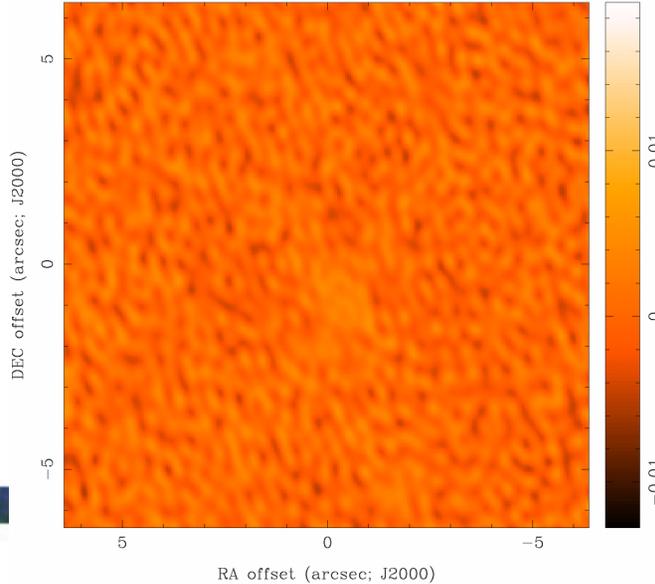
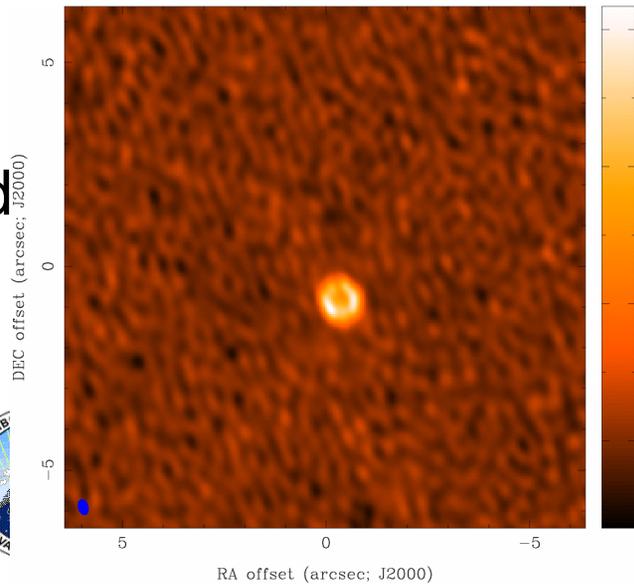


$T^D(x,y)$



CLEAN
model

restored
image



residual
map



dirty

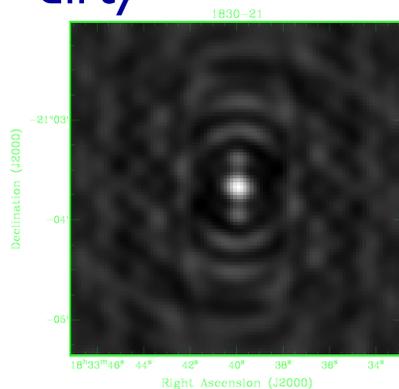
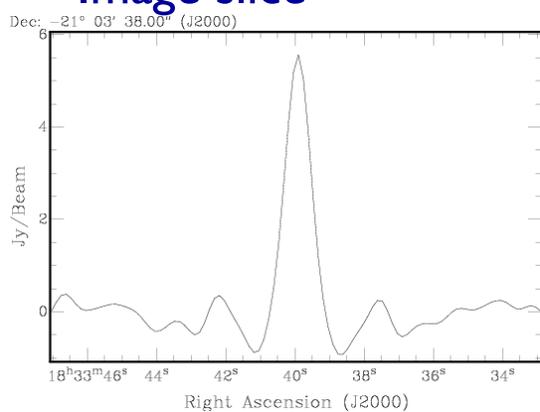
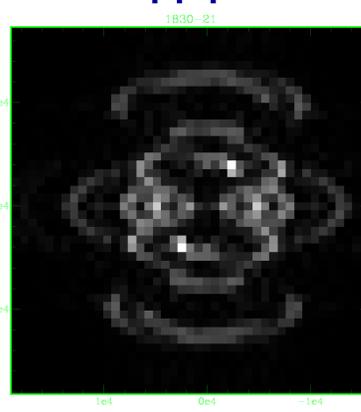


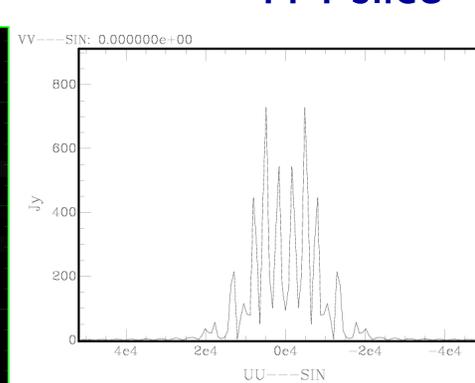
Image slice



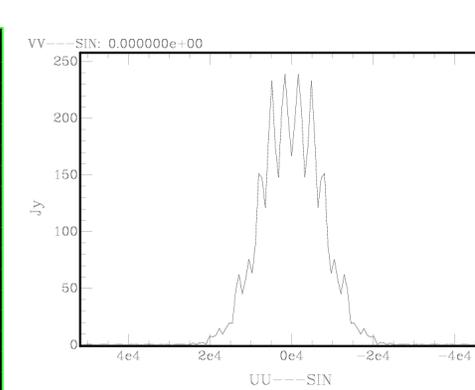
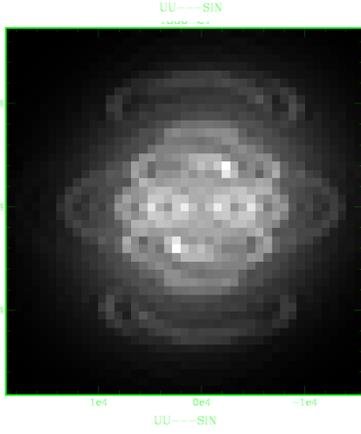
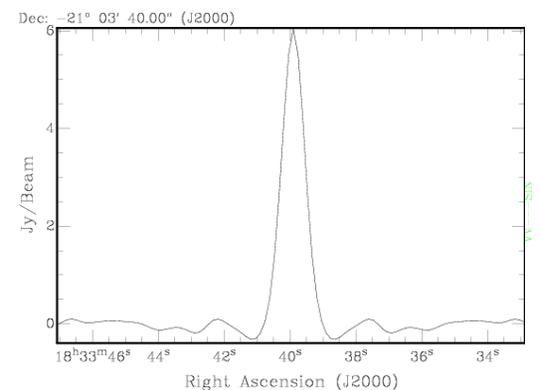
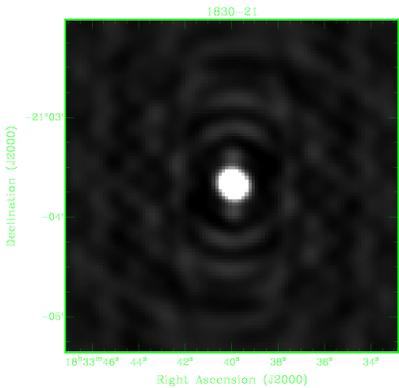
FFT



