

Data Reduction Workshop

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Wide-band Wide-field Imaging

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Why new algorithms?

- Instantaneous wide-band capability of the EVLA is the single dominant parameter that enables new scientific capabilities

$$\text{Noise} \propto \frac{T_{\text{sys}}}{A_{\text{eff}} \sqrt{\Delta \nu \Delta T}}$$

- More instantaneous information about the emission
 - Spectral Index, RM,...

$$V_{ij}(\nu) = G_{ij}^{DI} W_{ij} \int \underbrace{P_{ij}(s, \nu, t) I(s, \nu) e^{i s \cdot b_{ij}}}_{\text{Direction Dependent (DD) terms}} ds$$

- Terms inside the integral cannot be accounted-for before imaging
 - Conventional imaging ignores DD terms
 - Also ignores time, frequency and polarization dependence
- Solutions: Project-out the effects during imaging + model frequency dependence of the sky during deconvolution
- Or resort to spectral cube imaging + image-plane corrections/averaging

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PB Effects
(A-Projection)

↙

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Spectral Index effects
(MT-MFS)

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Non co-planar baselines (W-term)
(W-Projection)

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Plan

- Wide-band Imaging

- Account for frequency dependent sky brightness distribution
- Algorithm: Multi-term Multi-Frequency Synthesis (MT-MFS, MS-MFS)

[Rau & Cornwell, A&A, 2011]

- Wide-field Imaging: Includes any effect that increases with R

- Non co-planar baseline effect (W-term) [Cornwell, Golap, Bhatnagar, Proc. IEEE, 2009]
- Effect of antenna PB: Time- and Poln.-dependence [Bhatnagar et al., A&A, 2008]
 - Includes mosaic imaging
- Algorithm: W-Projection, (WB) A-Projection

[General review: Rau et al., Proc. IEEE, V. 97 (8) 2009]

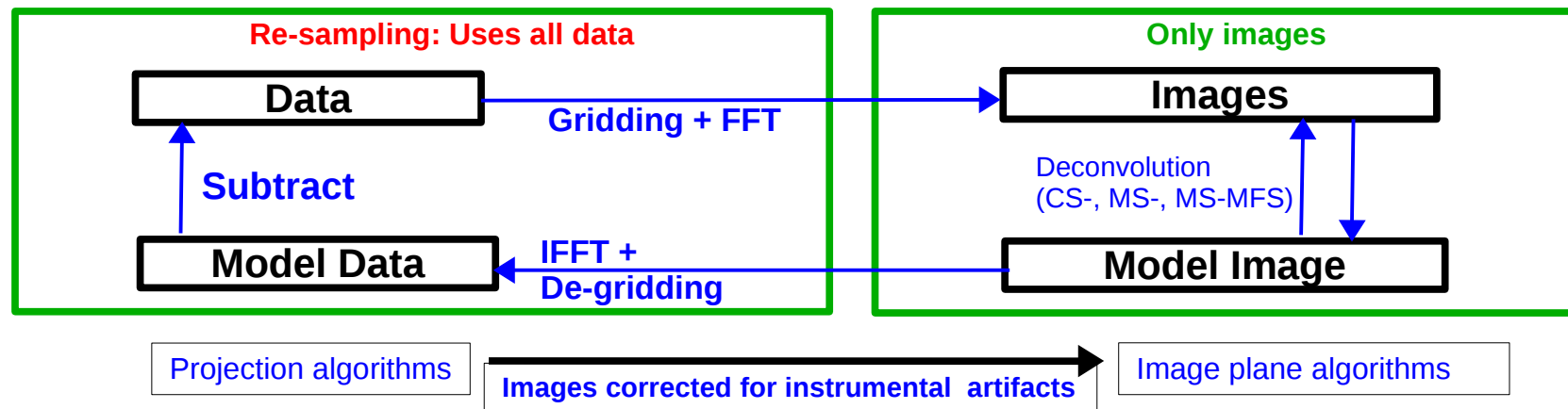
- Wide-band Wide-field Imaging

- All of the above + PB frequency dependence [Bhatnagar et al., A&A, 2012]
- Algorithm: MT-MFS + (WB) AW-Projection (+ Mosaic) [WB Mosaic: Rau, Bhatnagar, Golap, In prep.]



Imaging & Deconvolution: A recap

- Compute residuals using the original data
 - Needs Gridding and de-Gridding during major-cycle iterations



W-Projection

A-Projection

WB A-Projection

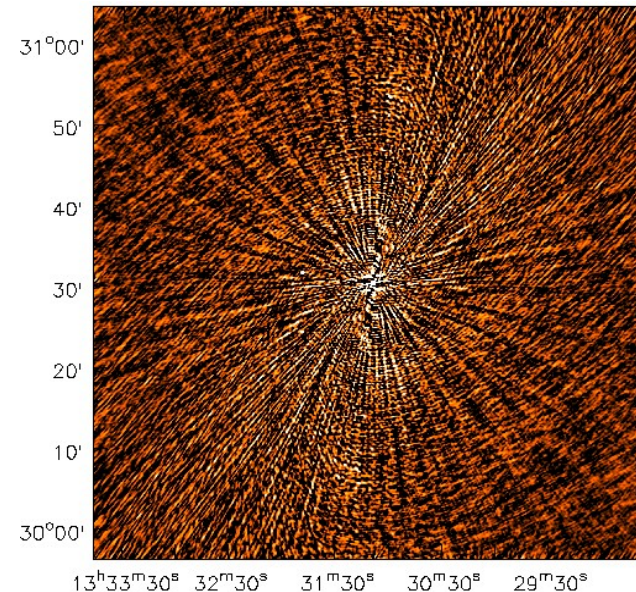
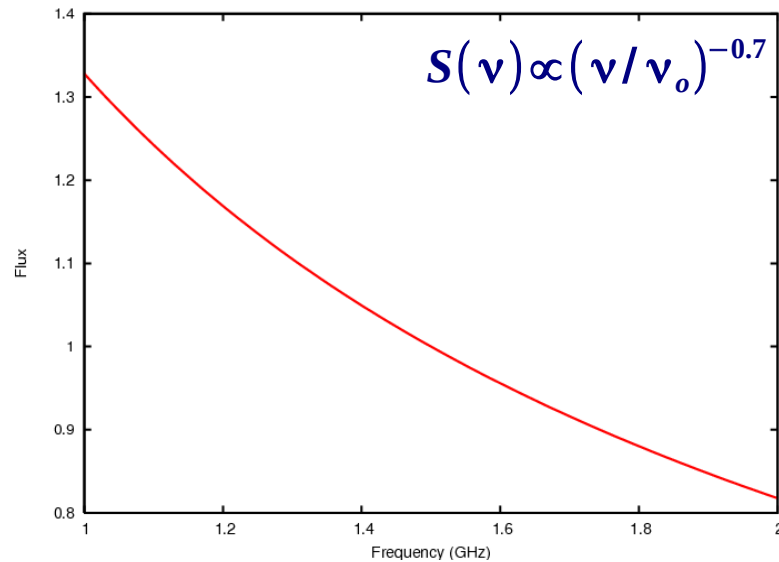
CS-Clean

MS-Clean

MT-MFS/MS-MFS

What do we call wide-band?

- When fractional signal bandwidth used for imaging $> \sim 20\%$
 - Plus source spectral index ≥ -1.0
 - Plus target dynamic range > 1000
- Spectral effects for higher source spectral index will become significant at lower bandwidth ratios
 - Empirical Dynamic range : $\frac{I\alpha}{100}$
 - Spectral line imaging, by definition, does not require wide-band imaging algorithms



Wide-band Imaging Sensitivity

Frequency Range :	(1 – 2 GHz)	(4 – 8 GHz)	(8 – 12 GHz)
Bandwidth : $\nu_{max} - \nu_{min}$	1 GHz	4 GHz	4 GHz
Bandwidth Ratio : $\nu_{max} : \nu_{min}$	2 : 1	2 : 1	1.5 : 1
Fractional Bandwidth : $(\nu_{max} - \nu_{min}) / \nu_{mid}$	66%	66%	40%

Broad-band receivers increase the 'instantaneous' imaging sensitivity of an instrument

$$\text{Continuum sensitivity : } \sigma_{cont} \propto \frac{T_{sys}}{\sqrt{N_{ant}(N_{ant}-1)} \delta \tau \delta \nu}$$

(at field-center)

50 MHz → 2 GHz Theoretical sensitivity improvement : $\sqrt{\frac{2 \text{ GHz}}{50 \text{ MHz}}} \approx 6$ times.

In practice, effective broadband sensitivity for imaging depends on bandpass shape, data weights, and regions of the spectrum flagged due to RFI (radio-frequency interference).

Use narrow-band channels – avoid bandwidth smearing

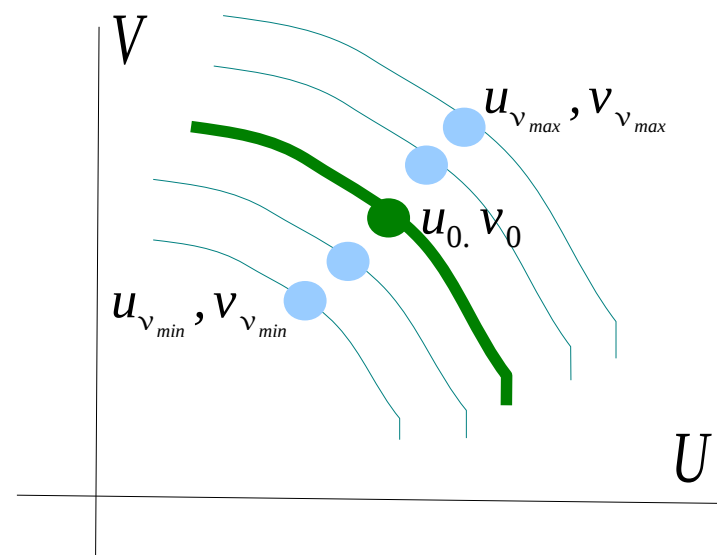
In the early days of continuum-observing, only one visibility was computed across the entire bandwidth of the receiver, and attributed to the reference (or middle) frequency ν_0 . Delay-tracking was also done only at ν_0 .

The visibility $V(u_\nu)$ is mistakenly mapped to $u_0 = \frac{b \nu_0}{c} = \frac{\nu_0}{\nu} u_\nu$

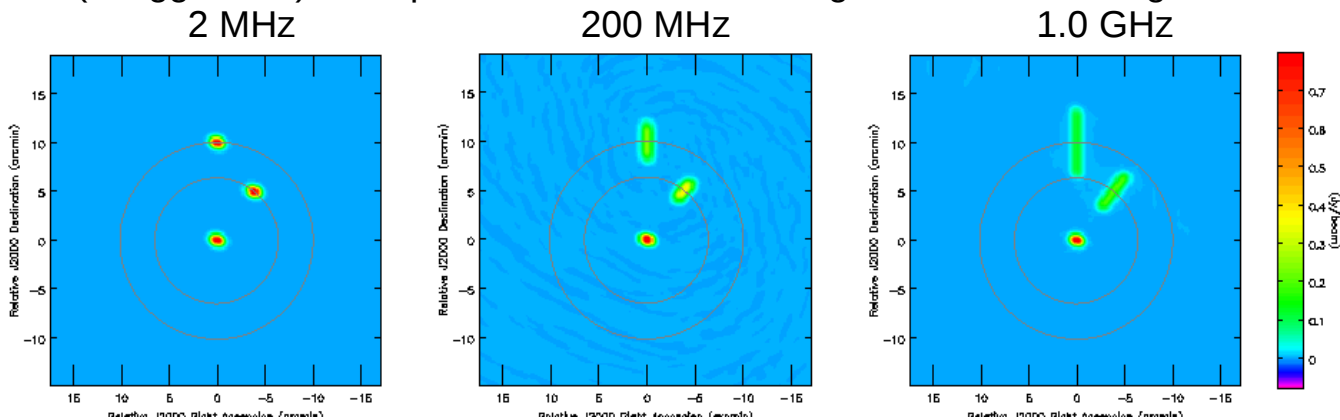
Similarity theorem of Fourier-transforms :

- => A radial shift in the source position, with frequency.
- => Radial smearing of the brightness-distribution

Note : Excessive channel-averaging has a similar effect.



An (exaggerated) example of bandwidth-smearing with a 1-2 GHz signal.....



Bandwidth Smearing Limits at 1.4 GHz

- 33 MHz (VLA D-config),
- 10 MHz (VLA C-config),
- 3 MHz (VLA B-config),
- 1 MHz (VLA A-config)

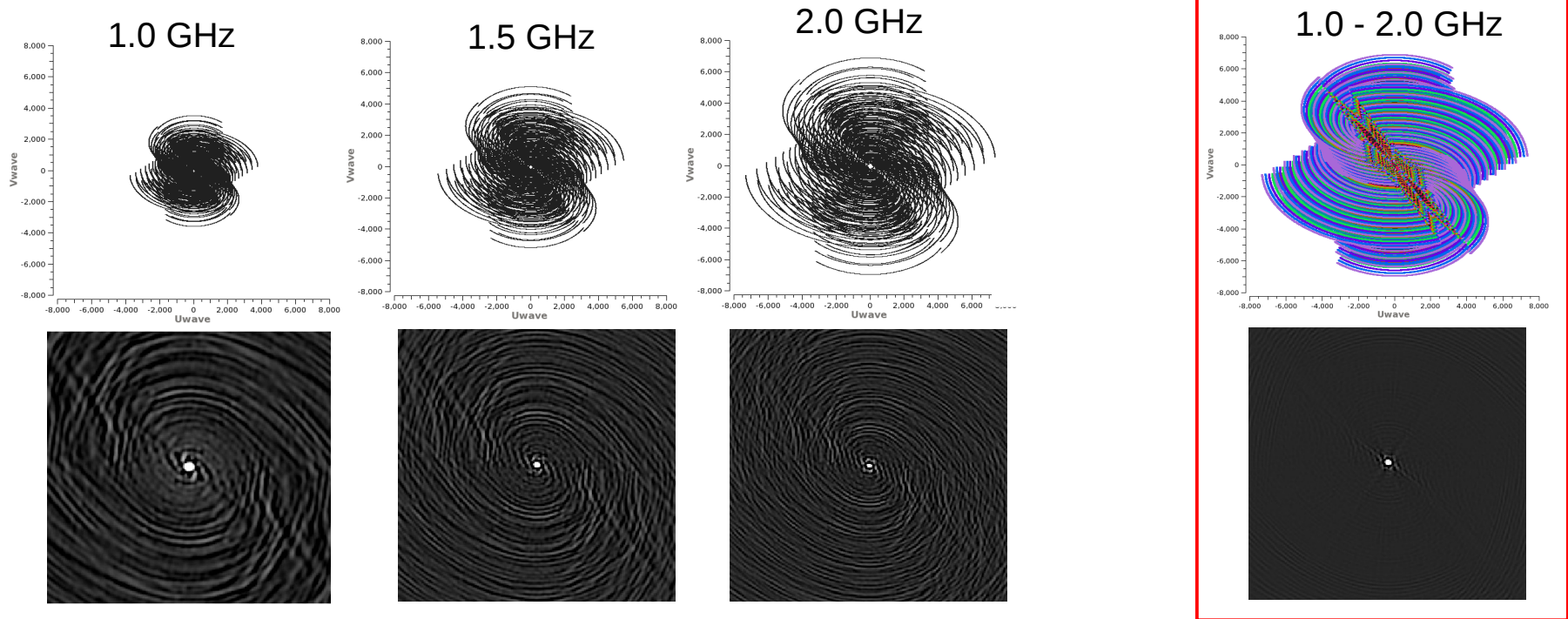
Contours represent 5 and 10 arcmin distances from the phase-center.

Frequency-dependent UV-coverages and PSFs

Spatial-frequency coverage and imaging properties change with frequency

- Angular-resolution increases at higher frequencies
- Sensitivity to large scales decreases at higher frequencies
- Wideband UV-coverage has fewer gaps => lower Psf sidelobe levels

$$S(u, v)_\nu = \frac{\vec{b}}{\lambda} = \frac{\vec{b}_\nu}{c}$$



But, when the source intensity varies with frequency, different channels measure the visibility function of different sky-brightness distributions

$$\text{the } V(u_\nu, v_\nu) = \iint I(l, m, \nu) e^{2\pi i(u_\nu l + v_\nu m)} dl dm$$

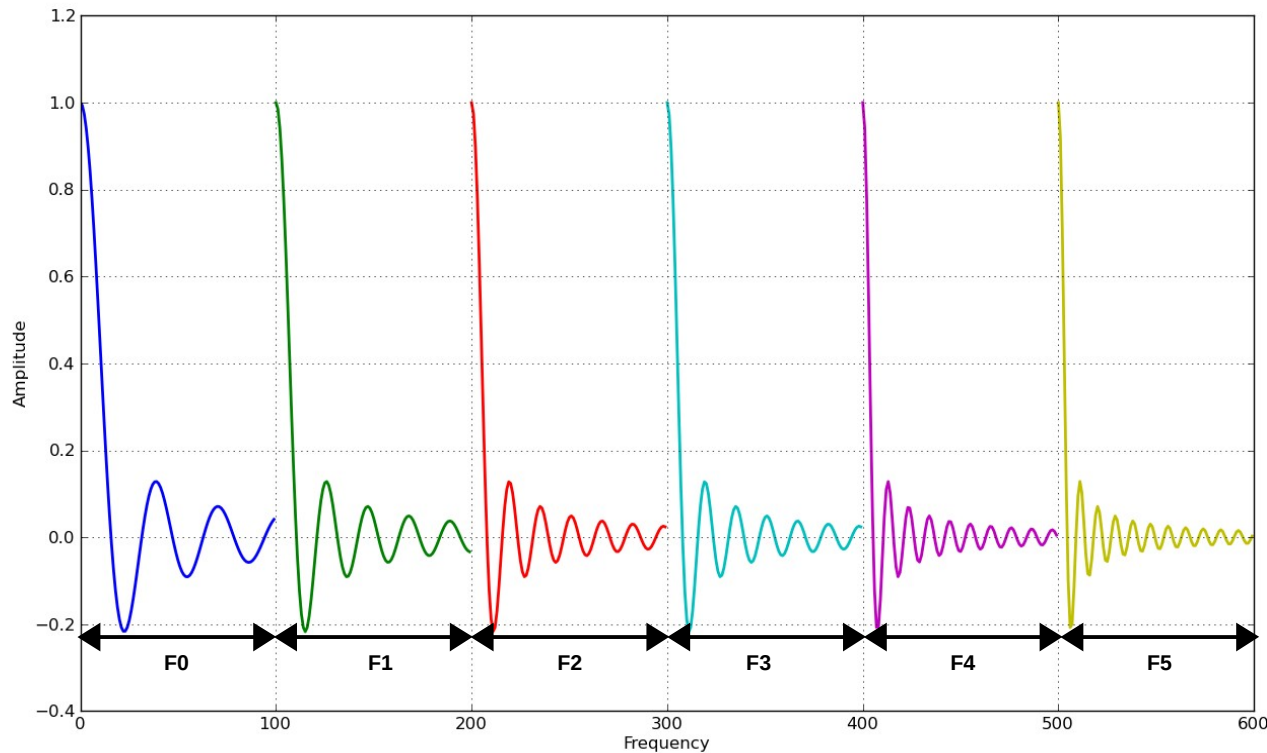
=> Need to model the spectrum as part of image reconstruction

Frequency-dependent UV-coverages and PSFs

Spatial-frequency coverage and imaging properties change with frequency:

- PSF structure scales with frequency

$$S(u, v)_\nu = \frac{\vec{b}}{\lambda} = \frac{\vec{b} \nu}{c}$$



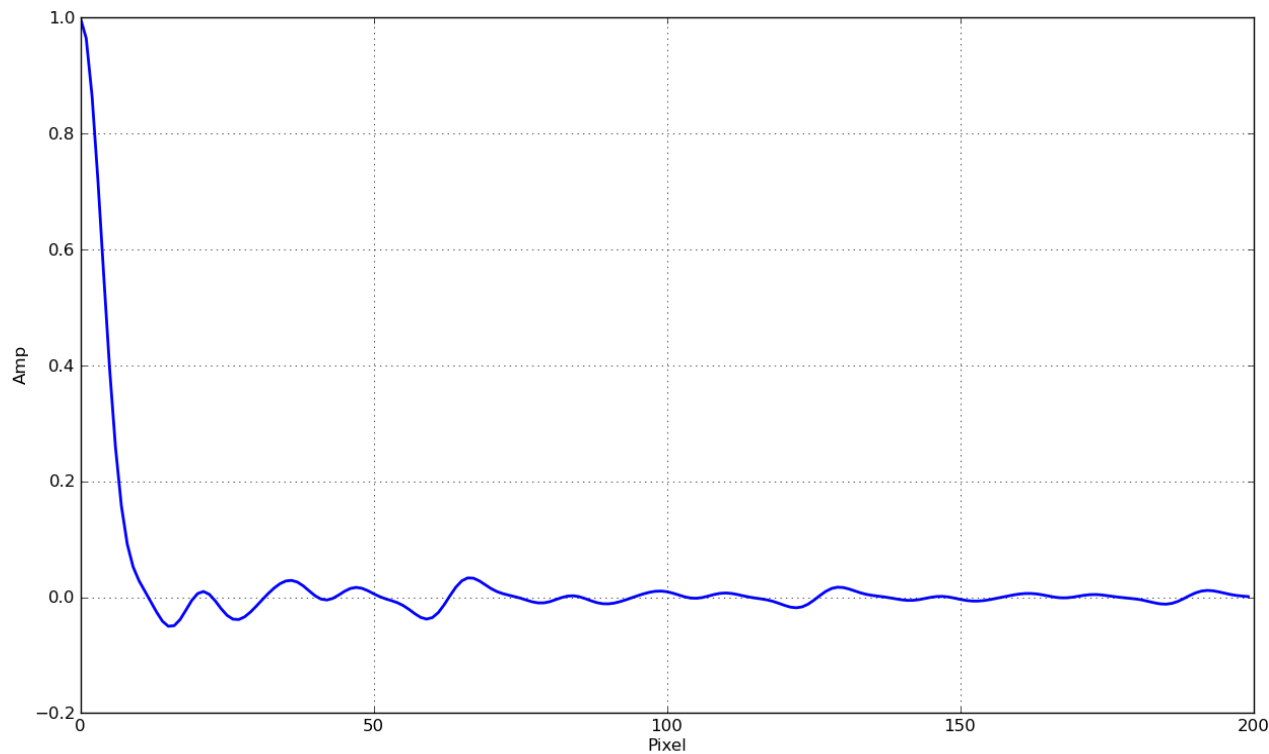
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$$S(u, v)_\nu = \frac{\vec{b}}{\lambda} = \frac{\vec{b} \nu}{c}$$

$$PSF_{Continuum} = \sum_{\nu} PSF(\nu)$$

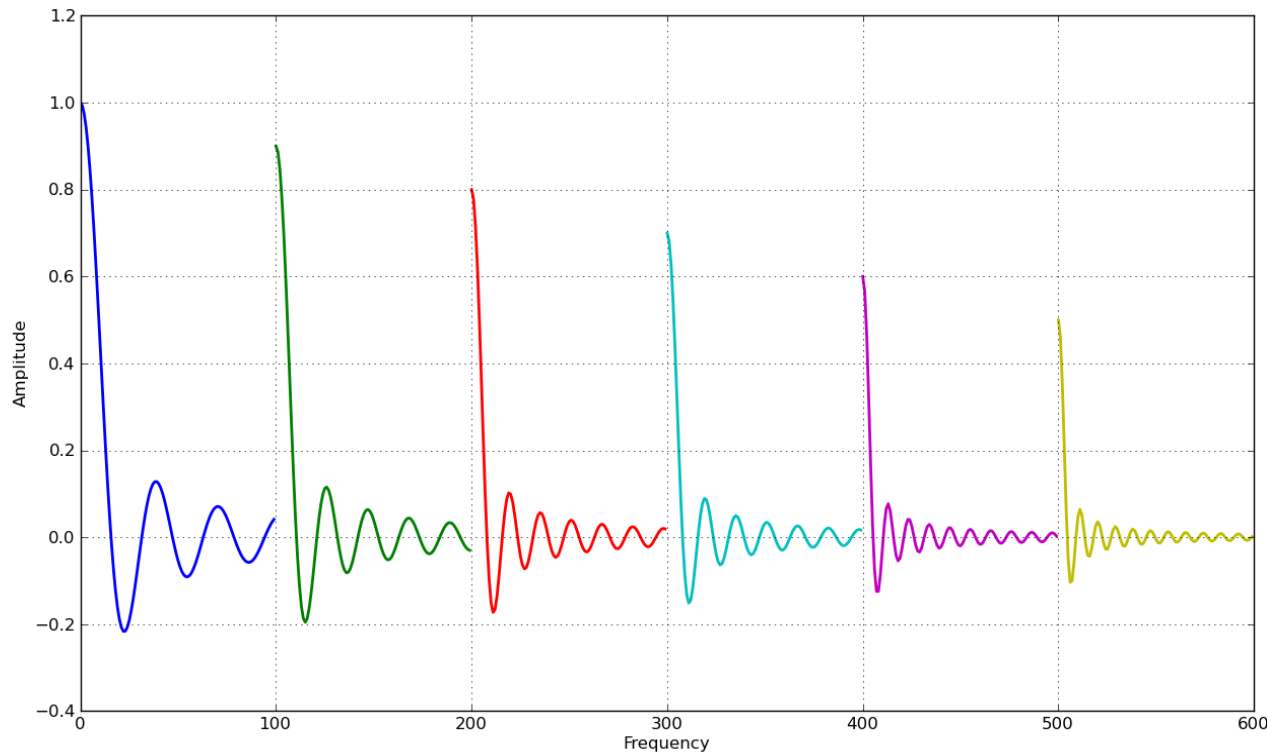


Frequency-dependent UV-coverages and PSFs

Spatial-frequency coverage and imaging properties change with frequency:

- PSF structure scales with frequency
- Due to source Spectral Index, PSF amplitude also changes with frequency

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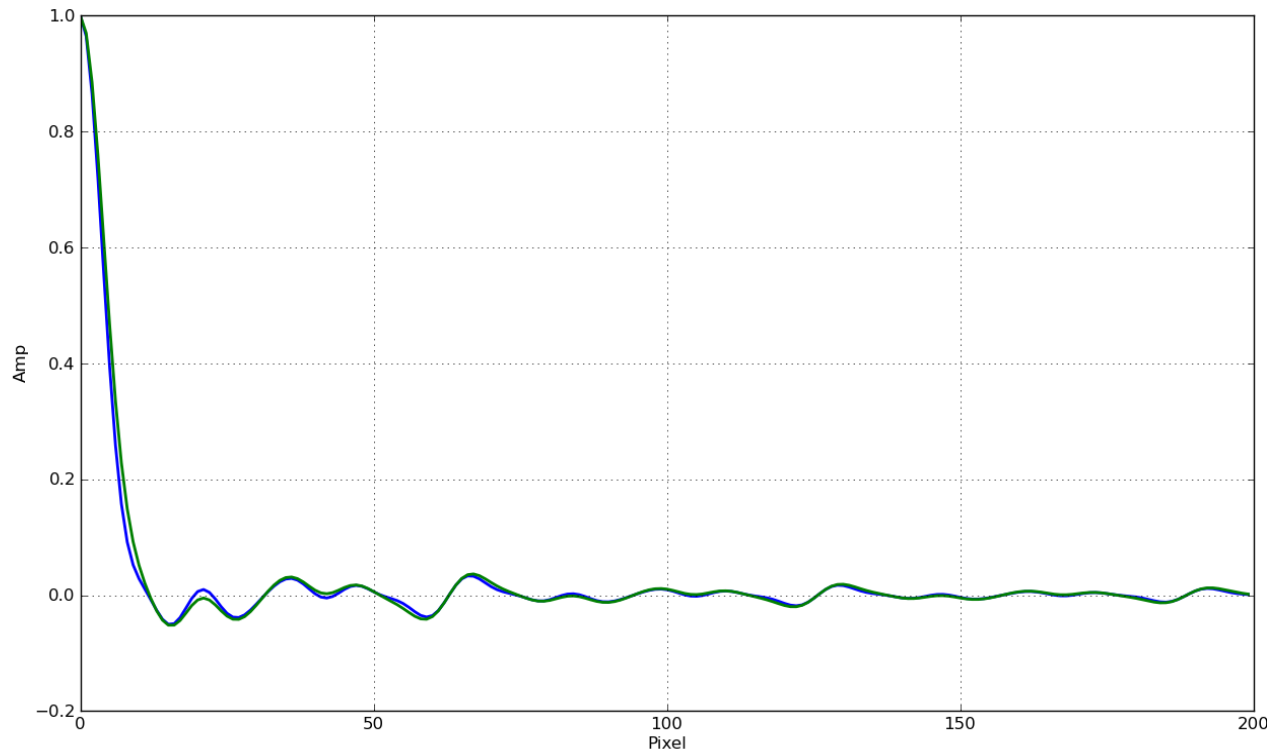
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$$PSF(x_o)_{Continuum} = \sum_\nu I(x_o, \nu) PSF(x - x_o, \nu)$$



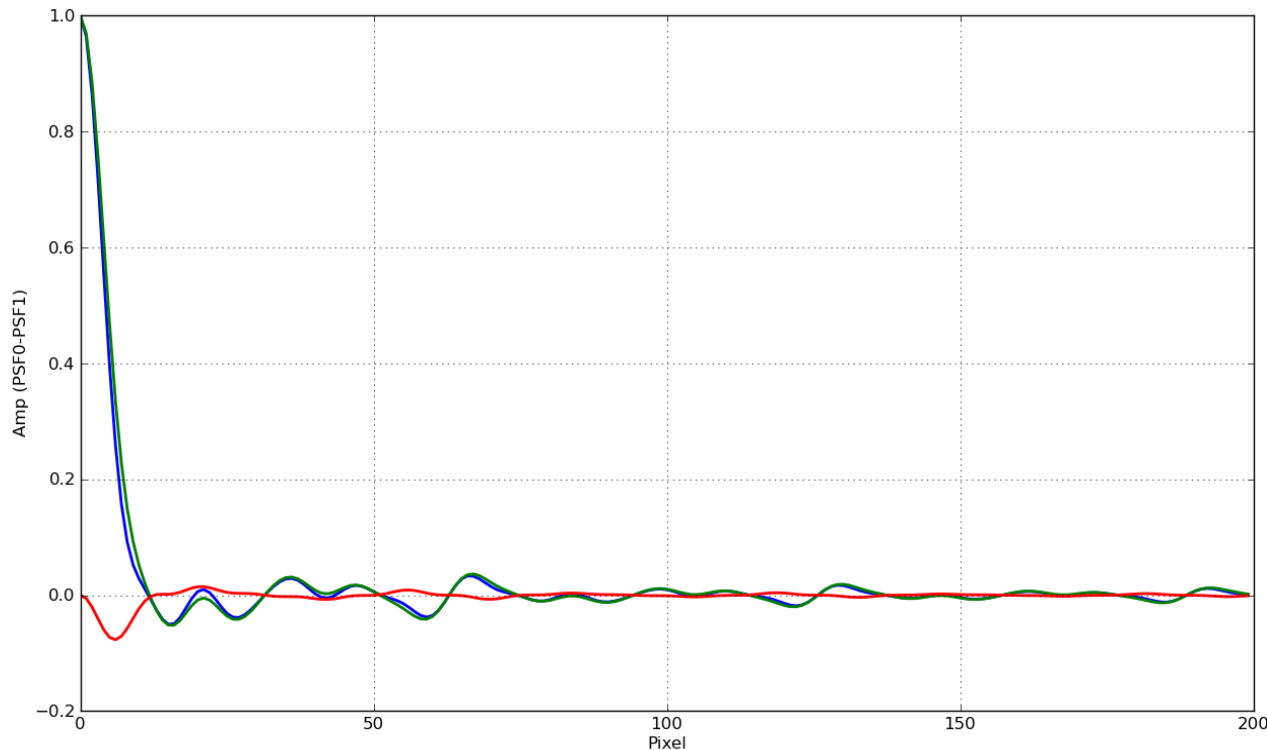
Frequency-dependent UV-coverages and PSFs

Spatial-frequency coverage and imaging properties change with frequency:

- PSF structure scales with frequency
- Due to source Spectral Index, PSF amplitude also changes with frequency

$$S(u, \nu)_\nu = \frac{\vec{b}}{\lambda} = \frac{\vec{b} \nu}{c}$$

$$Res(x_o)_{Continuum} = \sum_\nu PSF(x - x_o, \nu) - \sum_\nu I(x_o, \nu) PSF(x - x_o, \nu)$$



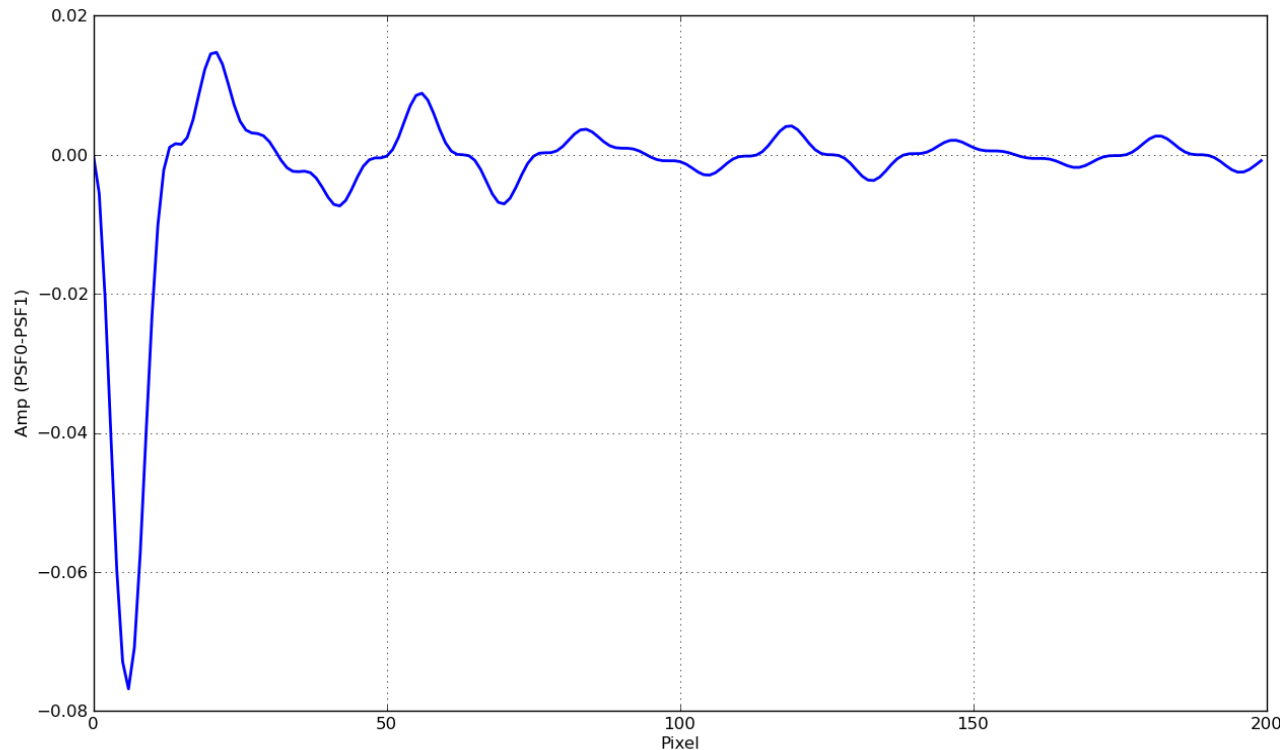
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$$Res(x_o)_{Continuum} = \sum_{\nu} PSF(x - x_o, \nu) - \sum_{\nu} I(x_o, \nu) PSF(\nu)$$



Wideband Imaging Options

(1) Make images for each channel / SPW separately.

- Signal-to-noise ratio : one SPW
- Angular resolution varies with SPW (smooth to lowest)
- Imaging fidelity may change across SPWs
- Primary beam correction can be done per SPW

Cube imaging will suffice for sources with simple spatial structures, and where the added uv-coverage, sensitivity and angular resolution is not required for the target science.

(2) Combine all frequencies during imaging (MFS : multi-frequency synthesis)

- Signal-to-noise ratio : all SPWs
- Angular resolution is given by the highest frequency
- Imaging fidelity is given by the combined uv-coverage
- Wideband PB correction is required (average gain and spectrum)

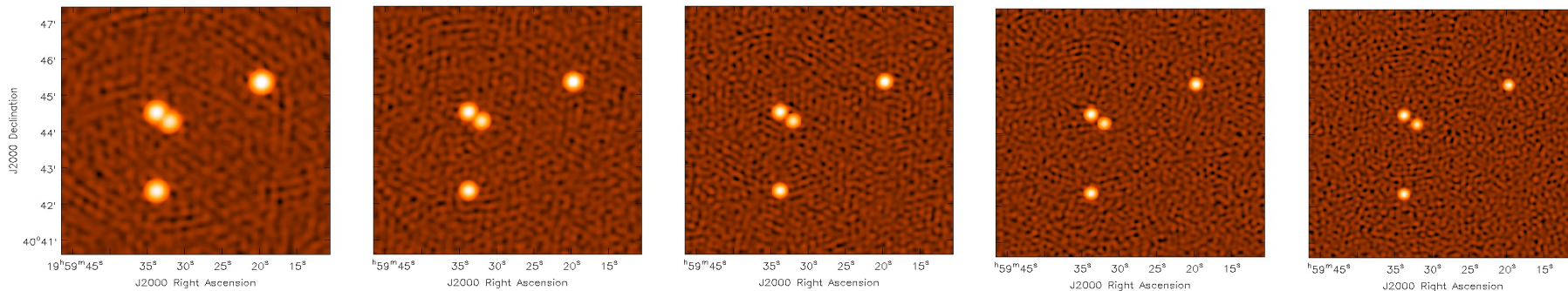
Multi-frequency-synthesis is needed to fully utilize the wideband uv-coverage and sensitivity during image reconstruction.

The frequency dependence of the sky and instrument must be taken into account

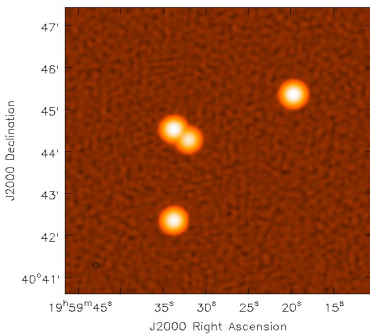
Single-channel vs MFS imaging – Angular Resolution

Simulated Example : 3 flat-spectrum sources + 1 steep-spectrum source (1-2 GHz)

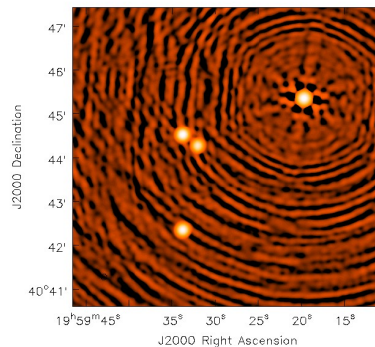
Images made separately at different frequencies between 1 and 2 GHz



Combine all single-frequency images (after smoothing)

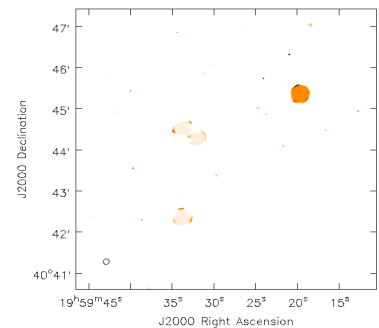
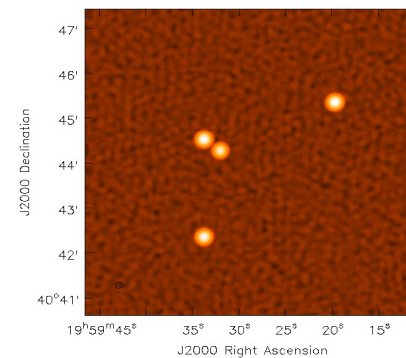


Use all UV-coverage together, but ignore spectra



Use all UV-coverage together + Model and fit for spectra too

Output : Intensity and Spectral-Index



=> Imaging with a spectrum model : higher angular resolution + continuum sensitivity.