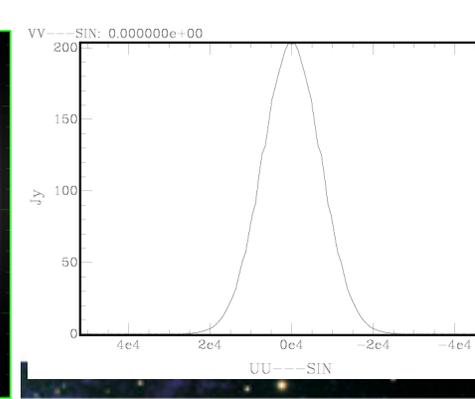
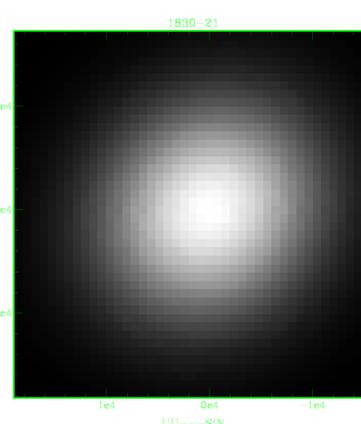
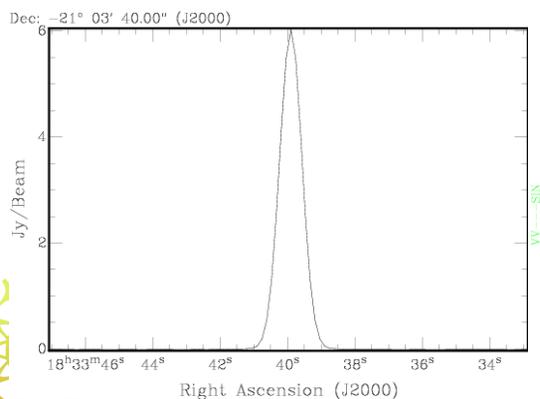
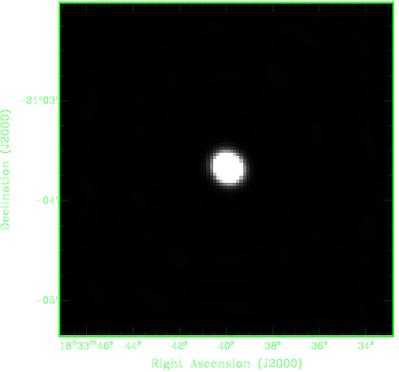
FFT-slice



Few iterations



more iterations



uv-coverage

- **Solution (I)** deconvolution
- Take dirty map → find strongest source → remove dirty beam → write in table
- Fit dirty beam with Gaussian → clean beam
- Convolve table of positions and strengths with clean beam
- CLEAN:
 - Makes nice images
 - Removes sidelobes
 - Interpolates visibilities
 - Removes gaps → gives a flux to the components (Σ sine waves have zero flux)
 - Extrapolates the short and zero spacing → estimates flux to full image



uv-coverage

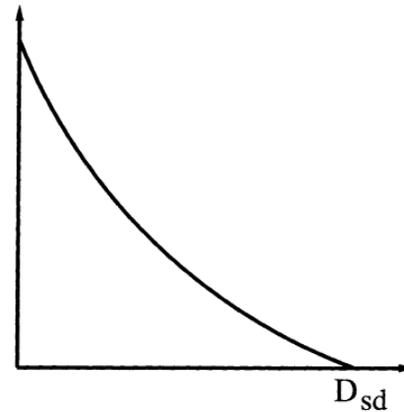
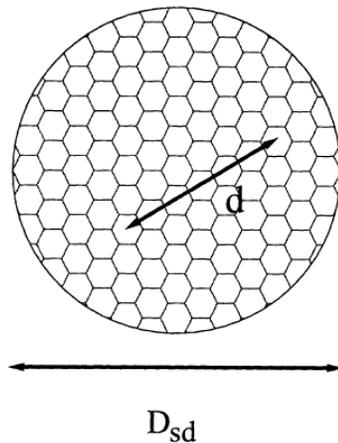
- **Solution (I)** deconvolution
- ‘classic’ CLEAN assumes that the image is composed of a number of point sources!
- This works to some extent but is clearly an issue when trying to decompose extended emission by δ -functions
- Other deconvolution methods that work better for extended structure:
- Multi-scale clean: go for different widths in addition to δ -functions
- Maximum entropy: maximize a “quality of fit” value between a model and the data

$$\mathcal{X} = - \sum_i I_i \ln \left(\frac{I_i}{M_i e} \right)$$



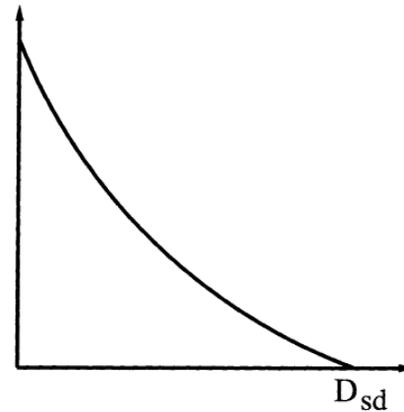
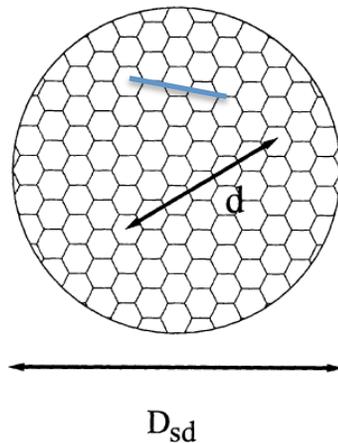
uv-coverage

- CLEAN **EXTRAPOLATES** to the central short and zero spacings
- Can we measure those instead?
- Yes!
- **Solution (2)** Short/zero spacing correction
- Short spacings due to minimum telescope distance, but what about a single dish?