Continuum Imaging : (multi-scale) multi-frequency-synthesis

Sky Model : Collection of multi-scale flux components whose amplitudes follow a polynomial in frequency

$$I_\nu^{sky} = \sum_t I_t \left(\frac{\nu - \nu_0}{\nu_0} \right)^t \quad \text{where } I_t = \sum_s [I_s^{shp} * I_{s,t}]$$

Algorithm : **Linear least squares + deconvolution**

Parameters : mode='mfs', nterms=2, reffreq='1.5GHz', multiscale=[0,6,10]

Data Products : **Taylor-Coefficient images** $I_0^m, I_1^m, I_2^m, \dots$ that represent the observed spectrum

Interpretation :

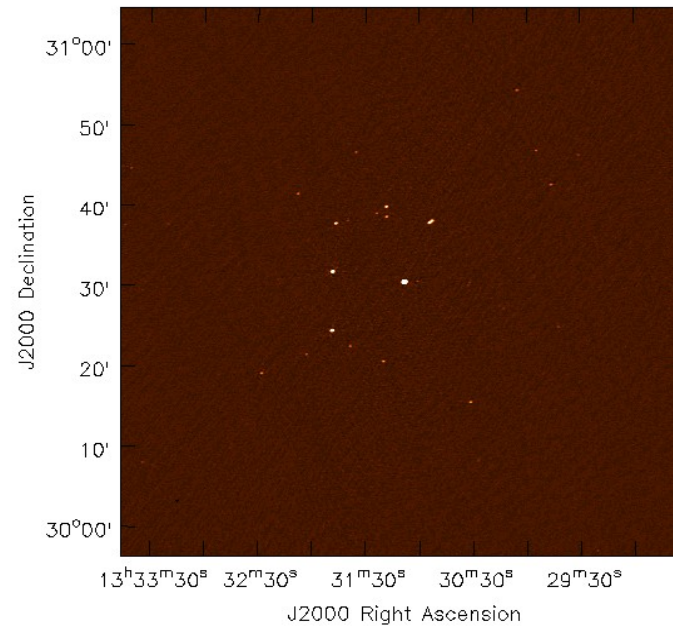
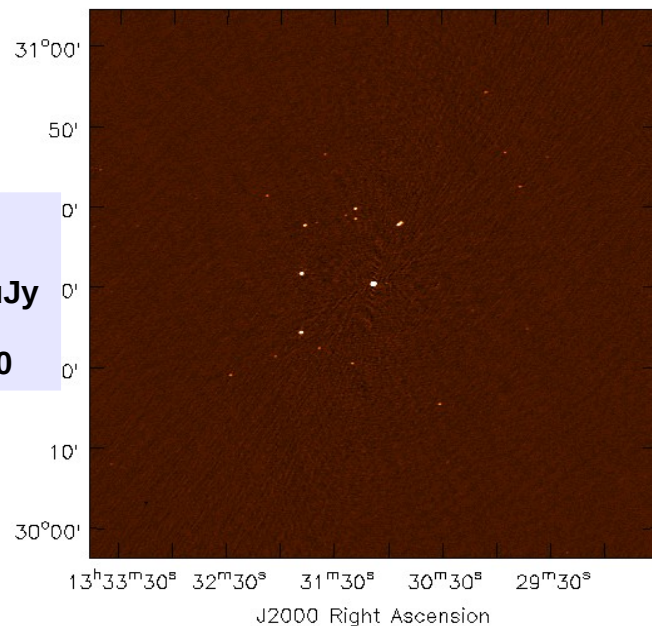
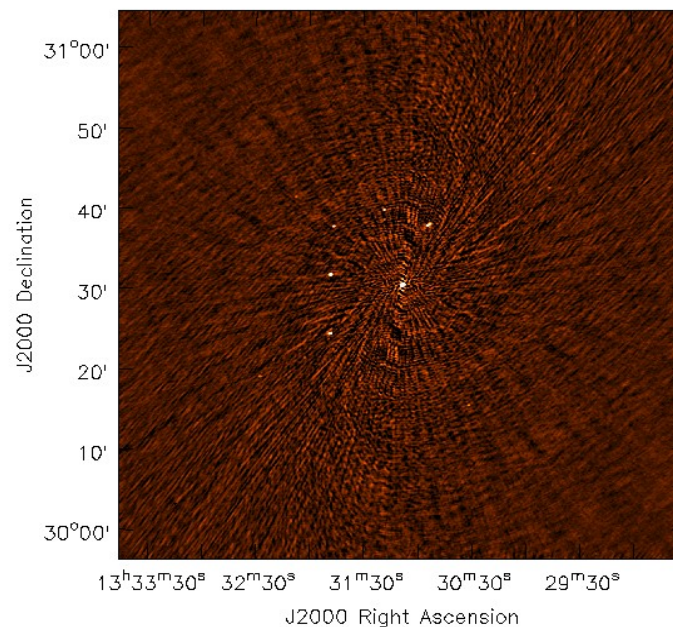
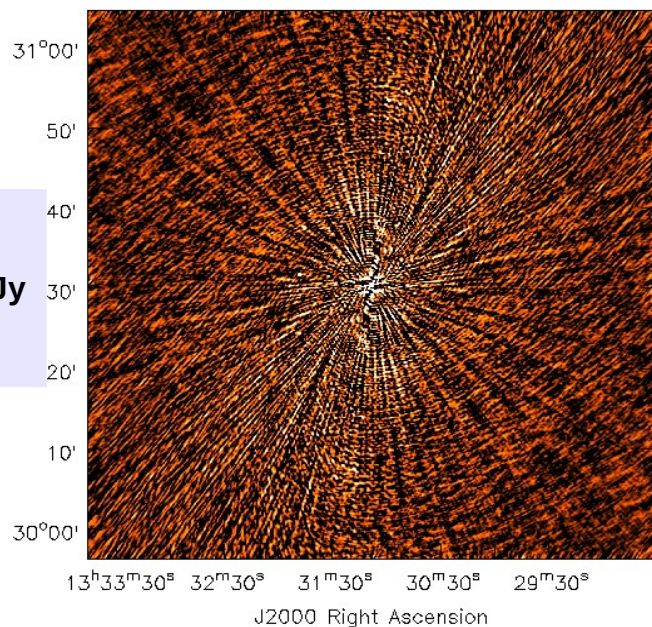
- **As a power-law** (spectral index and curvature) $I_\nu = I_{\nu_0} \left(\frac{\nu}{\nu_0} \right)^{\alpha + \beta \log(\nu/\nu_0)}$

$$I_0^m = I_{\nu_0} \quad I_1^m = I_{\nu_0} \alpha \quad I_2^m = I_{\nu_0} \left(\frac{\alpha(\alpha-1)}{2} + \beta \right)$$

- **PB-correction** : Model the average PB-spectrum with a Taylor-polynomial, and do a post-deconvolution Polynomial-Division

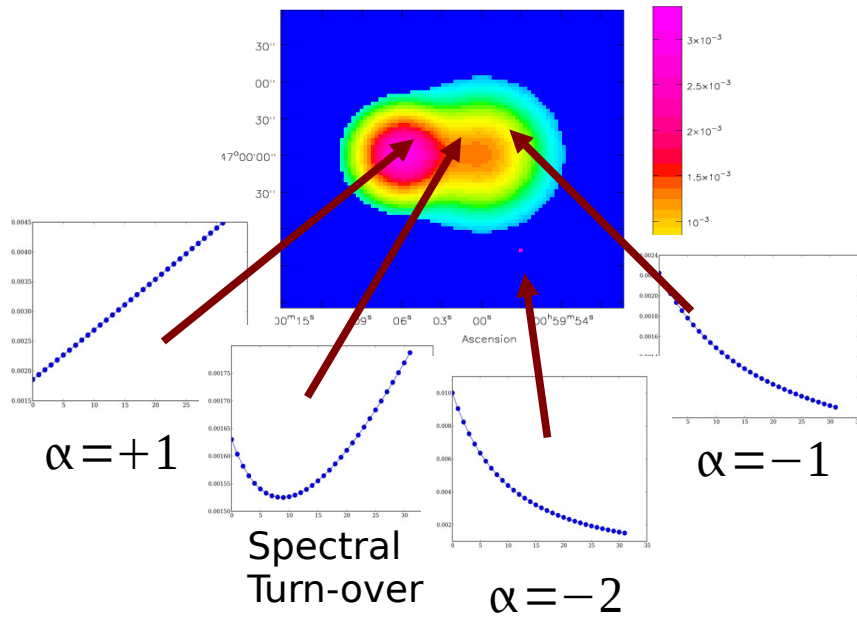
$$\frac{(I_0^m, I_1^m, I_2^m, \dots)}{(P_0, P_1, P_2, \dots)} = (I_0^{sky}, I_1^{sky}, I_2^{sky}, \dots)$$

Dynamic-range with MS-MFS : 3C286 example : Nt=1,2,3,4

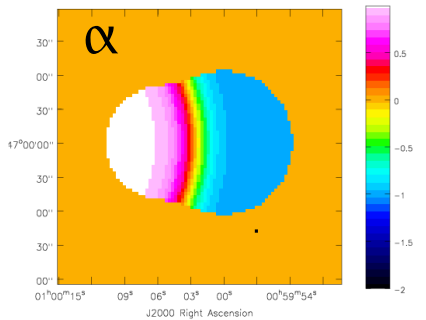


Example of wideband-imaging on extended-emission

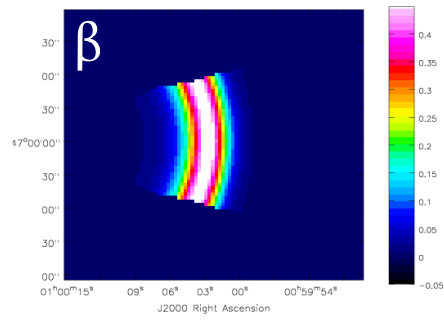
Intensity Image



Average Spectral Index

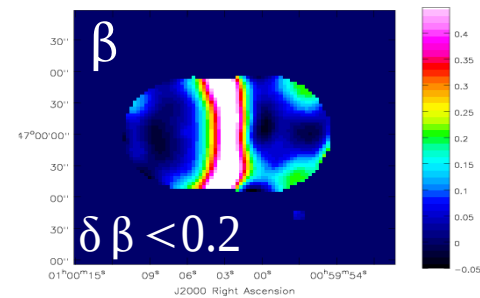
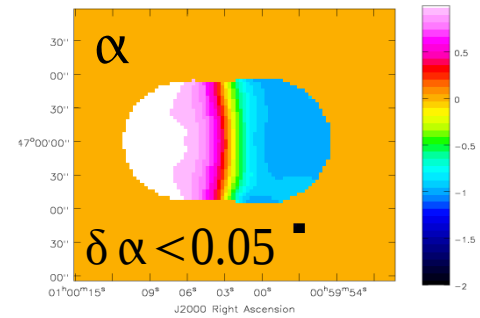
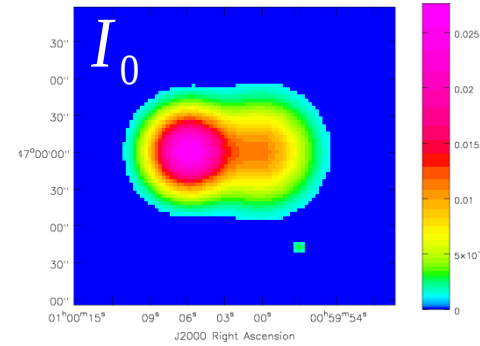


Gradient in Spectral Index

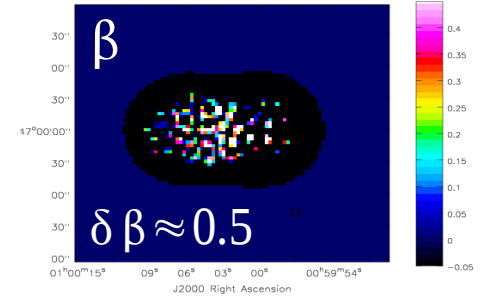
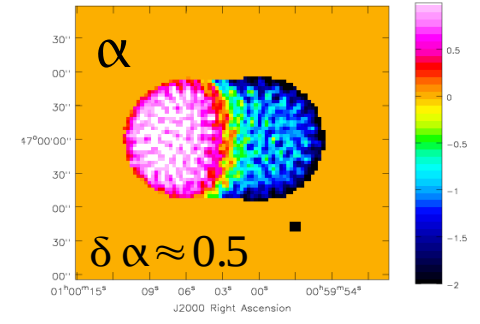
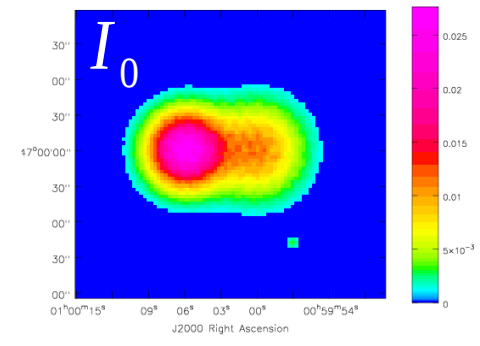


MFS

multi-scale



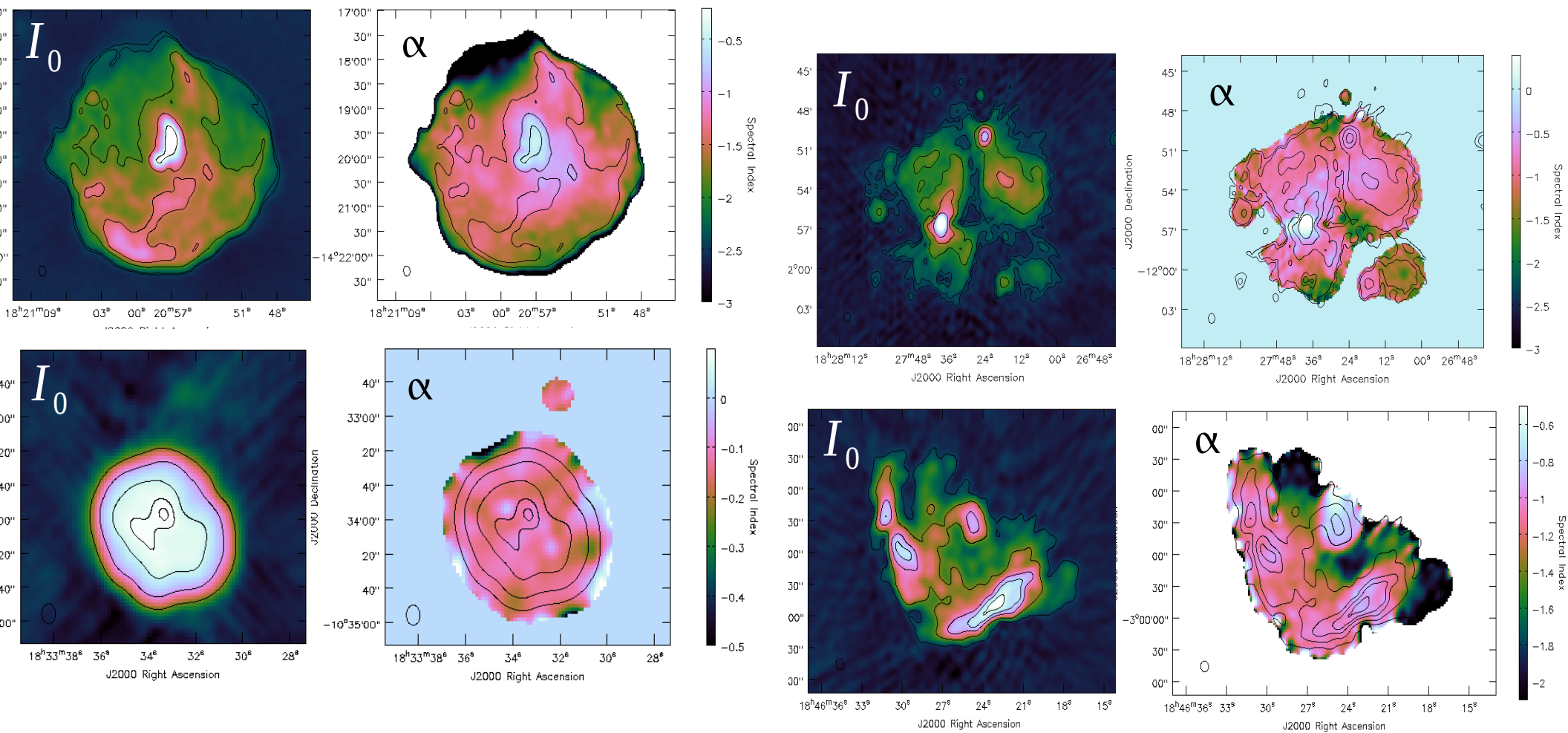
point-source



=> For extended emission - spectral-index error is dominated by 'division between noisy images'

- a multi-scale model gives better spectral index and curvature maps

Extended emission – SNR example (a realistic expectation)



These examples used $n_{\text{terms}}=2$, and about 5 scales.

=> Within 1-2 GHz and 4-8 GHz, can tell-apart regions by their spectral-index (± 0.2) if $\text{SNR} > 100$.
 (this accuracy will increase with wider bandwidths – 1-3 GHz CABB)

=> These images have a dynamic-range limit of few x 1000 ---> residuals are artifact-dominated

Errors in polynomial fitting + Imaging (empirical)

For a 1 Jy point source with spectral index of -1.0 ...

- If spectra are ignored during MFS imaging => Errors increase with bandwidth.

Dynamic-range limits for VLA uv-coverage (natural)

1-2 GHz => ~ 1000

1-3 GHz => few 100

- If spectra are modeled + High signal-to-noise => Need higher-order polynomials to fit a power-law

1 term (flat spectrum) => peak intensity error of 0.1 (on 1 Jy)

2 terms (linear spectrum) => peak intensity error of 0.02, spectral index error of 0.1

3 terms (quadratic spectrum) => intensity error of 0.0001, spectral index error of 0.05

- If spectra are modeled + Low signal-to-noise => Higher-order polynomials give more errors

The following situations give similar error on spectral index (~ 0.1) for a point source....

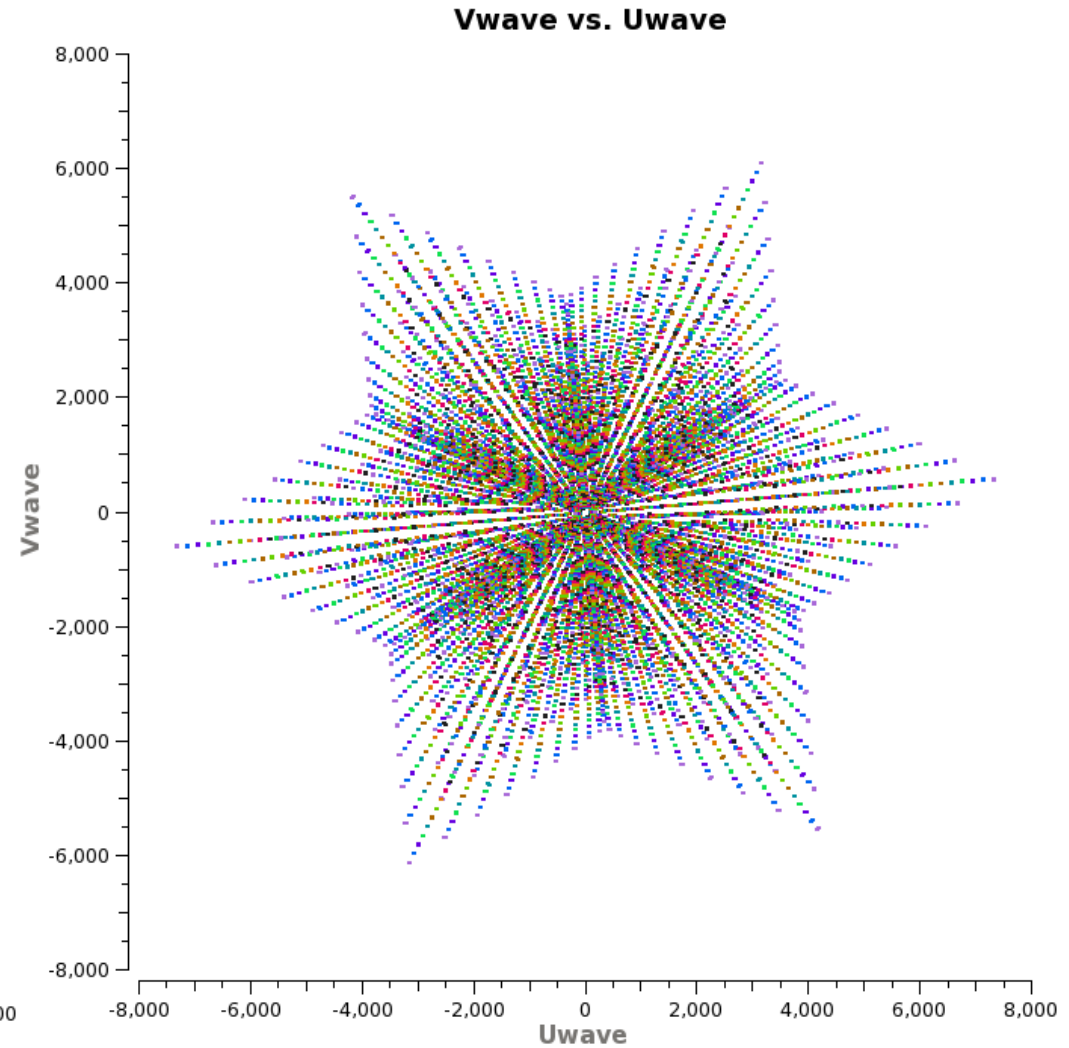
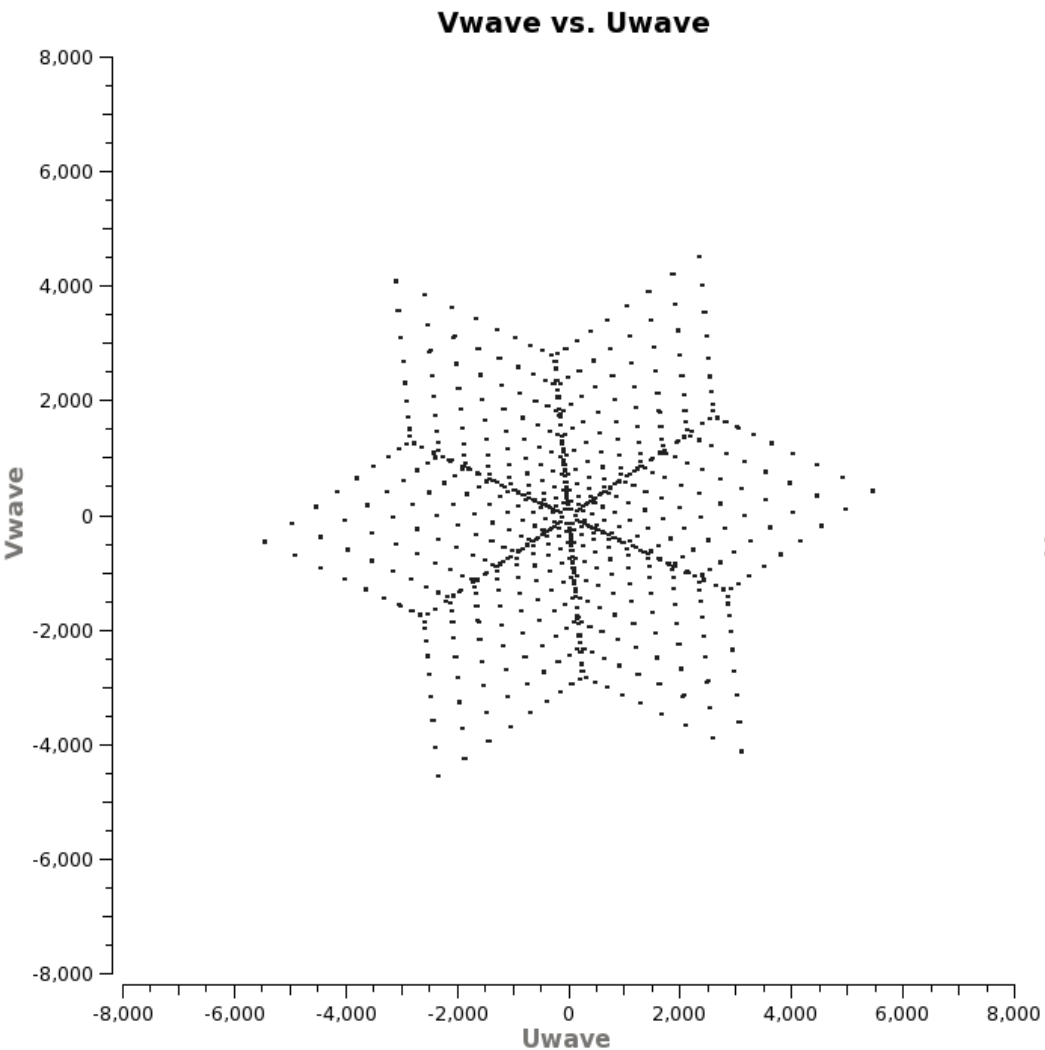
L-Band + C-Band : 1-8 GHz : Sources with signal-to-noise ratio of 10~20

L-Band only (1-2 GHz) or C-Band only (4-8 GHz) : Sources with SNR ~ 40

For extended emission, spectral index errors ≤ 0.2 only for SNR > 100.....

Multi-Frequency-Synthesis : Snapshot

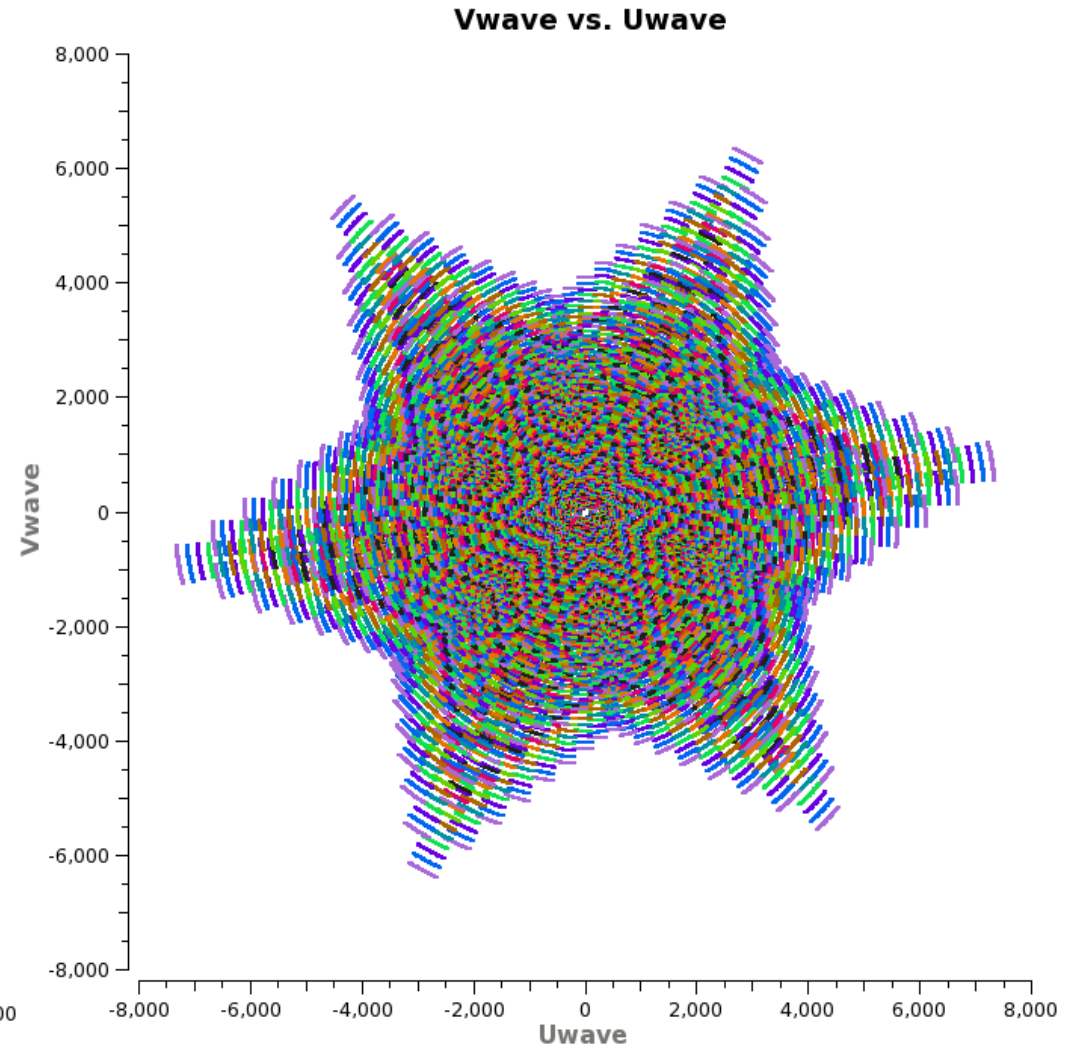
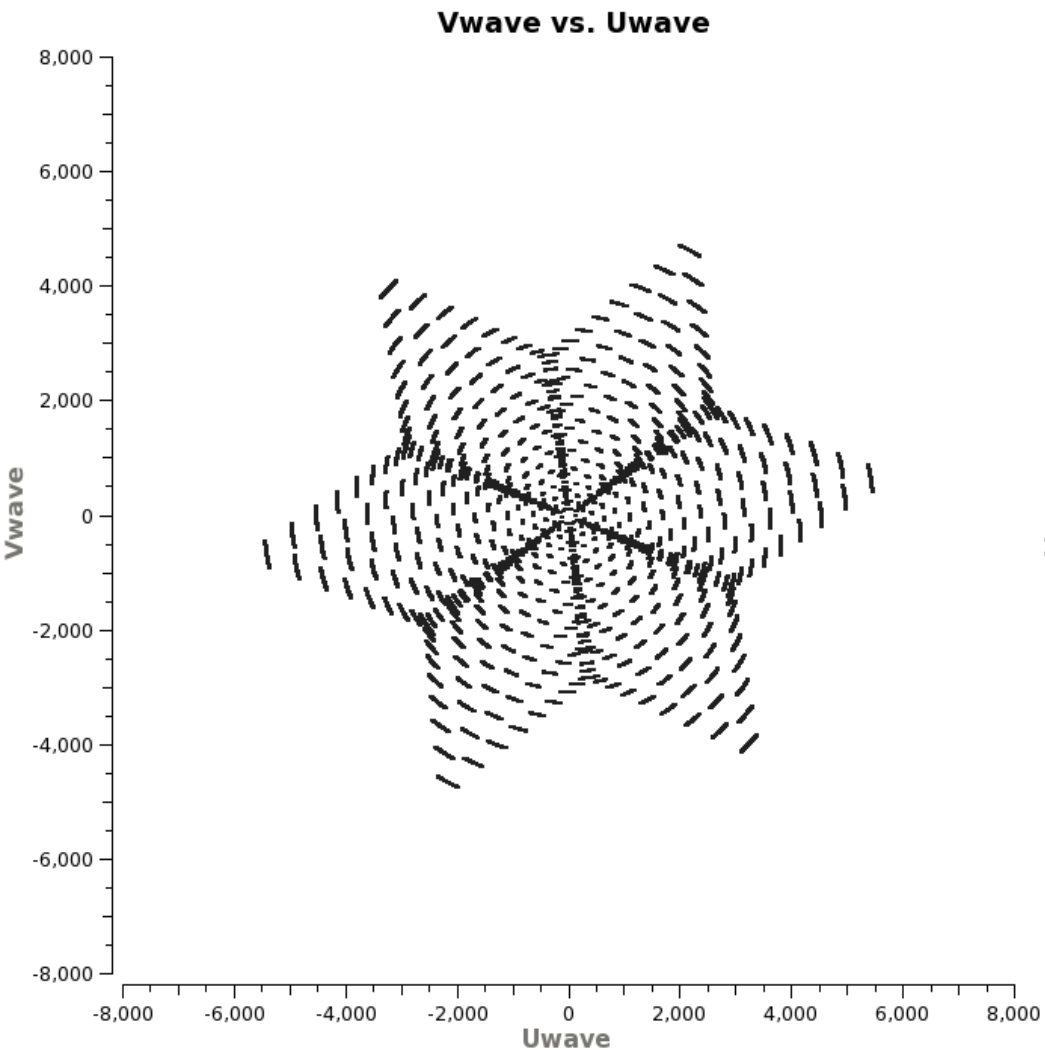
Observing tip.....



Wideband UV-coverage fills the UV-plane radially.....

Multi-Frequency-Synthesis : 30 min

Observing tip.....

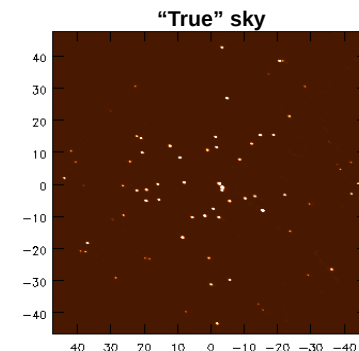
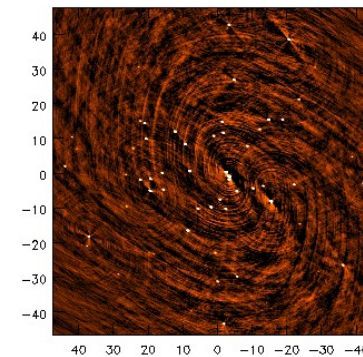
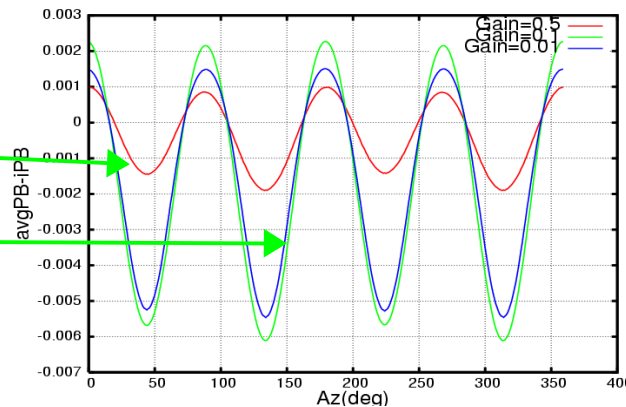
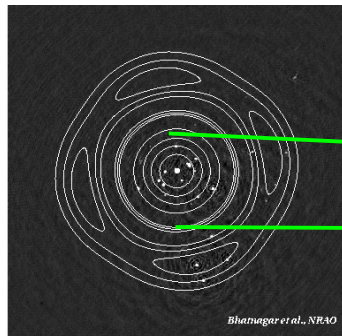
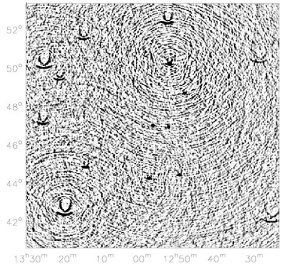


Small time-increments generate good uv-filling => Plan wideband observations in small time-chunks, spread out in time to cover more spatial-frequencies at-least once.

What do we call wide-field?

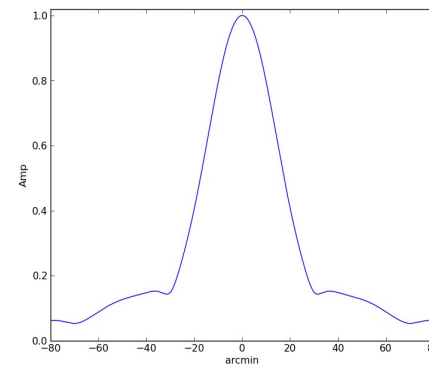
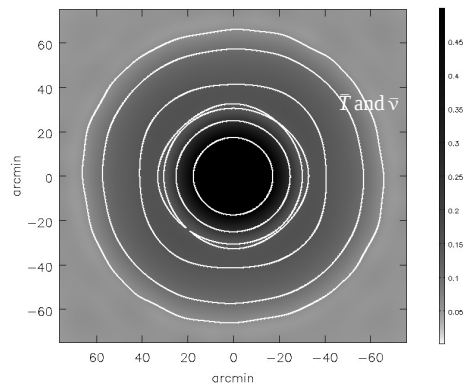
- Imaging that requires invoking any of the following:
 - Corrections for non co-planar baseline effects
 - Corrections for the rotational asymmetry of the PB
 - Imaging beyond 50% point, mosaicking
 - Corrections for the frequency or polarization dependent effects
 - Noise limited imaging at 4-,P-,L-, S- (and probably C-Band)
 - Because of the radio brightness distribution
- Noise limited imaging of structure comparable to the PB beam-width
- Mosaicking: imaging on scales larger than the PB beam-width

$$\frac{\lambda}{B_{max}} \leq \theta_f^2$$



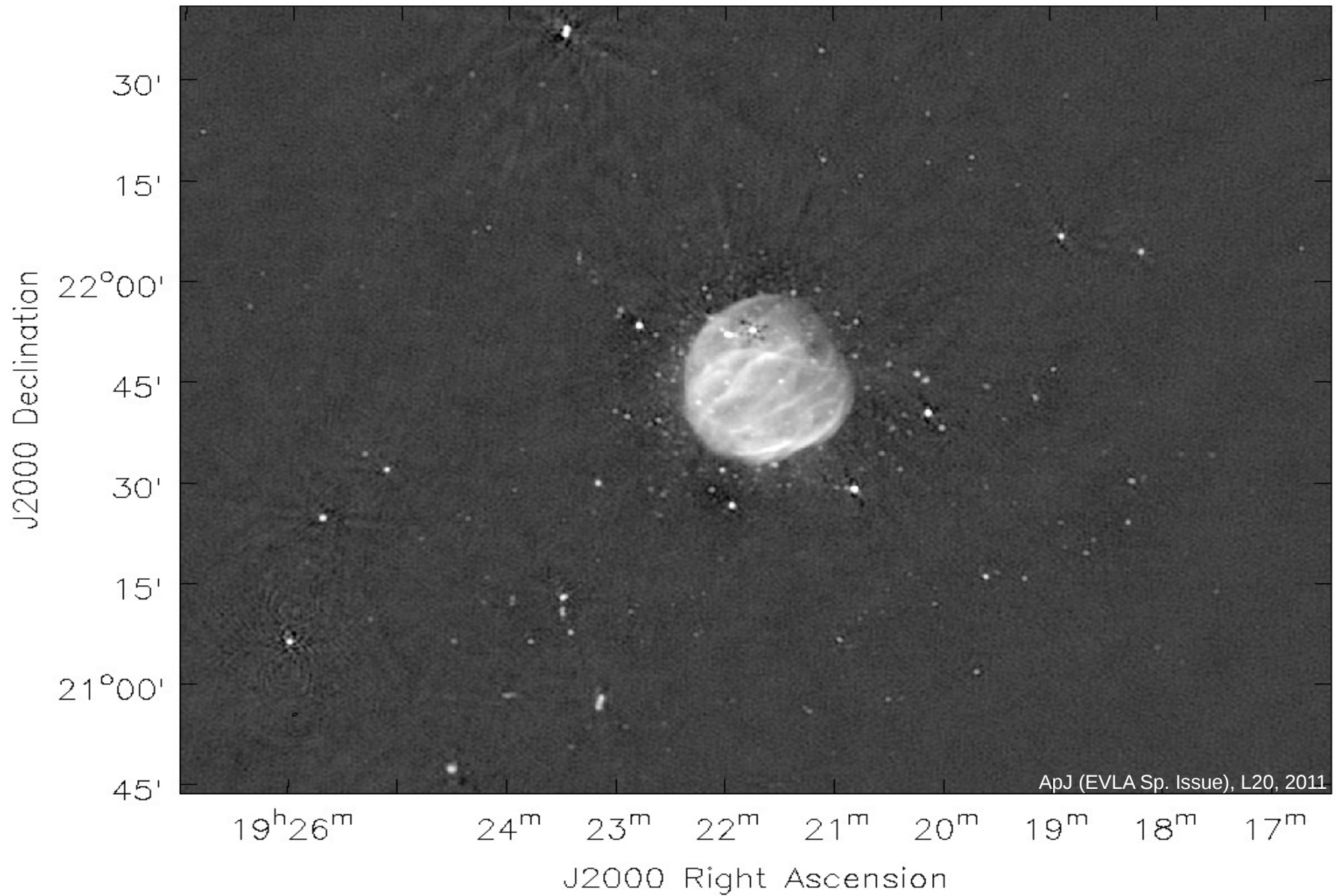
Why wide-field?