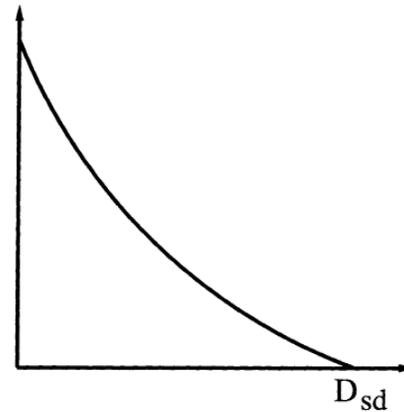
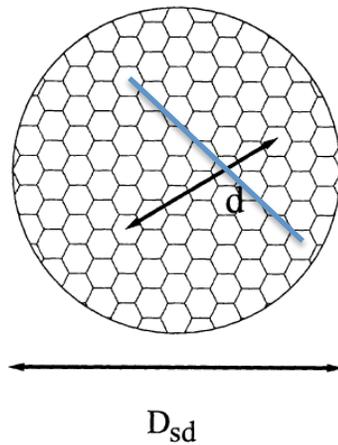
uv-coverage

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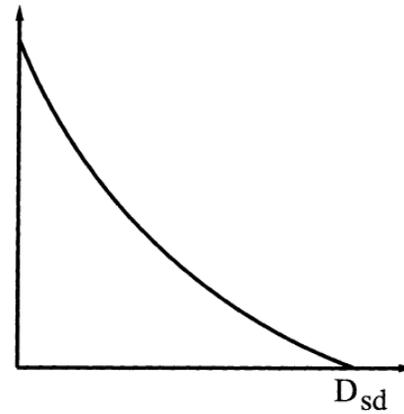
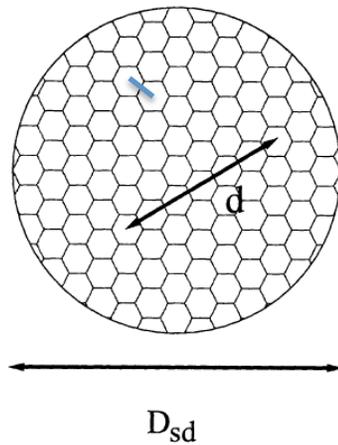
uv-coverage

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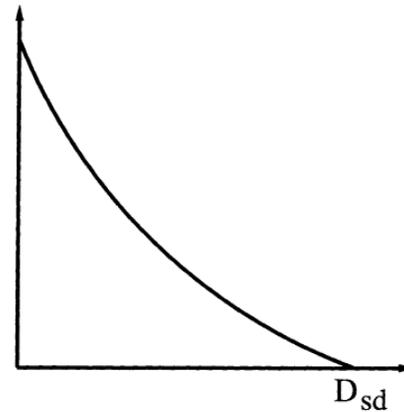
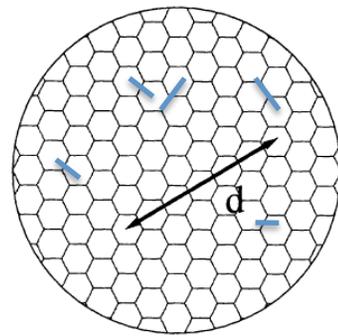
uv-coverage

- CLEAN **EXTRAPOLATES** to the central short and zero spacings
- Can we measure those instead?
- Yes!
- **Solution (2)** Short/zero spacing correction
- Short spacings due to minimum telescope distance, but what about a single dish?

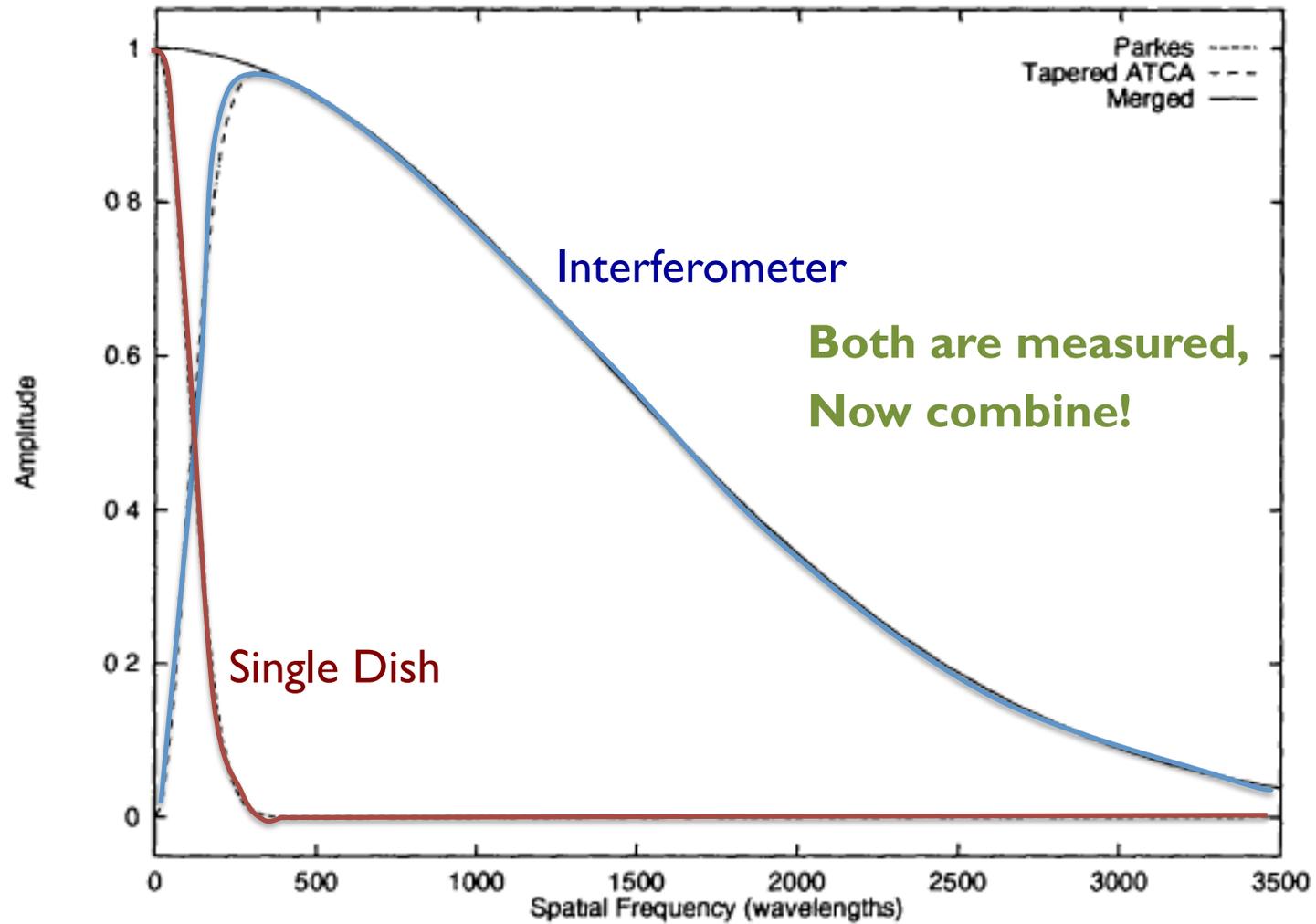


uv-coverage

- CLEAN **EXTRAPOLATES** to the central short and zero spacings
- Can we measure those instead?
- Yes!
- **Solution (2)** Short/zero spacing correction
- Short spacings due to minimum telescope distance, but what about a single dish?



uv-coverage



Practical aspects:

- What single dish to use?
- To cover all uv-ranges, One needs to observe at all spacings. So best to use a single dish that is larger than the minimum separation of interferometer antennas, e.g.

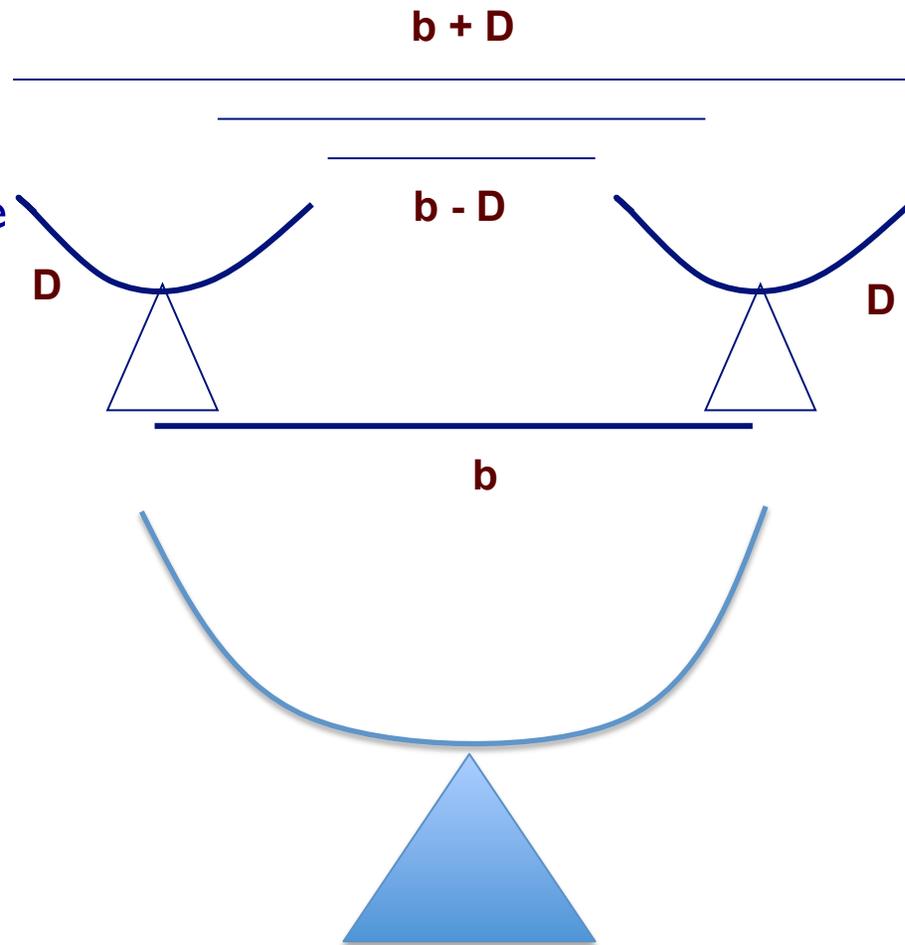
EVLA-C/D + GBT

EVLA-B + Arecibo

ATCA + Parkes

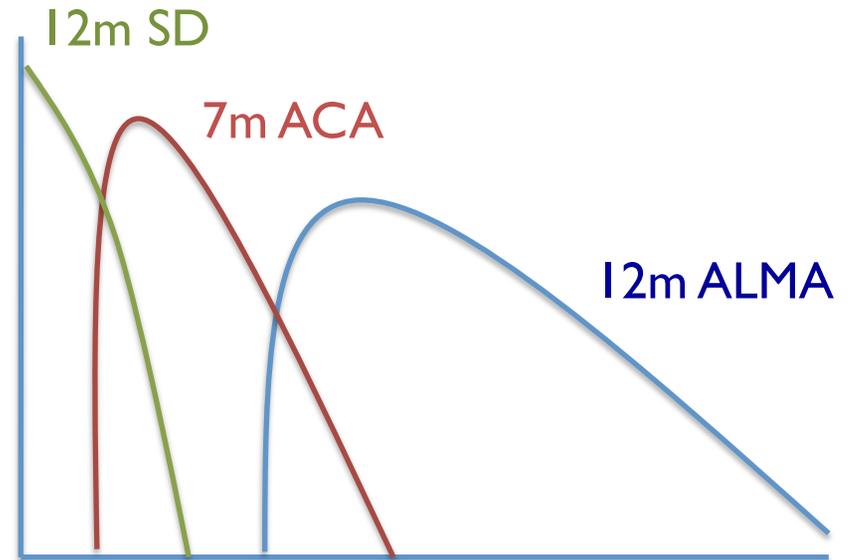
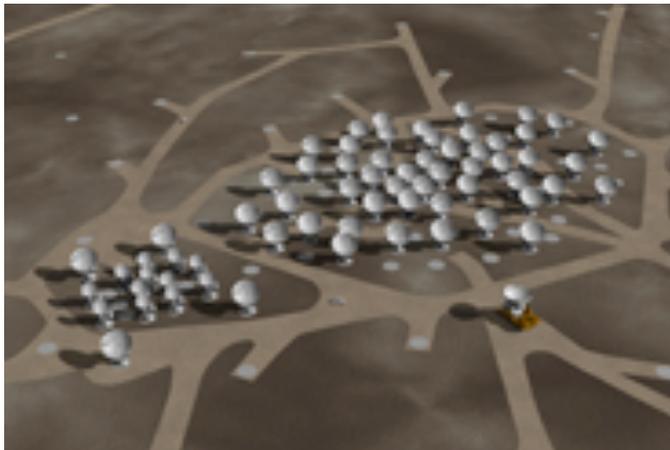
Plateau de Bure + Pico Veleta

CARMA + LMT



Interferometry

- ALMA approach:
- 12m antennas + 7m antennas +
- 12m antennas that operate as SD



Practical aspects:

- How deep?
- Surface brightnesses need to be adjusted, not point source sensitivity. Like go to the same sensitivity in K.
- SB sensitivity proportional to the beam area. So the single dish is usually not nearly as long per point as the interferometer observations
- Interferometer Antenna beam (fov) > SD beam > Interferometer synthesized beam
- BUT fov of SD is much smaller, so mapping may take longer than interferometer maps



Practical aspects:

- Can I use the autocorrelations of a single antenna in an array to be used as the single dish for the SSC?
- There will be a gap in the uv-domain as the diameter of the single dish is smaller than the minimum baseline
- However, the zero spacing may be covered, at least in theory
- Practically, a single dish needs a different observation technique, e.g. position switching, an interferometer stays on source interrupted by phase calibrator scans. The SD should also map the source where the interferometer may not
- On-the-fly mosaicking may be the solution, where the autocorrelations map the source and the reference can be constructed by a running median. We are at the beginning of testing such telescope modes