- Primarily due to improved continuum sensitivity
- @L-Band, PB gain ~ 1 deg. away can be up to 10%
 - In the EVLA sensitivity pattern, VLA sensitivity is achieved at the location of the VLA-null!
 - No null in the EVLA sensitivity pattern



- E.g. a 1% PSF side lobe due to a source away from the center is now significantly above continuum thermal noise limit
 - This is a largely independent of the total integration time

Wide-field Issues



Wide-field sensitivity because of wide-bandwidths

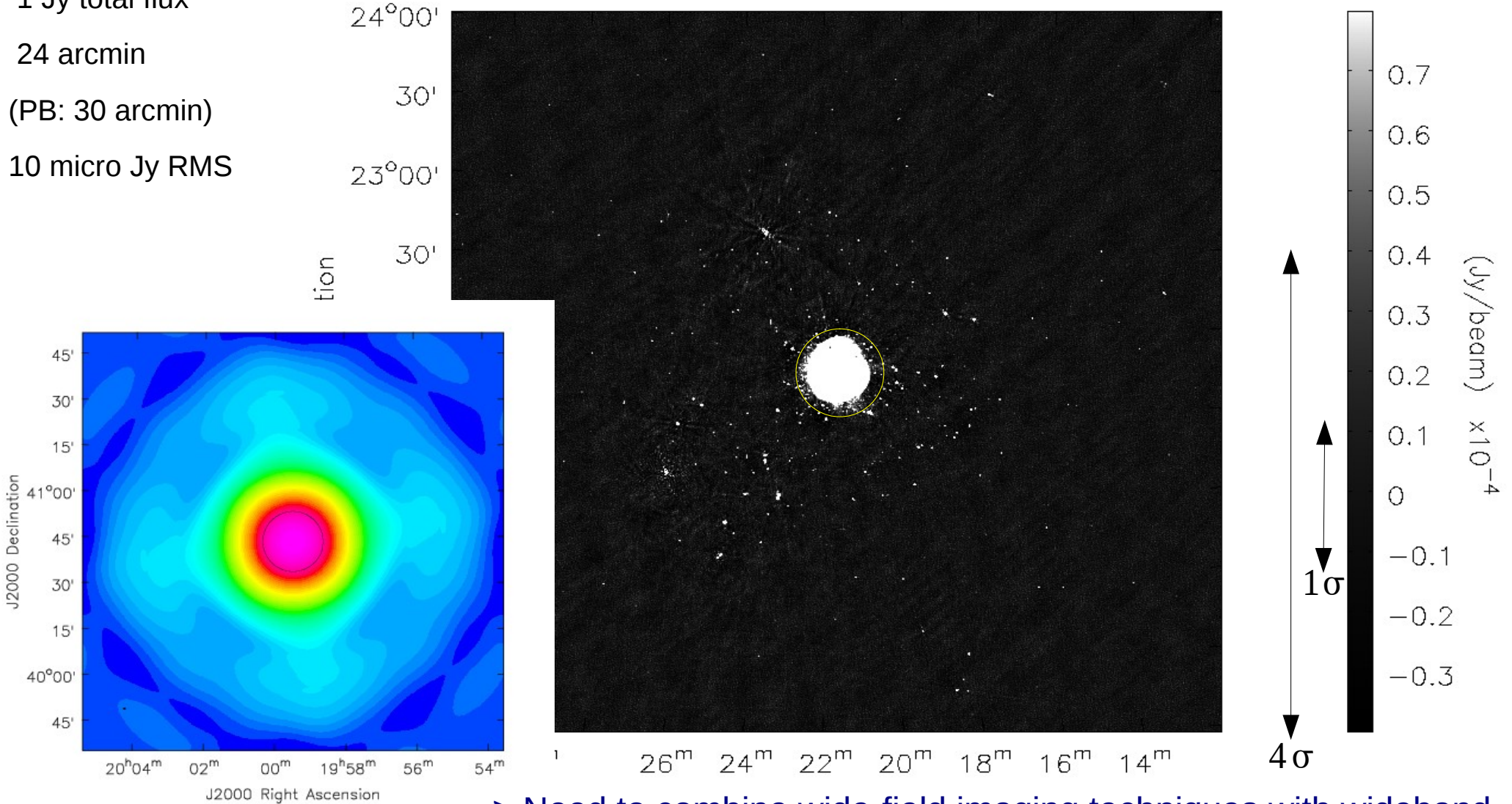
G55.7+3.4 : Galactic supernova remnant : 4 x 4 degree field-of-view from one EVLA pointing

1 Jy total flux

24 arcmin

(PB: 30 arcmin)

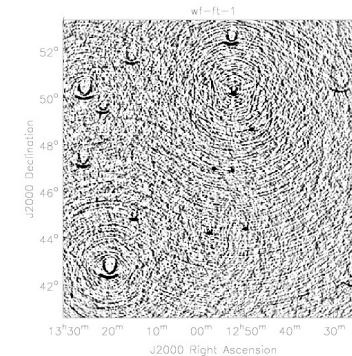
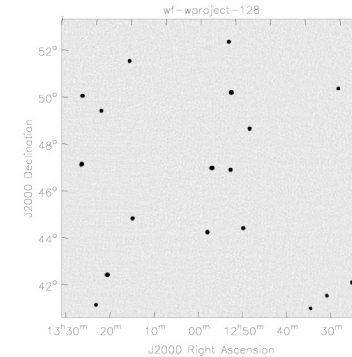
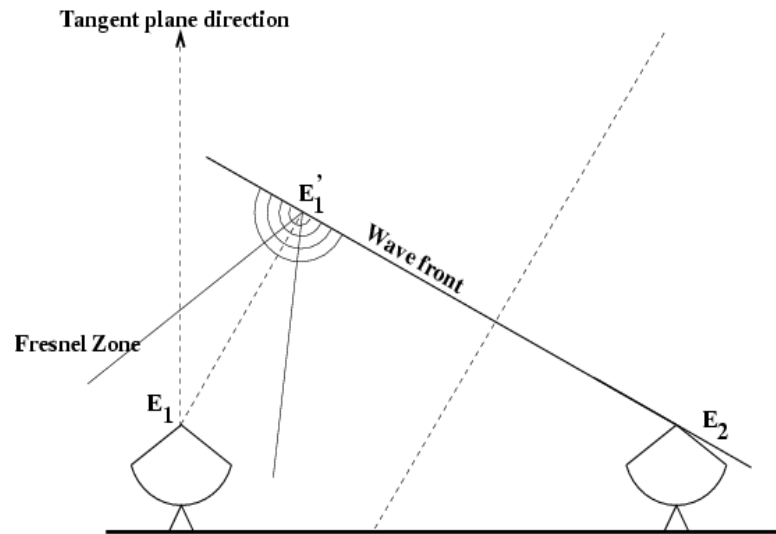
10 micro Jy RMS



=> Need to combine wide-field imaging techniques with wideband..

Non co-planar baseline: The W-term

- 2D FT approximation of the Measurement Equation breaks down



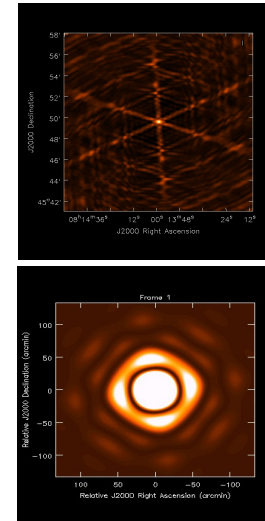
- We measure: $V_{12} = \langle \mathbf{E}_1(u, v, w=0) \mathbf{E}_2^*(0,0,0) \rangle$
- We interpret it as: $V_{12}^o = \langle \mathbf{E}'_1(u, v, w \neq 0) \mathbf{E}_2^*(0,0,0) \rangle$

We should interpret \mathbf{E}_1 as $[\mathbf{E}'_1 \times \text{Fresnel Propagator}]$

PB Effects: Rotation asymmetry

- Only average quantities are available in the image domain
- Asymmetric PB rotation leads to time and direction dependent gains

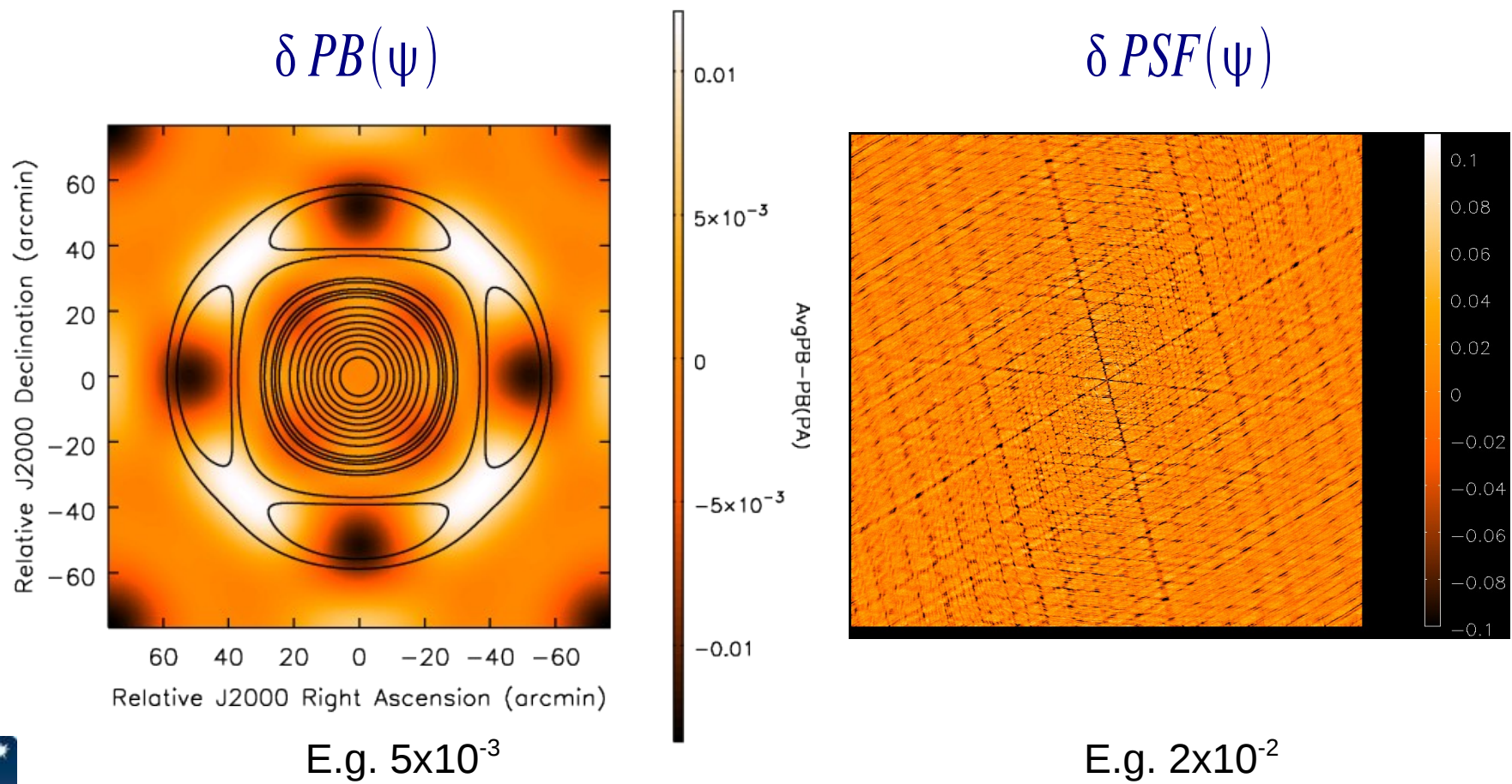
$$\Delta I^R = \sum_{\psi} [PSF(\psi) - avgPSF] * [(PB(\psi) - avgPB) I^0]$$



- Time-variability due to rotational asymmetry is stronger below $\sim 10\%$ point and in the side-lobes.
- Time-variability due to pointing errors is stronger $\sim 50\%$ point.

PB Effects: Error Propagation

$$\Delta I^R = \sum_{\psi} \delta PSF(\psi) * [\delta PB(\psi) I^o]$$



Projection algorithms

- Direction-dependent effects in the image domain are convolutional terms in the data domain
- Projection algorithms for DD corrections:
 - Project-out various DD effects as part of the gridding operator

- ME:

$$V_{ij}^{Obs} = A_{ij} * V^o + N_{ij}$$

- Construct D, such that

$$D_{ij}^T * A_{ij} \approx \text{Time/Freq./Pol. indep.}$$

- Imaging:

$$I = F^{-1} \sum_{ij} D_{ij}^T * V_{ij}^{Obs} = F^{-1} \frac{\sum_{ij} D_{ij}^T * A_{ij} * V_{ij}^o + D_{ij}^T N_{ij}}{\text{Normalization}}$$



DI Corrections: Standard Calibration

- DI ME entirely in the visibility domain:

$$V_{ij}^{Obs} = [J_i \otimes J_j^*] \cdot [V_{ij}^o] = [M_{ij}] \cdot [V_{ij}^o]$$

$$\begin{bmatrix} V_{pp}^{Obs} \\ V_{pq}^{Obs} \\ V_{qp}^{Obs} \\ V_{qq}^{Obs} \end{bmatrix} = \begin{bmatrix} M_{11} & M_{12} & M_{13} & M_{14} \\ M_{21} & M_{22} & M_{23} & M_{24} \\ M_{31} & M_{32} & M_{33} & M_{34} \\ M_{41} & M_{42} & M_{43} & M_{44} \end{bmatrix} \cdot \begin{bmatrix} V_{pp}^o \\ V_{pq}^o \\ V_{qp}^o \\ V_{qq}^o \end{bmatrix}$$

- Diagonal:** “pure” poln. products
- Off-diagonal:** Include poln. leakage

SelfCal model: $M_{ij} = g_i g_j^*$

- Full-pol. DI Correction

$$V_{ij}^{Corr} = [M_{ij}^{M^{-1}}] \cdot [V_{ij}^{Obs}] = \frac{\mathit{adj}(M_{ij}^M)}{\mathit{det}(M_{ij}^M)} \cdot [V_{ij}^{Obs}] \quad \text{Equivalent Complex math.: } G_i^{-1} = \frac{G^*}{|G|^2}$$

No pol. leakage case: $= \frac{G_{q,ij}^{M^*}}{G_{p,ij}^M G_{q,ij}^{M^*}}$

gaincal, bandpass, gencal, applycal, polcal,...



DD Corrections: Projection algorithms

- DD ME entirely in the visibility domain:

$$V_{ij}^{Obs} = [J_i \otimes J_j^*] * [V_{ij}^o] = [M_{ij}] * [V_{ij}^o]$$

J : Each elements is a function

\otimes = Element-by-element convolution

$$\begin{bmatrix} V_{pp}^{Obs} \\ V_{pq}^{Obs} \\ V_{qp}^{Obs} \\ V_{qq}^{Obs} \end{bmatrix} = \begin{bmatrix} M_{11} & M_{12} & M_{13} & M_{14} \\ M_{21} & M_{22} & M_{23} & M_{24} \\ M_{31} & M_{32} & M_{33} & M_{34} \\ M_{41} & M_{42} & M_{43} & M_{44} \end{bmatrix} * \begin{bmatrix} V_{pp}^o \\ V_{pq}^o \\ V_{qp}^o \\ V_{qq}^o \end{bmatrix}$$

- Diagonal:** “pure” poln. PBs
- Off-diagonal:** Include in-beam poln. leakage

$$M_{pq} = J_{p,i} * J_{q,j}^*$$

- Full-pol. DD corrections

$$V_{ij}^{Corr} = [M_{ij}^{M^{-1}}] * [V_{ij}^{Obs}] = \frac{adj(M_{ij}^M)}{det(M_{ij}^M)} * [V_{ij}^{Obs}]$$

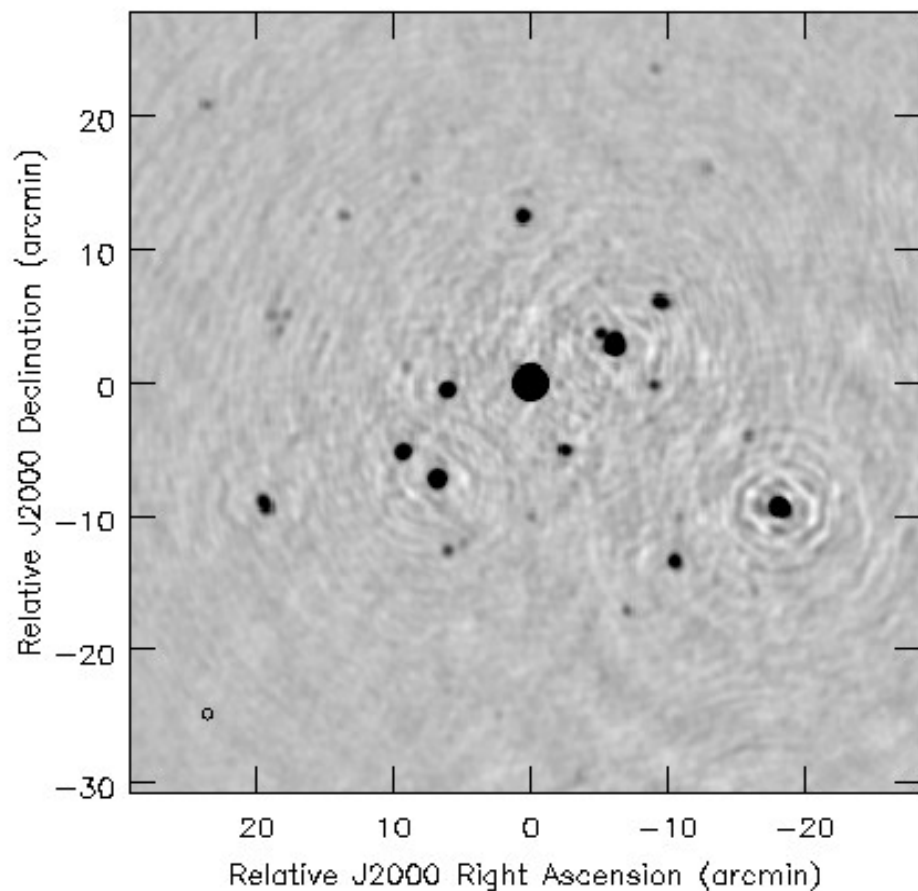
$$I_{ij}^{Corr} = \frac{F[adj(M_{ij}^{M^T})] * [V_{ij}^{Obs}]}{F det(M_{ij}^M)}$$