Methods – (I) Feathering

- Corrections:

$$f = \frac{S_{\text{int}}}{S_{\text{sd}}}$$

$$\alpha = \frac{\Omega_{\text{int}}}{\Omega_{\text{sd}}}$$

Calibration adjustment

beam/SB scaling



Methods – (I) Feathering

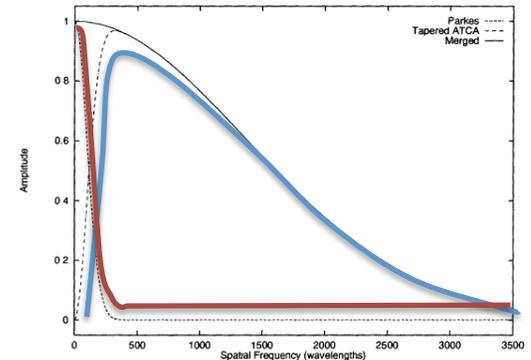
- All radio images are weighted/convolved by the radio beams!

$$I' = I \otimes B$$

$$\Rightarrow FFT(I') = FFT(I) * FFT(B)$$

$$FFT(I) = FFT(I'_{int}) / FFT(B_{int})$$

$$FFT(I) = FFT(I'_{SD}) / FFT(B_{SD})$$

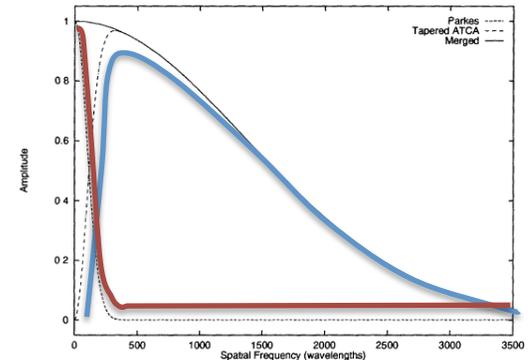


= in the overlap region



Methods – (I) Feathering

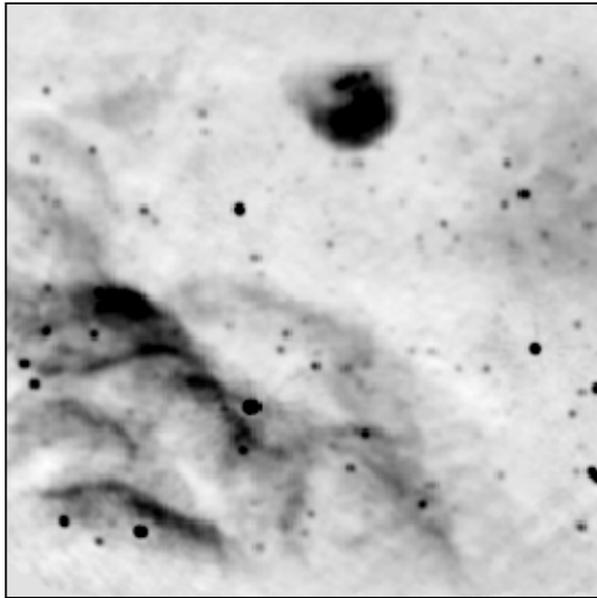
- Practically: weigh the visibilities along the FFT of the synthesized beam (synthesized beam is the large scale Gaussian over a uv-coverage)



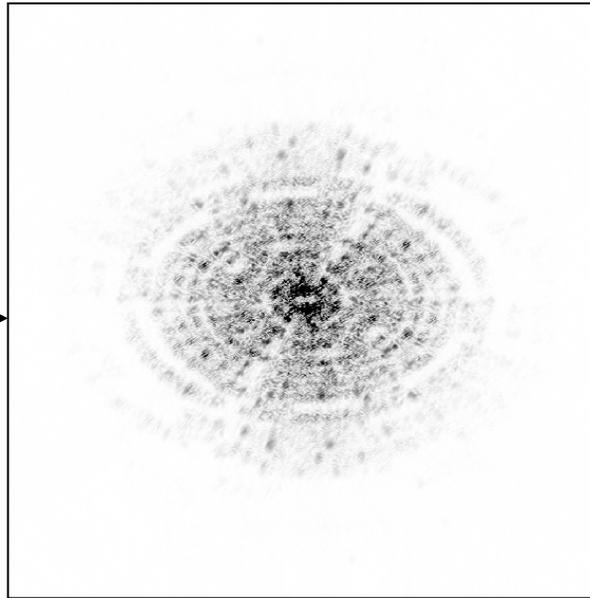
$$V_{comb}(k) = w'(k)V_{int}(k) + fw''(k)V'_{sd}(k)$$

$$w'(k) + w''(k) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{\theta_{int}^2 k^2}{4 \ln 2}\right)$$



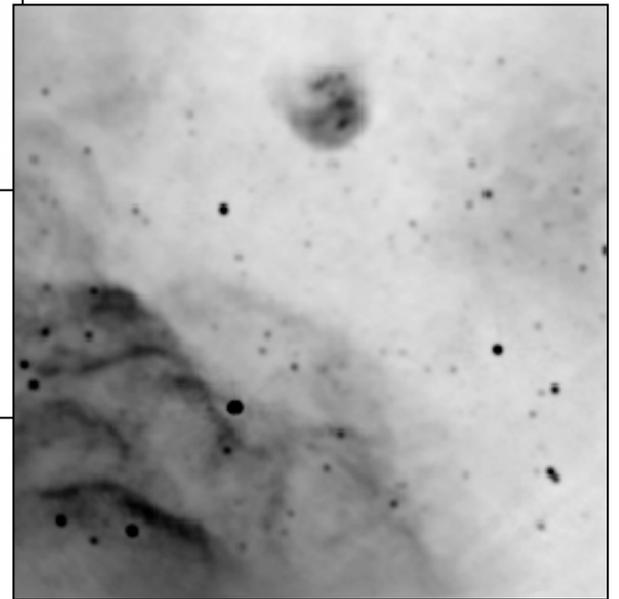


FT

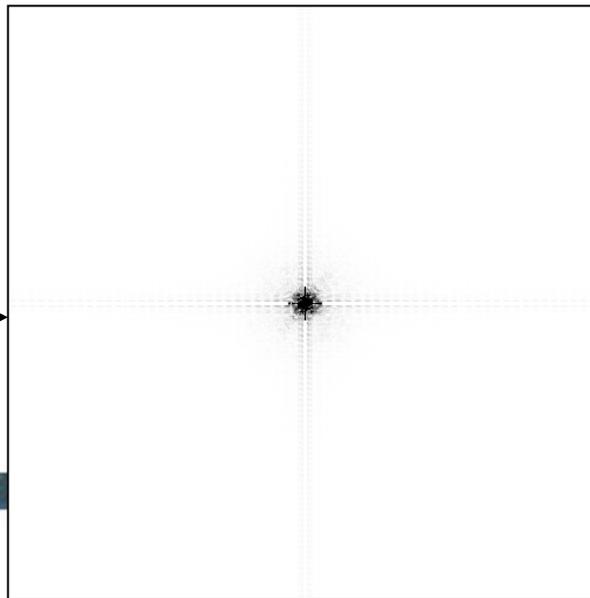


Example of Fourier
plane combination:
McClure-Griffiths et al.

$$+ \int_x^{cal} \text{FT}^{-1} =$$

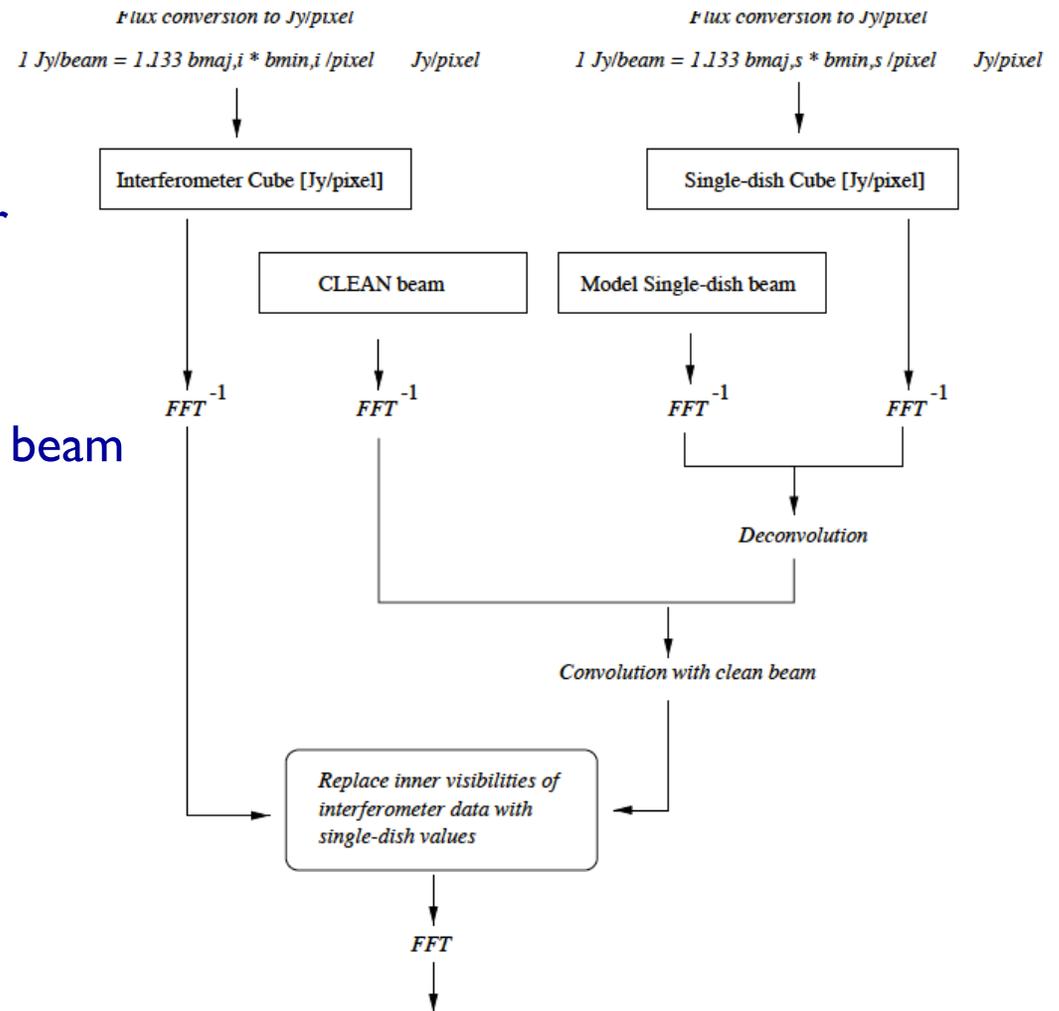


FT



Methods – (2) Feathering w/o weighting

- Clean interferometric dataset & replace extrapolated center by SD visibilities, then FFT
- Deconvolve SD map from SD beam
- Convolve it with Int. beam
- Replace inner uv hole with SD values
- FFT into image



Weiss et al.



Methods – (3) ‘Linear’ Combination in Image Domain

Combined image:

$$I_{\text{tot}} = w_{\text{int}} I_{\text{int}} + w_{\text{sd}} f_{\text{sd}} I_{\text{sd}}$$

Weights:

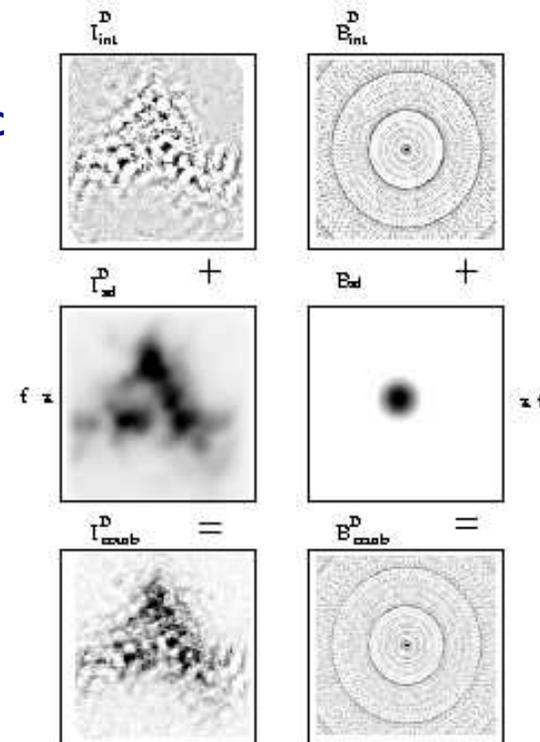
$$w_{\text{int}} = \frac{\Omega_{\text{sd}}}{\Omega_{\text{int}} + \Omega_{\text{sd}}}$$

$$w_{\text{sd}} = \frac{\Omega_{\text{int}}}{\Omega_{\text{int}} + \Omega_{\text{sd}}}$$