During gridding

Image plane normalization

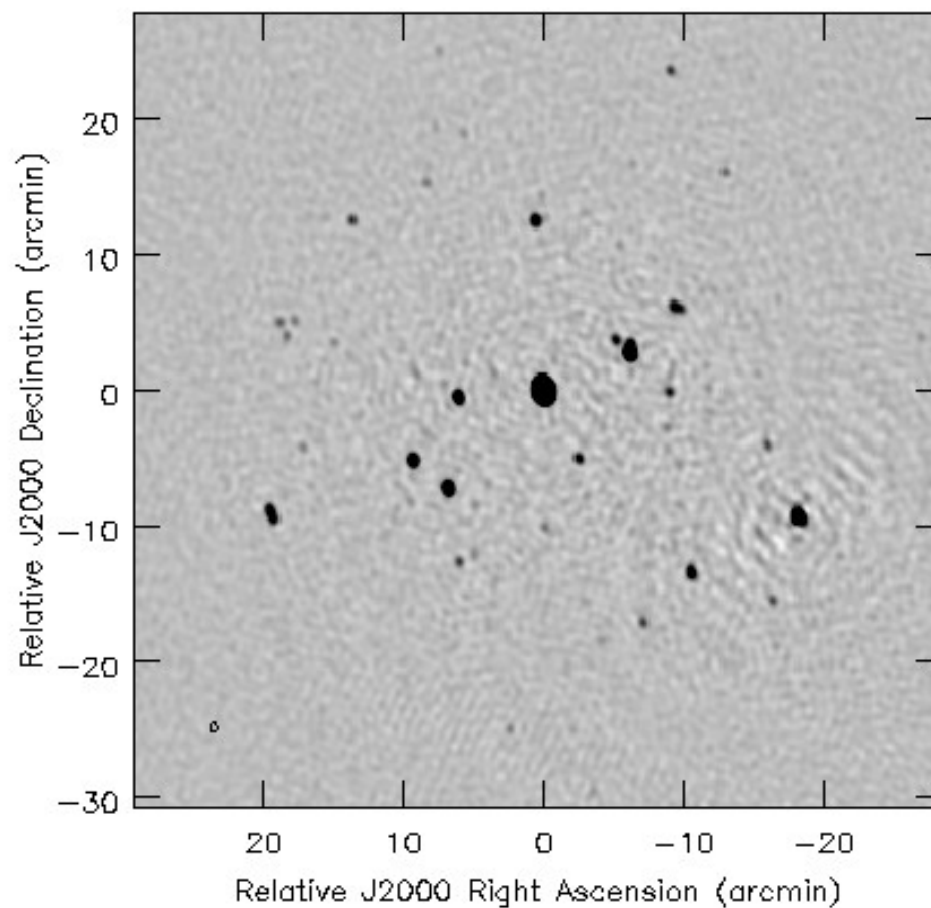


A-Projection: Stokes-I Before



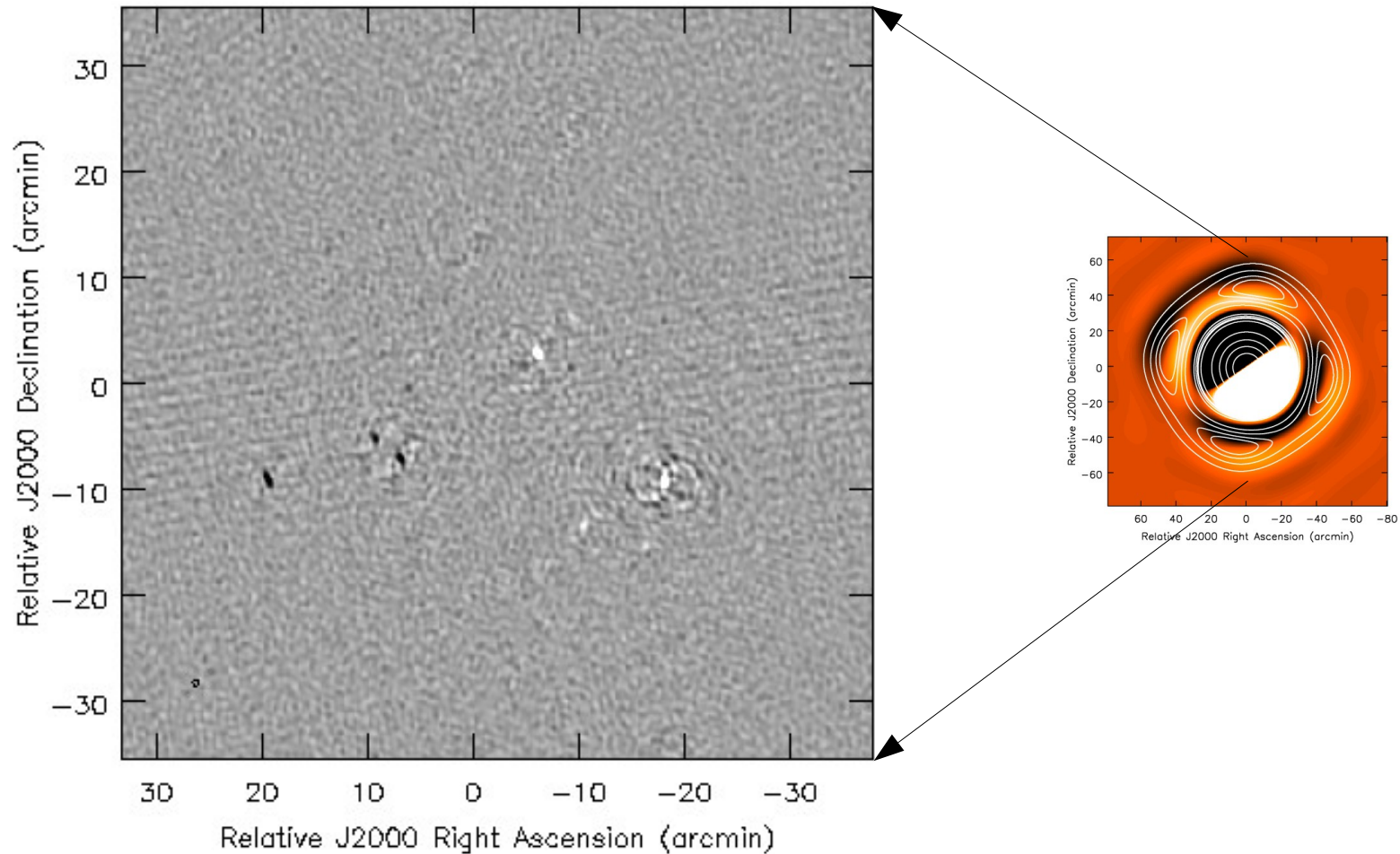
Effective PB is time-variant

A-Projection: Stokes-I After



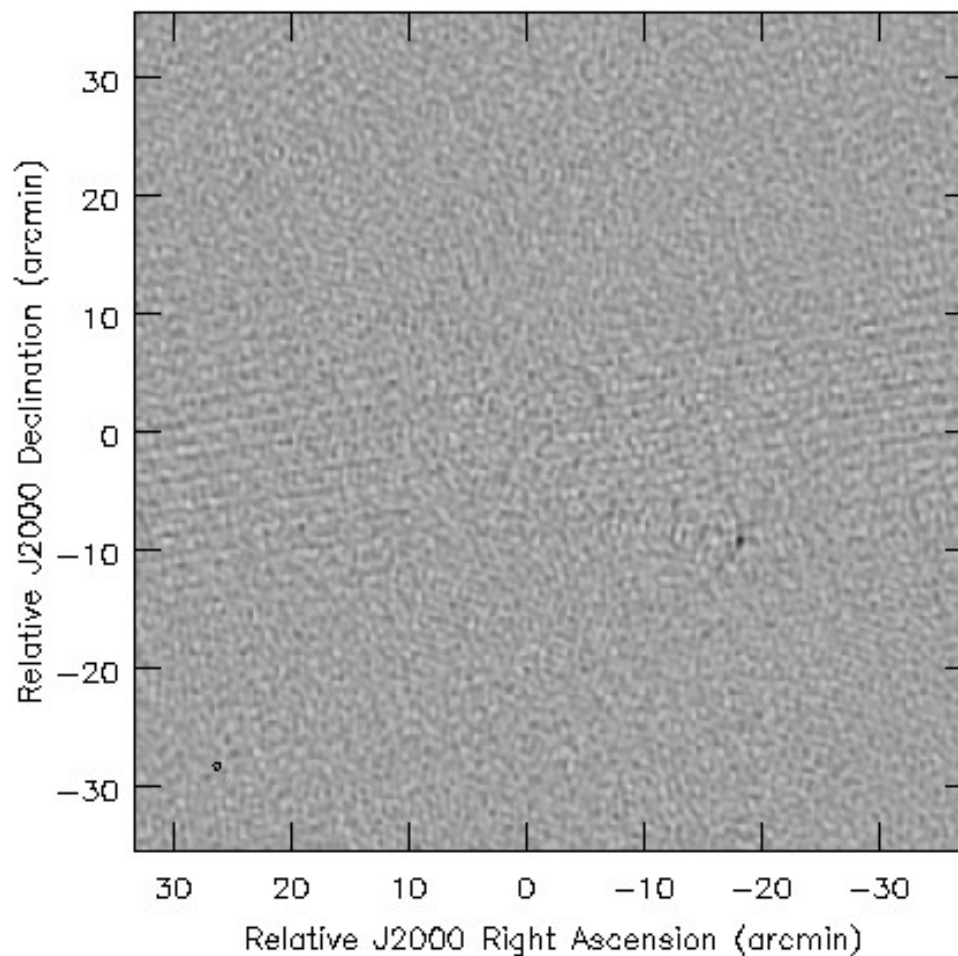
Effective PB is time-invariant

A-Projection: Stokes-V Before



Effective PB is polarization-variant

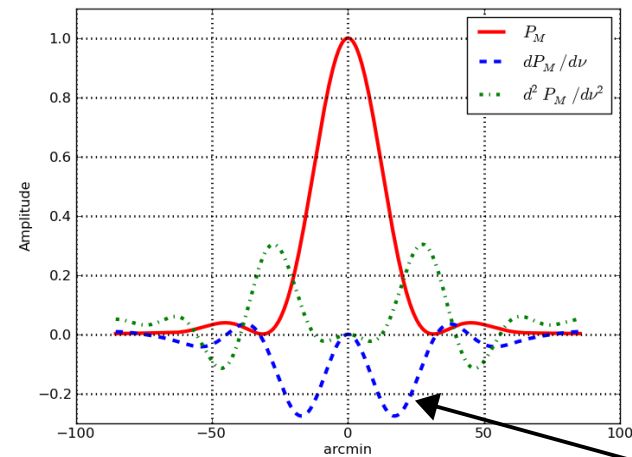
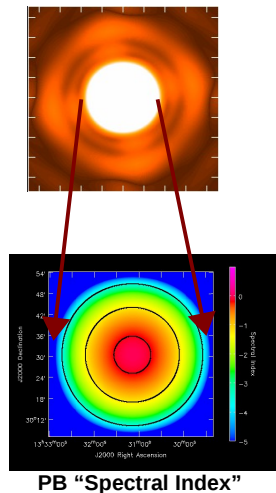
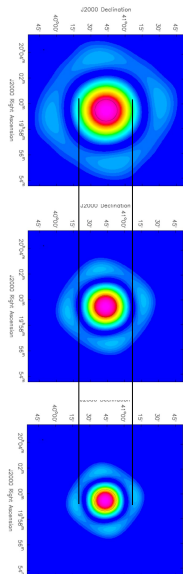
A-Projection: Stokes-V After



Effective PB is polarization-invariant

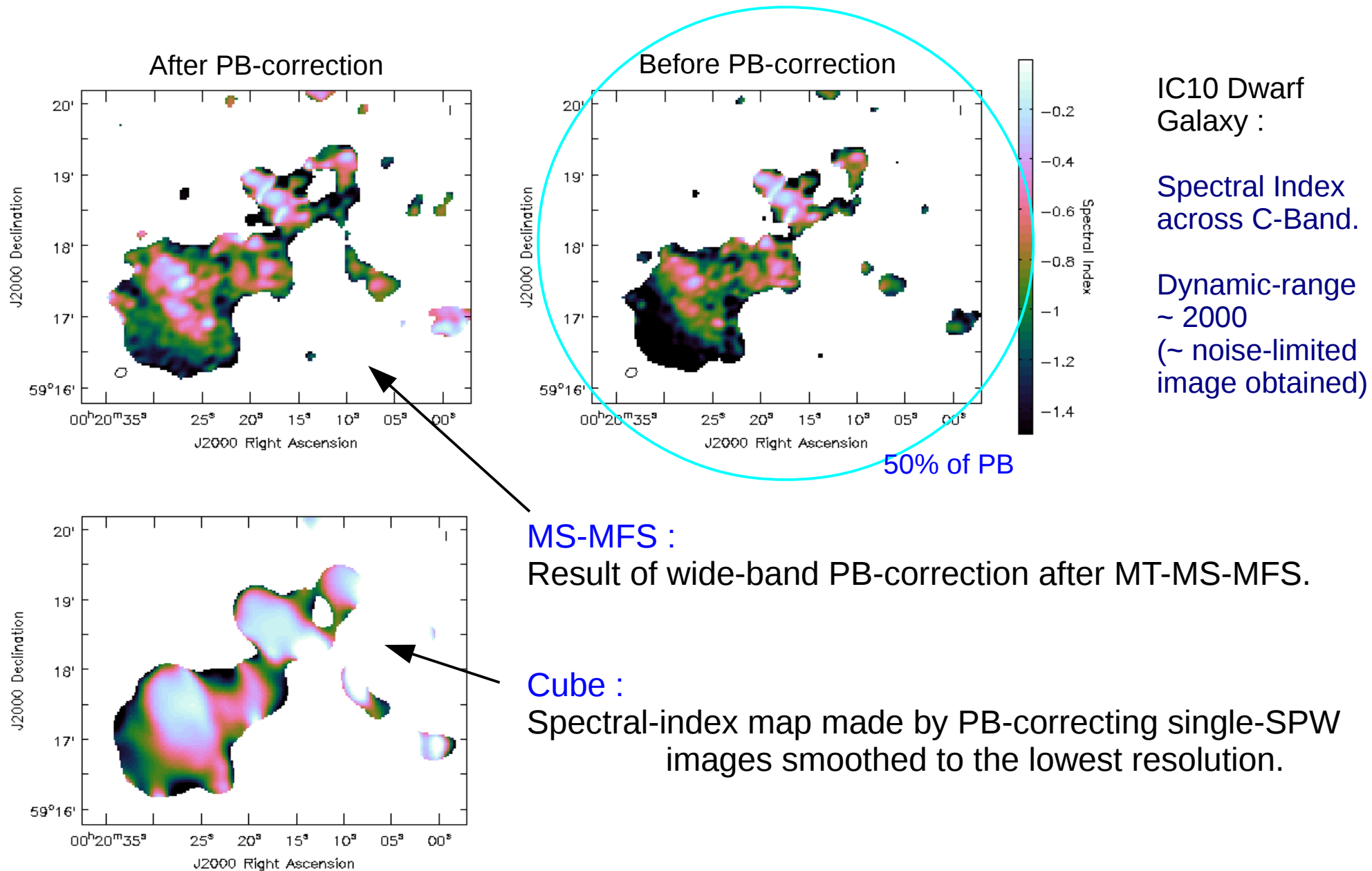
Wide-band Wide-field Imaging

- Wide band data to image beyond the $\sim 50\%$ point of the PB at a reference frequency
 - Bandwidth ratio $> \sim 20\%$
 - FoV $> \sim$ HPBW @ reference frequency
 - Variable PB:
 - Long integration (rotation), Mosaicking (pointings at different PA), in-beam polarization is large (AA)



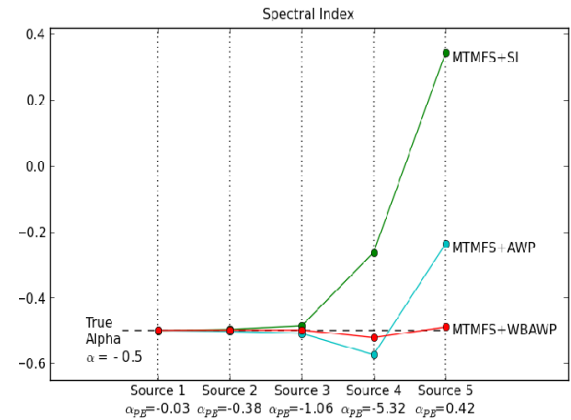
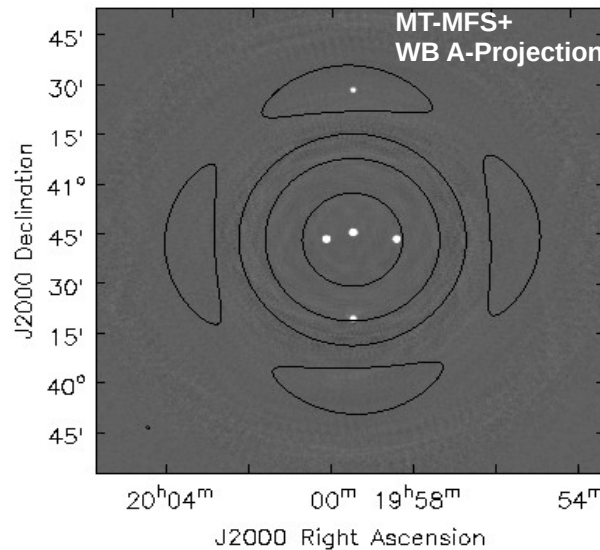
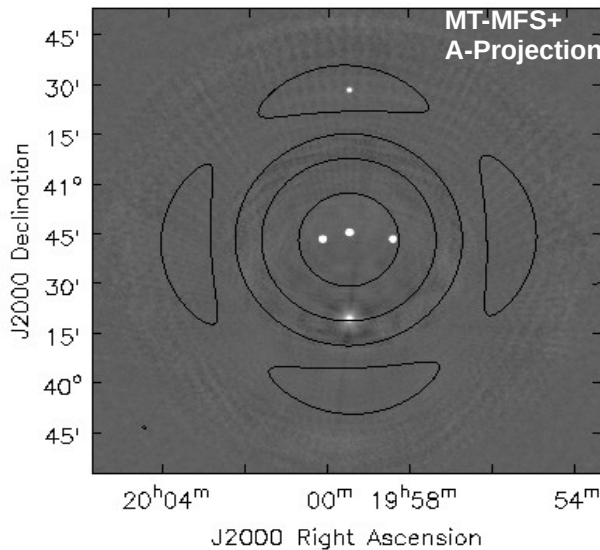
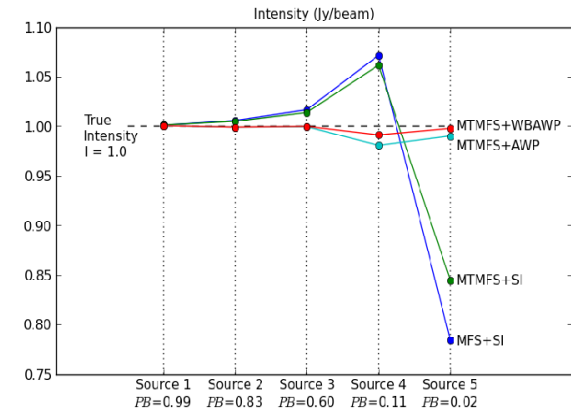
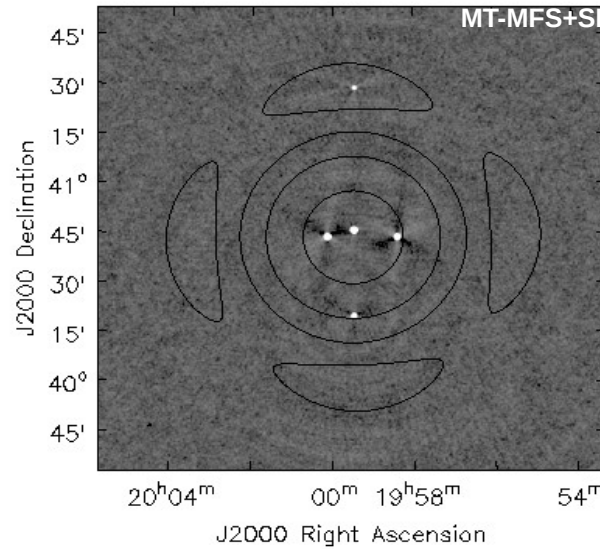
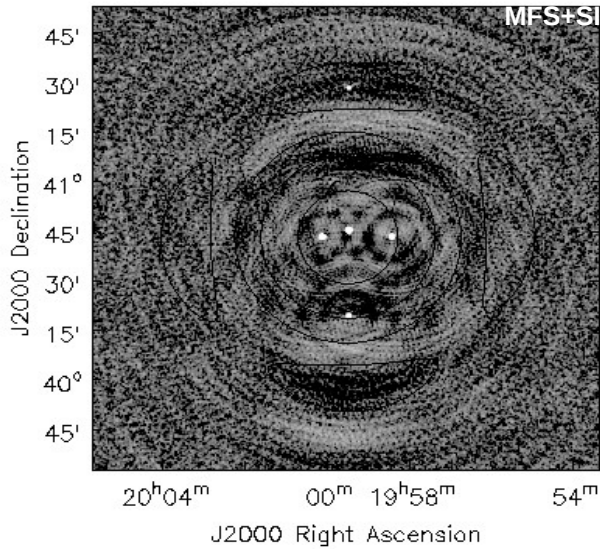
PB Frequency dependence (blue curve)

Continuum (MS-MFS) vs Cube Imaging (with PB-correction)



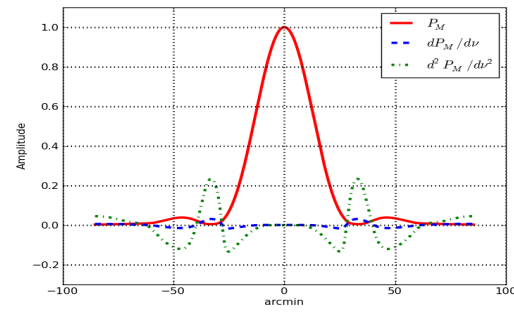
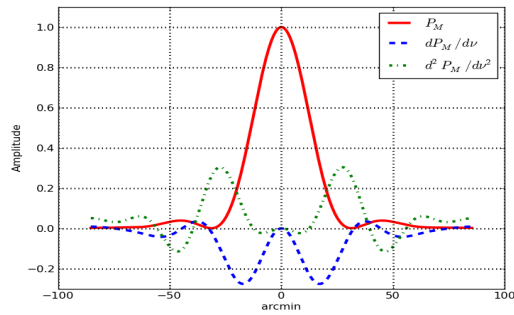
Wide-band Wide-field Imaging

- Characterization of the (WB) A-Projection + MT-MFS

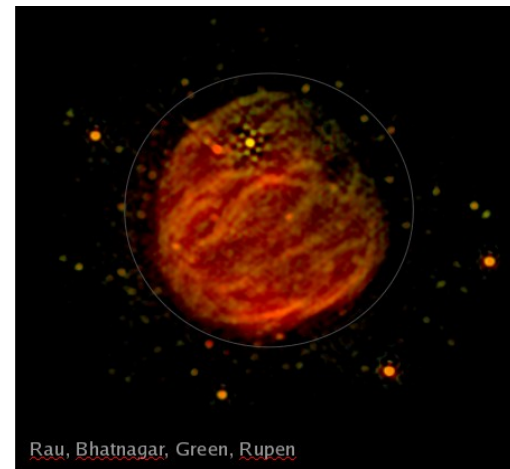
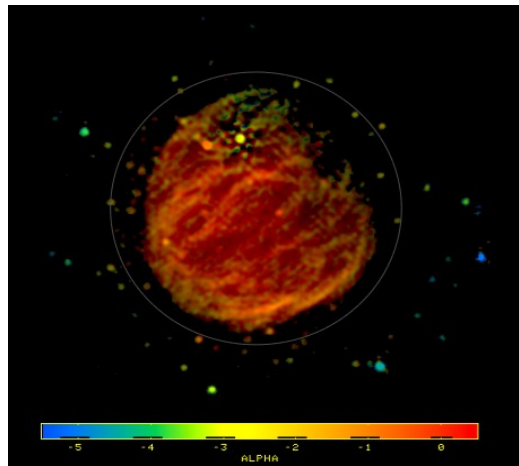


Wide-band Wide-field Imaging

- WB A-Projection + MT-MFS
 - WB A-Projection for PB

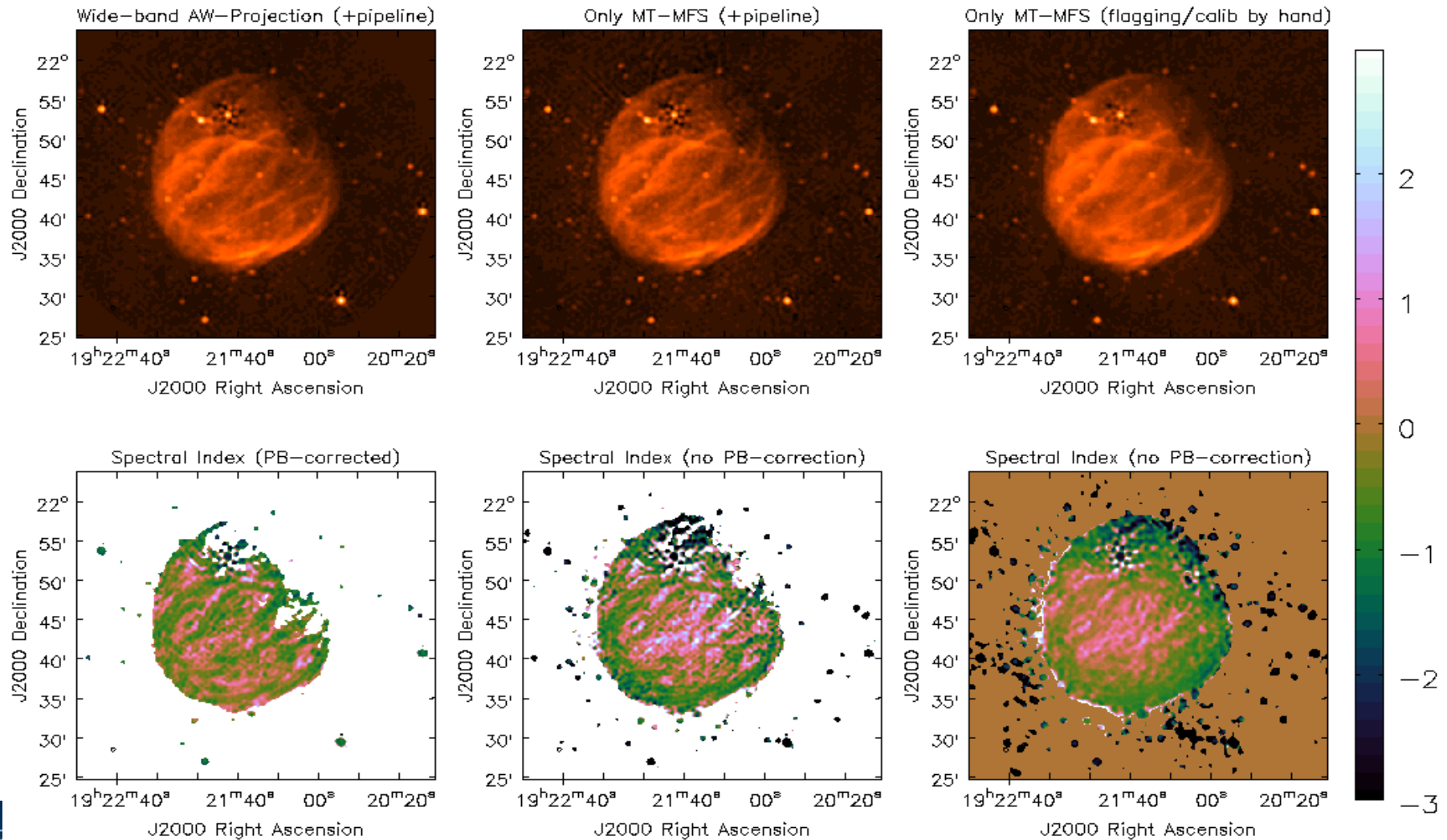


- MT-MFS for sky



Wide-band Wide-field Imaging

- WB A-Projection + MT-MFS

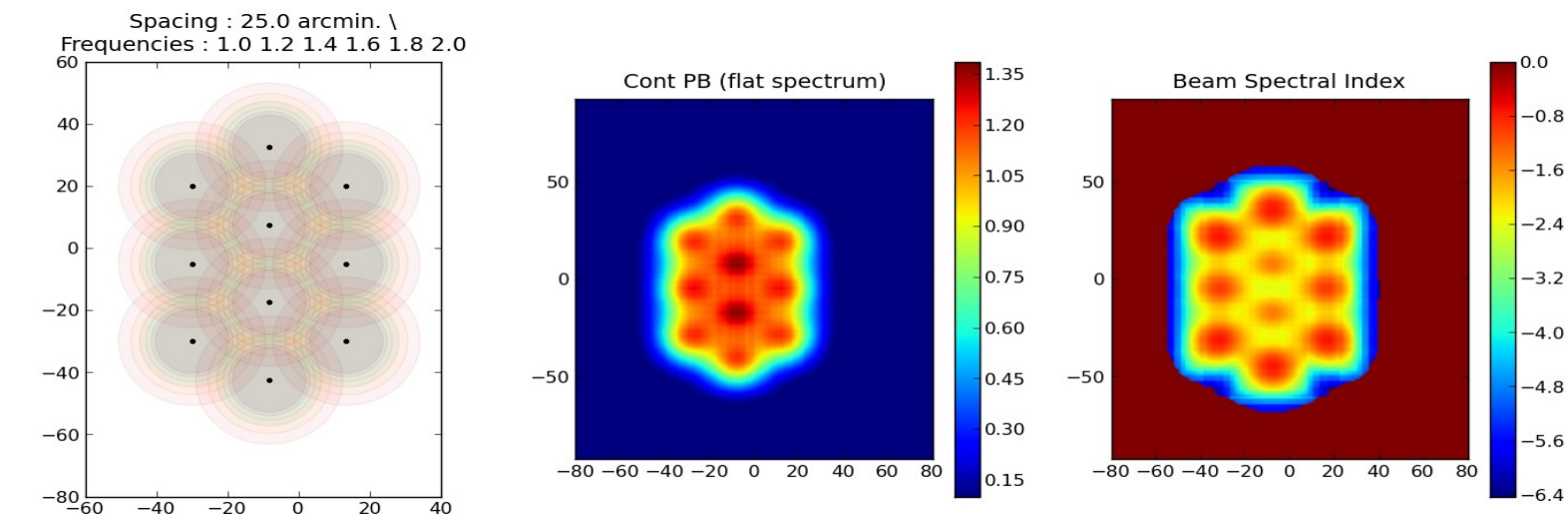


Wideband Primary Beams – Mosaic

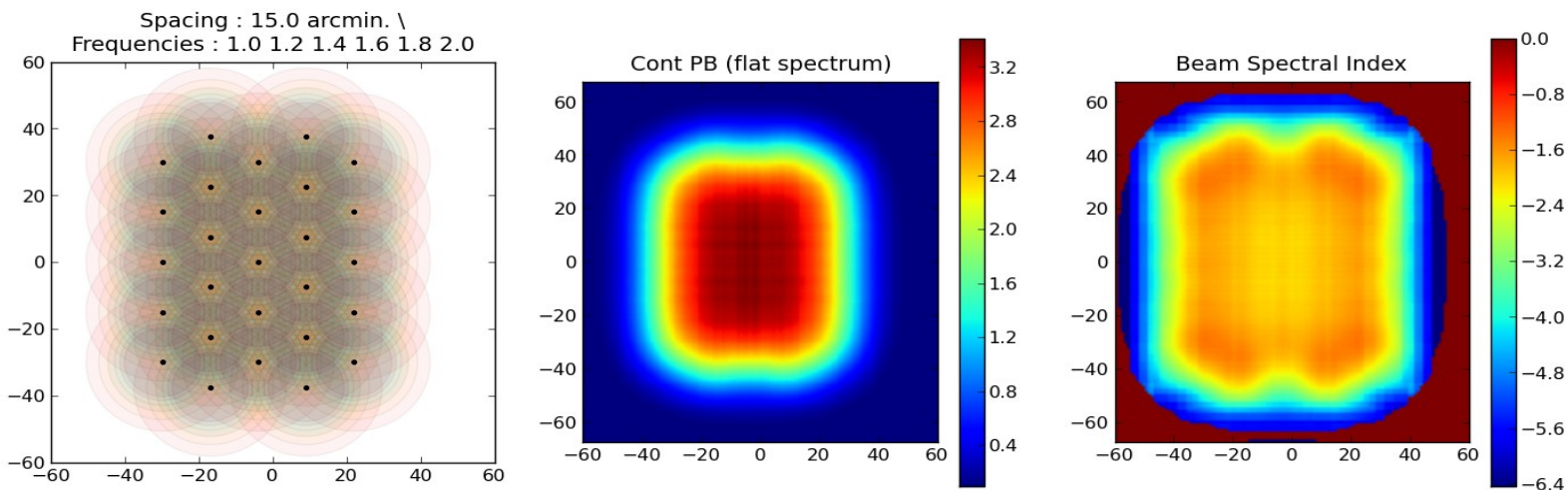
For single pointings, the wideband PB spectrum is relevant only away from the pointing center.

For mosaics, the wideband PB spectrum must be accounted-for all over the mosaic field of view

25 arcmin
spacing
(1-2 GHz)



15 arcmin
spacing
(1-2 GHz)



Wideband imaging capabilities in CASA – Now, and coming...

Cube Imaging :

- Per channel imaging with point source and multi-scale methods, and w-projection
- Post-deconvolution PB correction (divide final image by PB).
- Linear mosaics using the output of imaging
- Joint mosaic deconvolution within imaging (no w-projection)
- Tasks to smooth planes to a common resolution, and to collapse along frequency.

MFS Imaging :

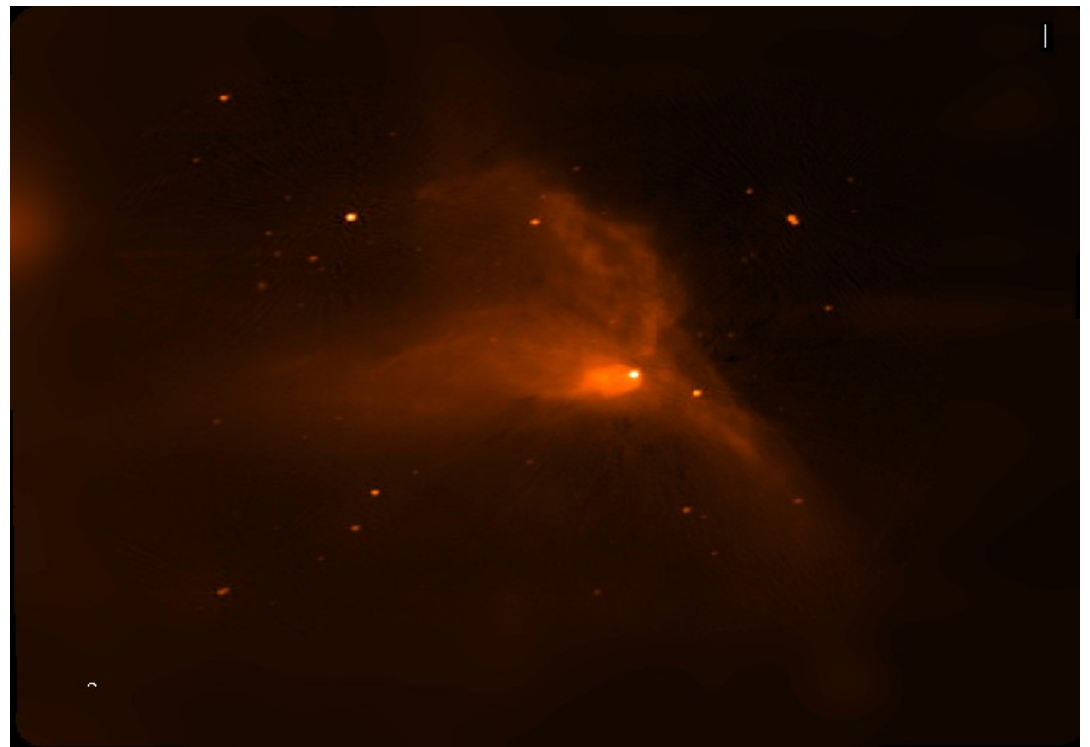
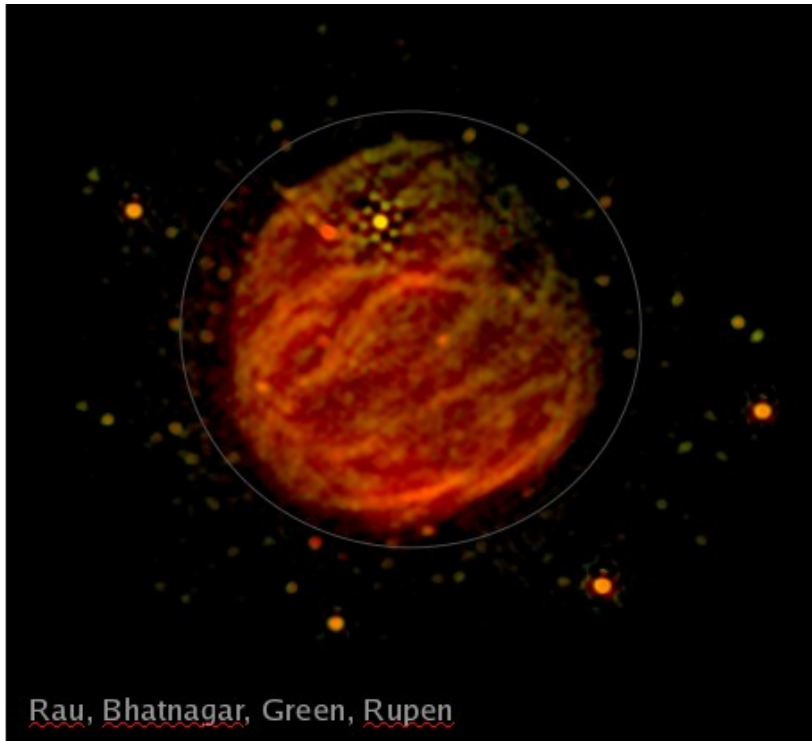
- Wideband imaging with point source and multi-scale methods
- Choice of the order of the polynomial used to model the spectrum
- Post-deconvolution wideband PB-correction with multi-term imaging
- Linear mosaics using the output of wideband imaging (single and multi-term)
- Joint mosaics with MFS gridding (not for multi-term)

Coming..... (needed mainly for high dynamic-range imaging)

- Time variable, full-polarization wide-band PB corrections with W-projection (DD-corrections)
- Combined application of DD-corrections for mosaics
- Joint mosaics for MFS multi-term imaging with pre- and post-deconvolution PB correction

Scales for Multi-Scale Deconvolution

- Thumb rule for selection largest scale
 - Smallest dimension of the largest scale in the image



Using Wide-Band Models for other processing....