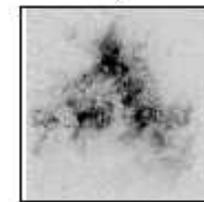
Interferometric
Dirty image
and beam

SD image
and beam

Combination



DECONVOLVE



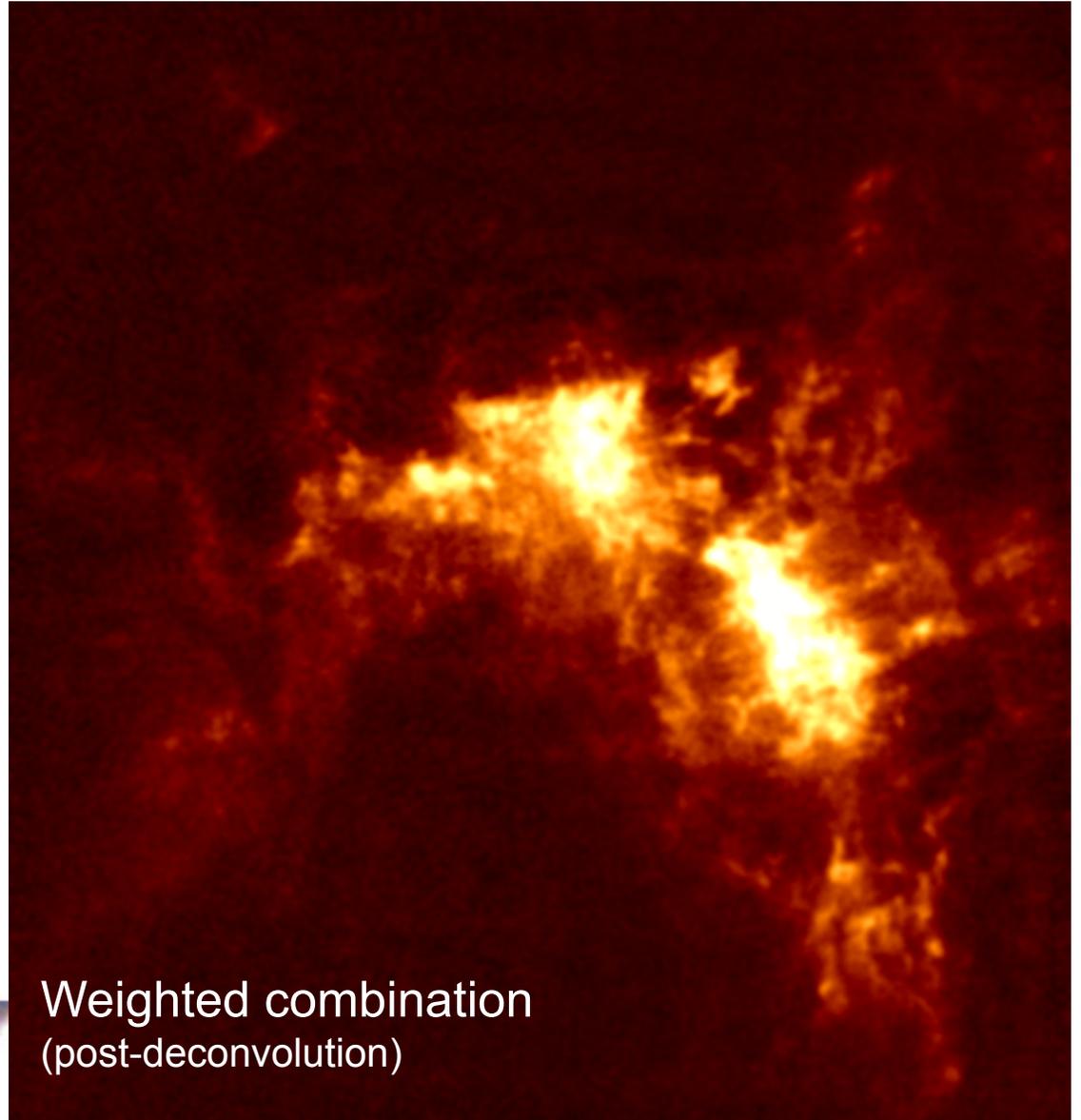
deconvolve

Stanimirovic et al.



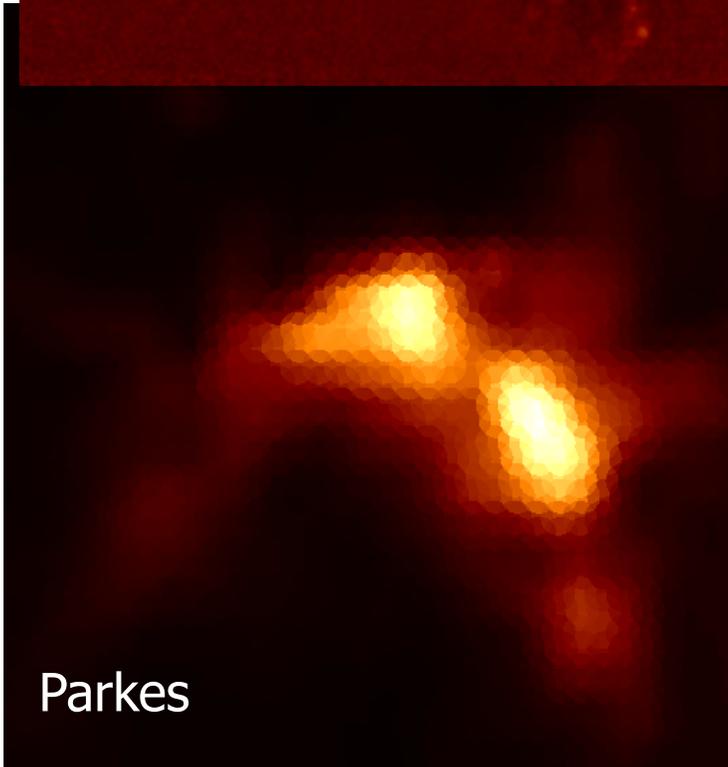
ATCA (post-deconvolution)

Example of image-plane combination:
SMC in HI at $V_h = 130$ km/s
(Stanimirovic et al 1999)



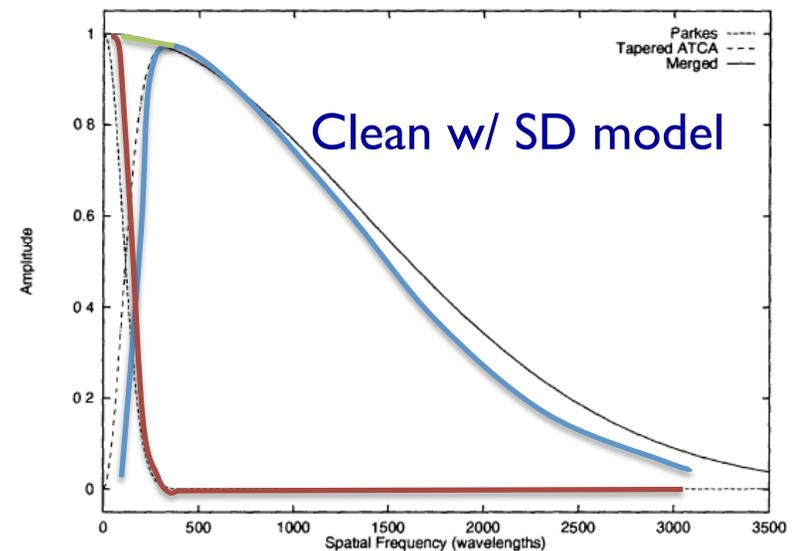
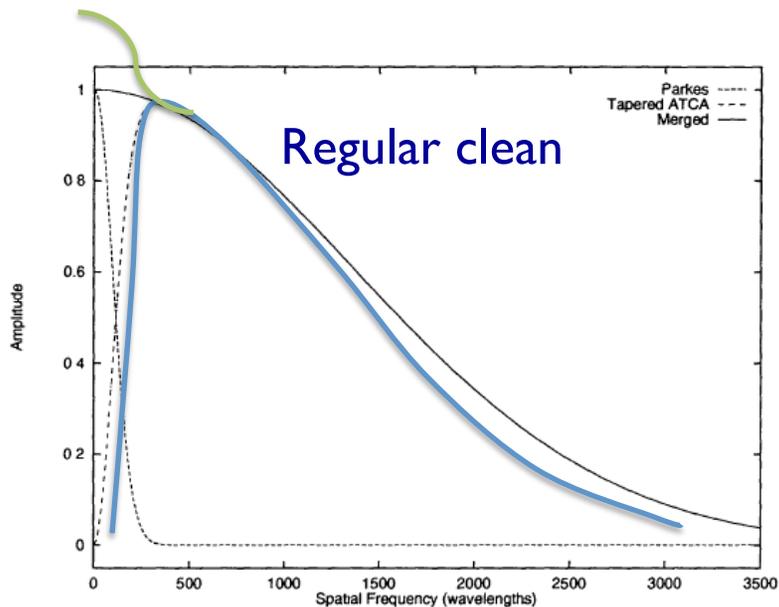
Weighted combination
(post-deconvolution)