WideBand Model : $I_0^m, I_1^m, I_2^m, \dots$

Evaluate spectrum $I_\nu^{sky} = \sum_t I_t \left(\frac{\nu - \nu_0}{\nu_0} \right)^t$

(1) Wide-Band Self-Calibration

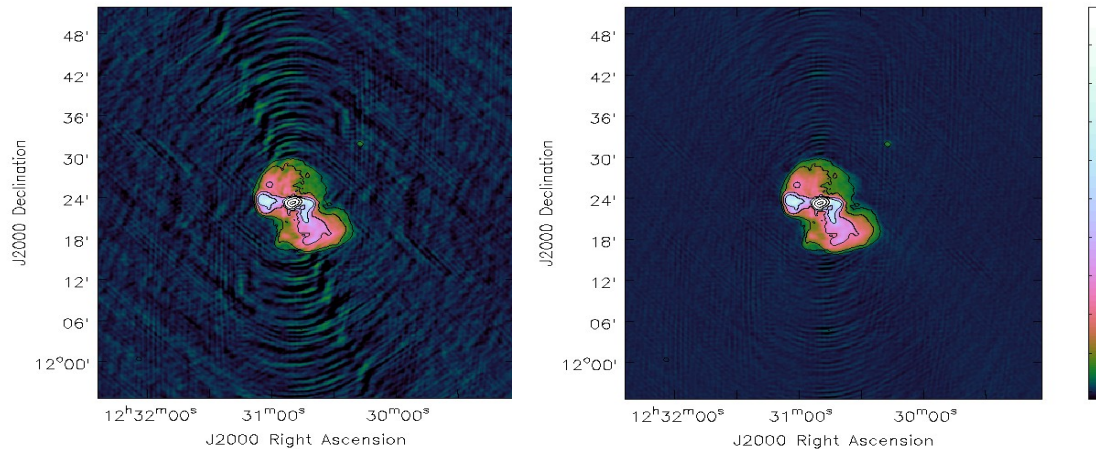
- Can be used on target source, after initial calibration per spw.
- Can use it on the calibrator itself to bootstrap the model.

(2) Continuum Subtraction

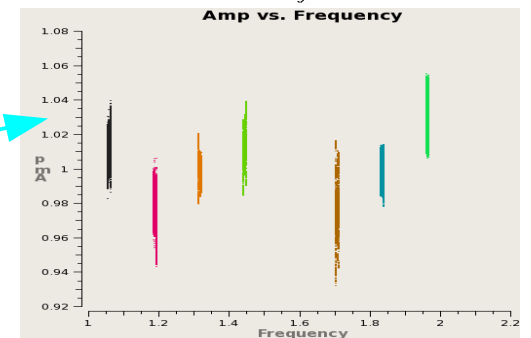
- De-select frequency channels in which your spectral-lines exist.
- Make a wide-band image model of the continuum intensity and spectra
- Predict model-visibilitys over **all** channels (using WB A-Projection, if necessary)
- Subtract these model visibilitys from the data

(3) Combination with single-dish data

- Use Taylor-coefficient images made from single-dish images, as a starting model



Amplitudes of bandpass gain solutions.....



Example : SNR G55.7+3.4

7 hour synthesis, L-Band, 8 spws x 64 chans x 2 MHz, 1sec integrations

Due to RFI, only 4 SPWs were used for initial imaging (1256, 1384, 1648, 1776 MHz)

(All flagging and calibration done by D.Green)

J2000 Declination

30'

15'

22°00'

45'

30'

15'

21°00'

45'

Imaging Algorithms applied : MS-MFS with W-Projection

(nterms=2, multiscale=[0, 6, 10, 18, 26, 40, 60, 80])

Peak Brightness : 6.8 mJy

Extended Emission : ~ 500 micro Jy

Peak residual : 65 micro Jy

Off-source RMS : 10 micro Jy (theoretical = 6 micro Jy)

19^h26^m

24^m

23^m

22^m

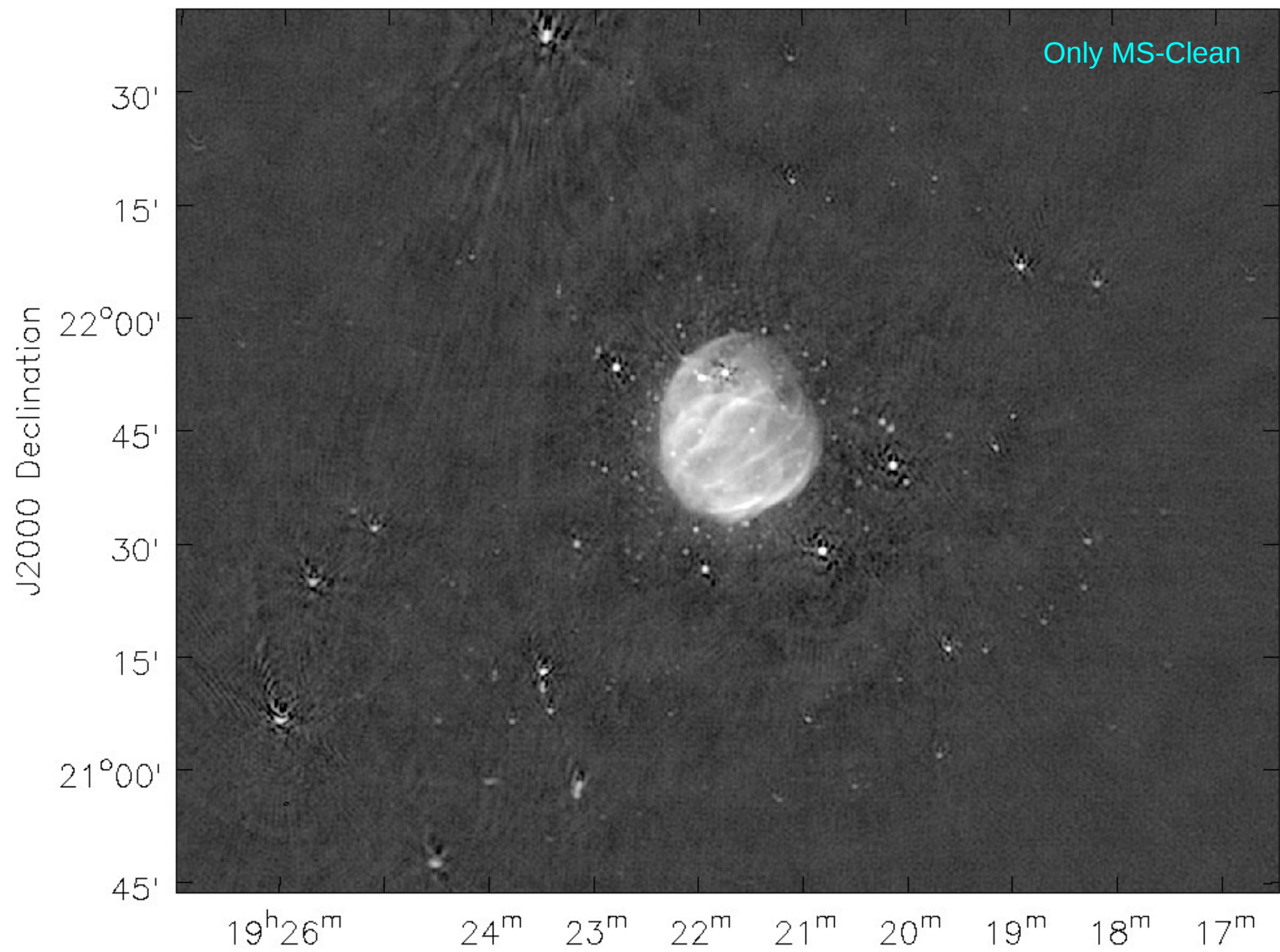
21^m

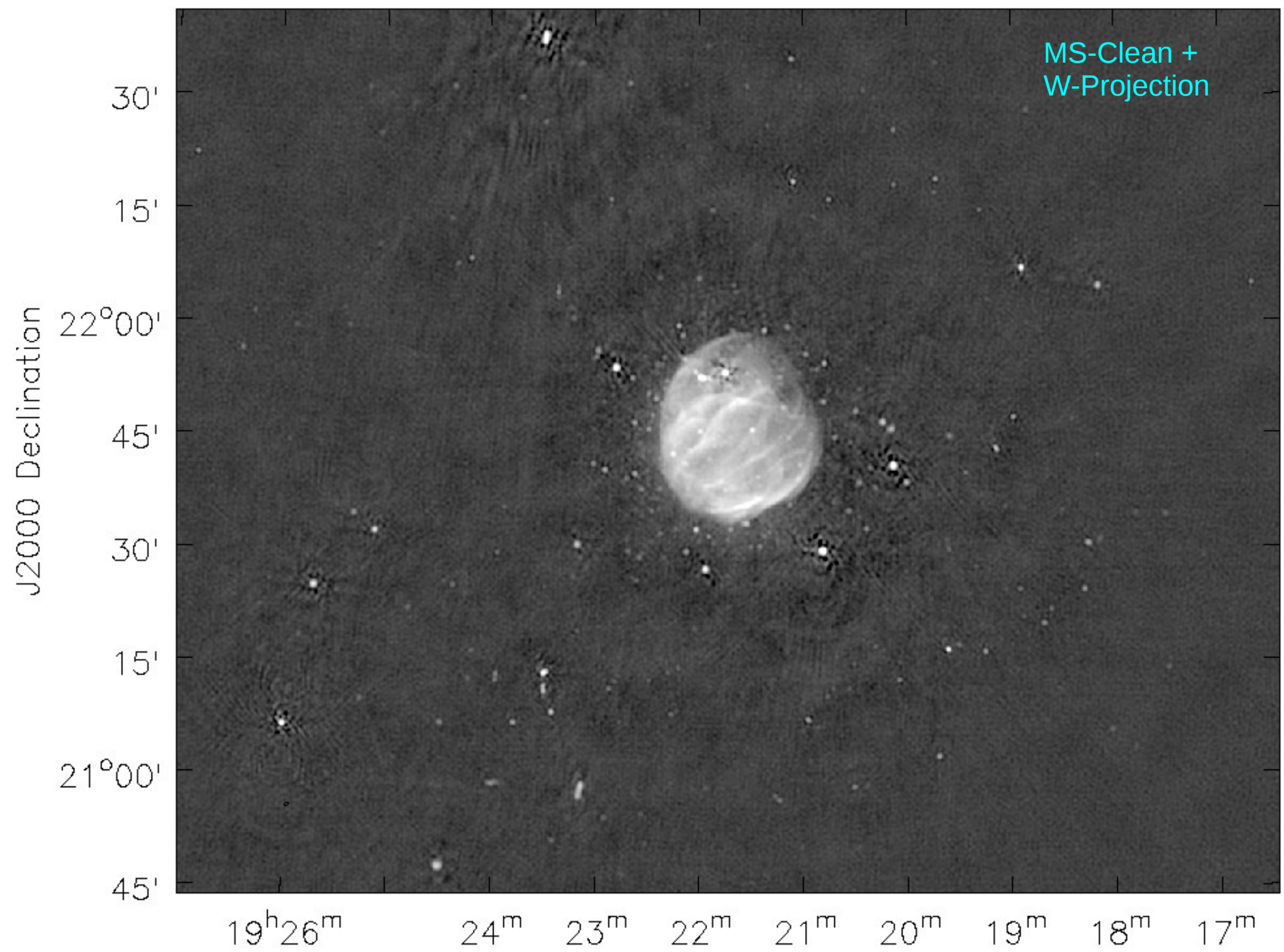
20^m

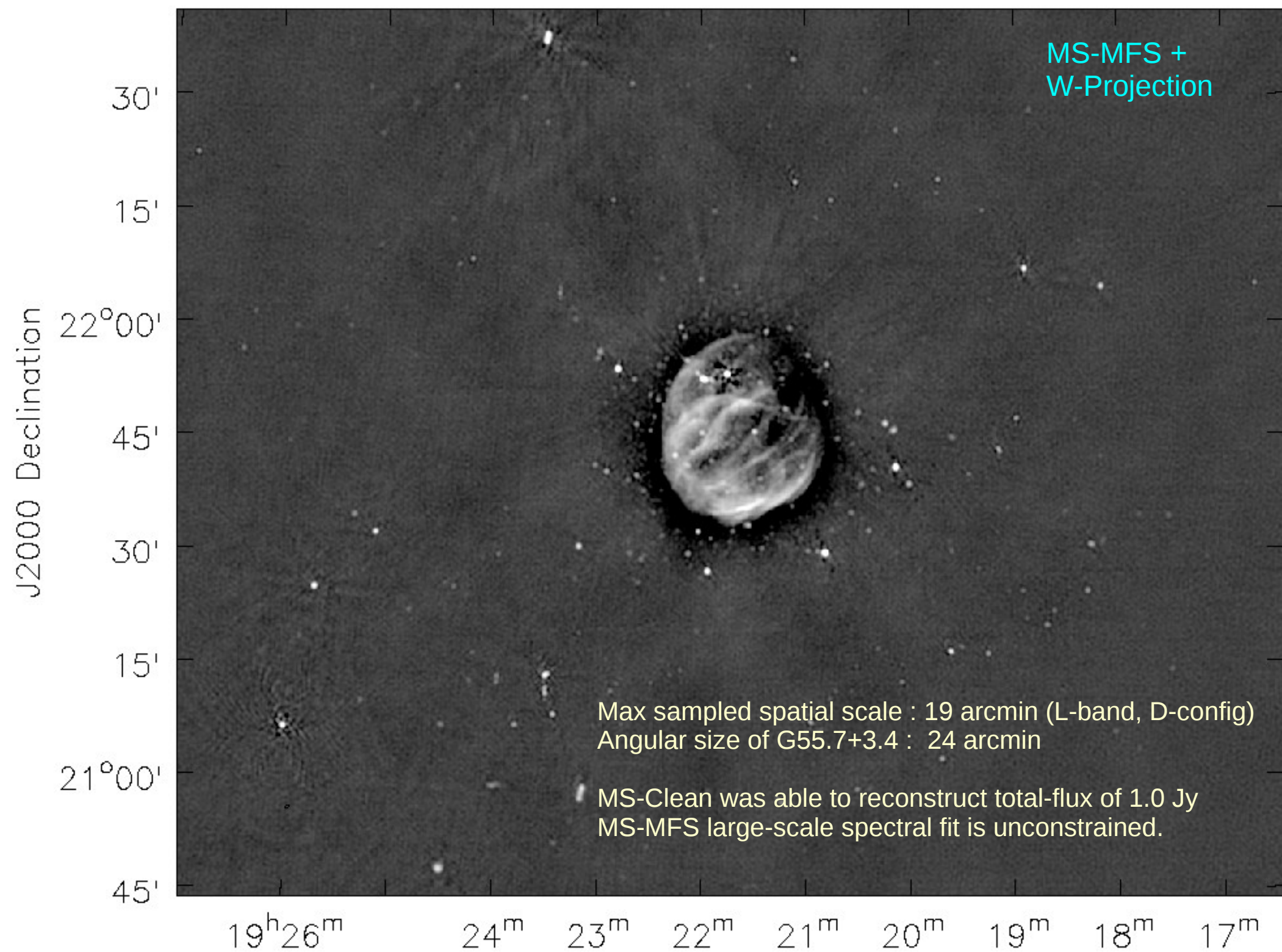
19^m

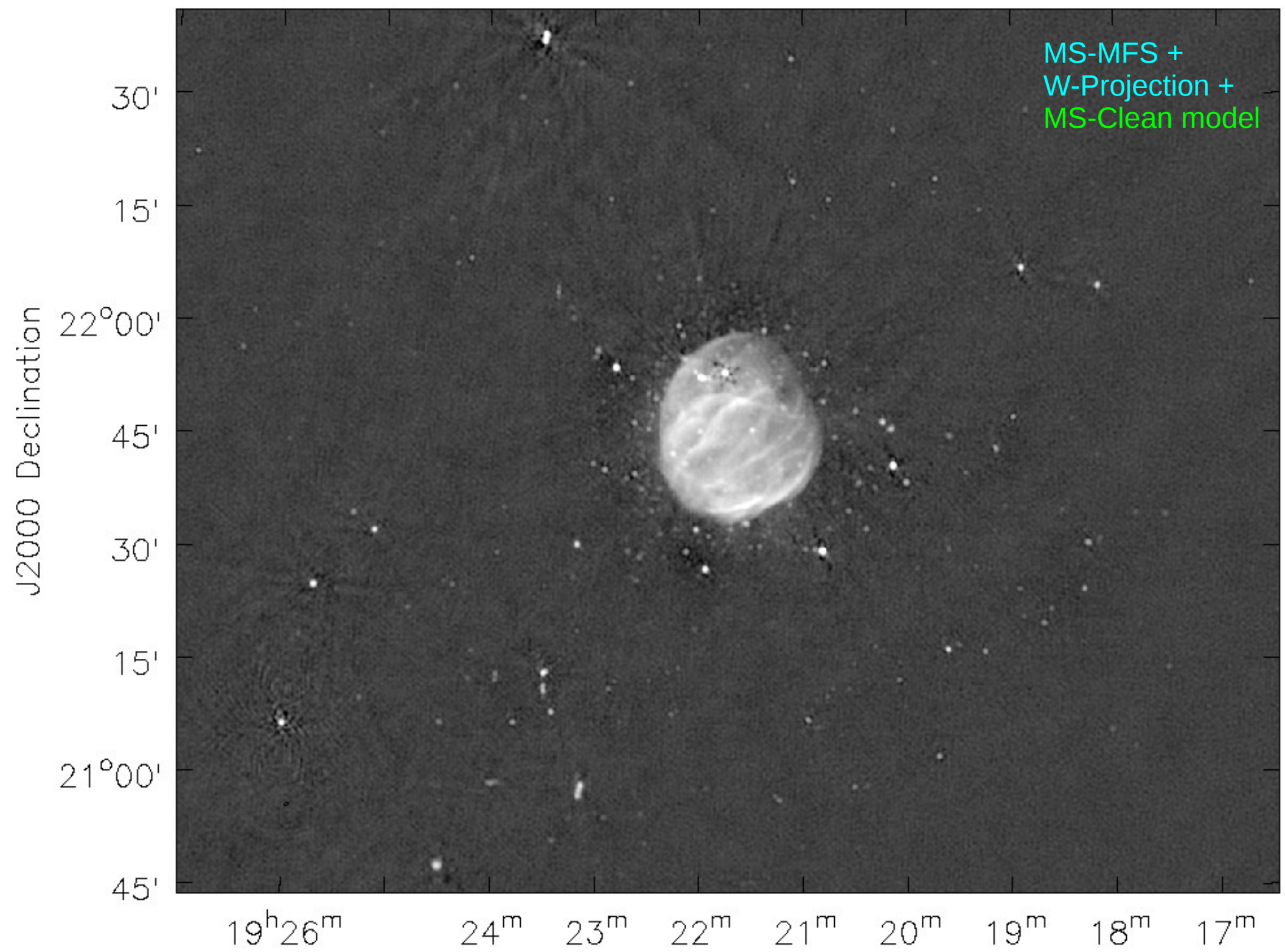
18^m

17^m









Wide-field Issues