Parkes



Methods – (4) SSC during Deconvolution

- One can use the SD image as a starting model for the deconvolution. Works best with multi-scale-cleaning or maximum-entropy
- What it does: clean will not extrapolate anymore but intrapolate!



Methods – (4) Joint Deconvolution

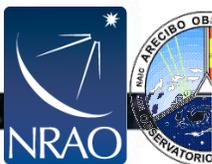
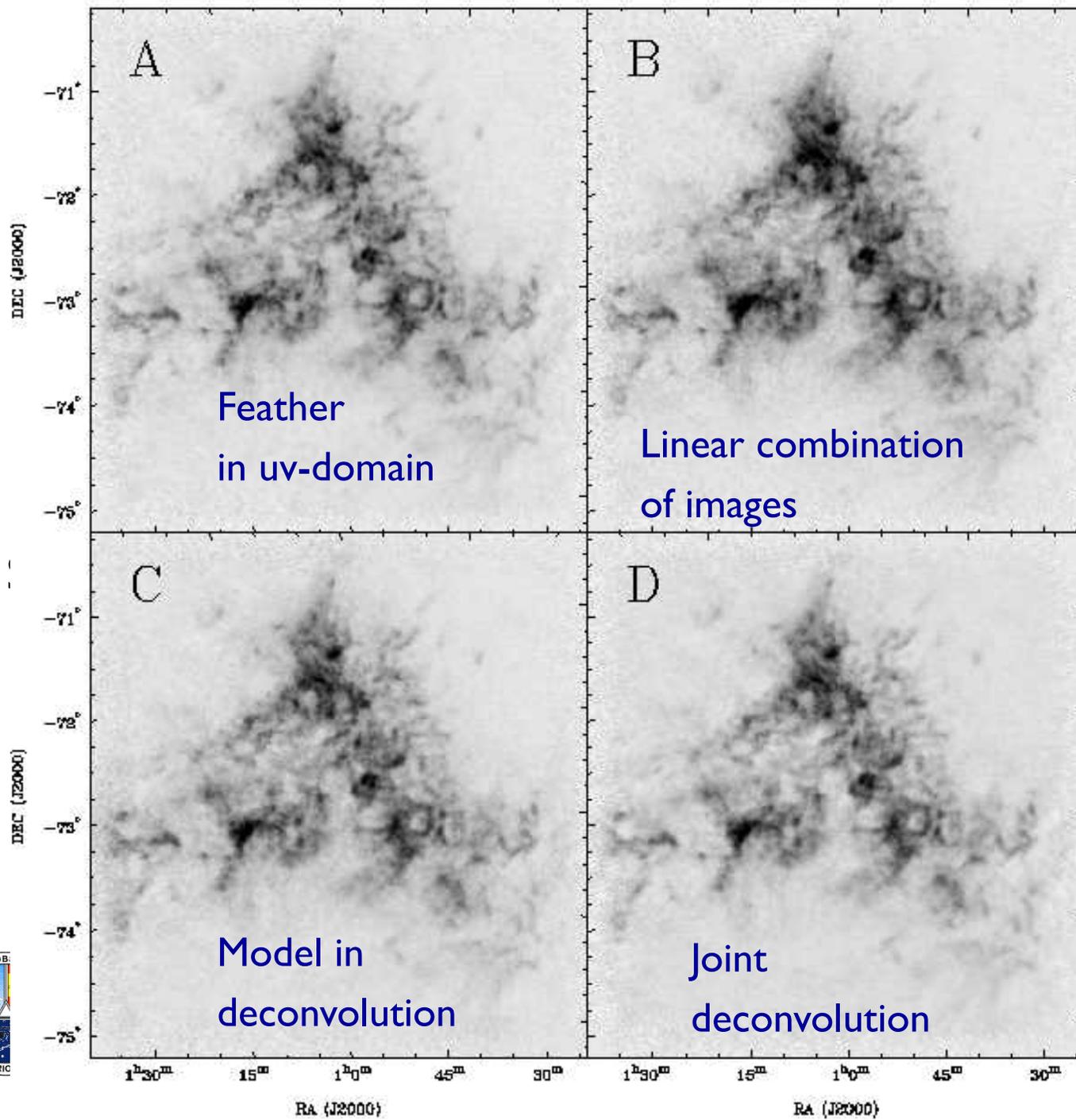
- Deconvolve both images simultaneously, with 2 conditions for improving the quality (entropy)

$$\mathcal{N} = - \sum_i I_i \ln \left(\frac{I_i}{M_i e} \right)$$

Subject to (1) $\sum_i \left\{ I_{\text{int}}^D - B_{\text{int}} * I \right\}_i^2 < N \sigma_{\text{int}}^2$

(2) $\sum_i \left\{ I_{sd}^D - \frac{B_{sd} * I}{f_{sd}} \right\}_i^2 < M \sigma_{sd}^2$





Summary

- Interferometric imaging lack spatial sensitivity on large scales (including the full flux over an image) (minimum baseline)
- SD lacks the high resolution an interferometer can get to (maximum baseline)
- Lack of inner uv-points create bowls in the image
- CLEAN extrapolates fluxes and structures into images which sometimes work sometimes not. Regular CLEAN assumes point sources (bad) more sophisticated methods like MEM and multi-scale clean can do better
- Even better than extrapolation is a SD measurement to determine the very inner uv-points
- The beams play an important role – know well you SD beam! Also calibrate your data well!
- Methods of combination incl. uv-domain, image domain, and deconvolution at different stages

